

for a greener tomorrow changes

Programmable Controllers MELSEC-L series



# Simple

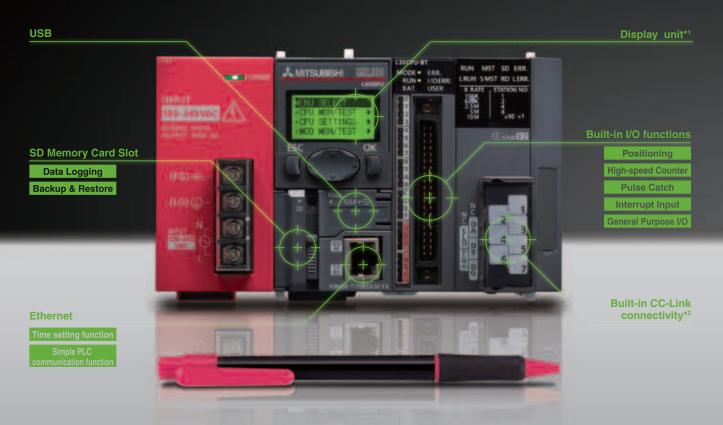


## Convenience that fits in the palm of your hand.

The L series is the latest in a long line of MELSEC products renowned for exceptional performance and rock solid reliability.

Get the performance, functions, and capabilities required for today's most demanding applications in an incredibly small package.

MELSEC-L series greatly expands the range of functionality traditionally associated with compact programmable controllers and through user-centric design, pushes the limits of ease of use.



## Maximum Functionality

#### The CPU module contains a diverse range of control functions.

A large variety of I/O types and features are built-in for convenience.

Due to an abundance of advanced functionality, L series CPUs are flexible enough to meet a wide variety of needs.

## Maximum

#### Performance

#### High speed, large memory capacity CPU

The CPU has a basic operation processing speed of 9.5ns\*3 and 260k steps\*4 of program capacity are available for complex programs and equipment control.

#### Maximum

## Capabilities

#### **Advanced capabilities** focused on improving efficiency

The user-friendly display unit enables routine operations to be made without a computer. An SD memory card slot is included as standard for data logging and program storage. Write programs and manage L series controllers using GX Works2 and iQ Works, the most advanced and effective software for Mitsubishi controllers yet.

- \*2: Included with L26CPU-(P)BT
- \*3: For L06CPU, L26CPU, L26CPU-(P)BT
- \*4: For L26CPU L26CPU-(P)BT

#### Built-in I/O Features → P.5

Positioning	High-speed Counter	Pulse Catch
Interrupt Input	General Purpose I/O	

Every L series CPU module comes with 24 points of built-in I/O that support advanced features to meet challenges head on.

#### Built-in Connectivity → P.7

Ethernet	USB	SD Memory Card
CC-Link Ver.2.0*2		

Convenient communication options and memory card storage are included with every CPU.

#### High-speed CPU → P.8

Program Memory 260 k steps*4	Maximum number of I/O points 8192 points	
Basic operation processing speed	Floating-point operation	MOV instruction
9.5 ns* <sup>3</sup>	0.057 μs	19 ns

L series raises the bar for performance specifications in a compact programmable controller with 260k steps of program memory and a basic operation processing time of just 9.5 nanoseconds.

## ☐ Display unit →P.13

Multi-lingual Display
English / Japanese

Display Size Multi-color Backlight
16 characters x 4 lines Green(Normal), Red(Error

The display unitallows for quick troubleshooting and diagnostic operations of the CPU and connected modules.

#### Software → P.65

GX Works2	iQ Works	GX LogViewer
MX Component	MX Sheet	

L series is compatible with the latest and most advanced programmable controller engineering software from Mitsubishi.





#### **INDEX**

L series Features

CPU P.15

I/O

P.25

## Flexible

## The L series has the ability to flex to meet your application's requirements.

MELSEC L series has been designed with three key concepts in mind.

The first key is reliability.

Mitsubishi Electric products are world renowned for quality.

The second is ease of use.

We are committed enabling engineers and programmers to do their job as efficiently as possible to reduce costs.

The third key is flexibility.

L series systems expand to meet the application requirements without wasting money or space.



**Analog / Temperature Control** 

Simple Motion / Positioning

P.43

**High-Speed Counter** 

P.51

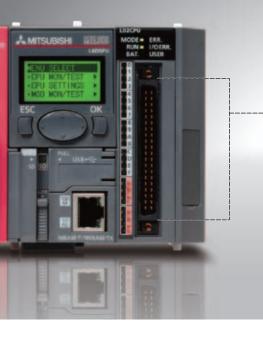
Network

Software

P.65

**Related Products** 





#### L series Built-in I/O Features

Every L series CPU comes with 24 points of built-in I/O standard. These I/O points are capable of many functions usually reserved for separate modules. Save on system costs by using the built-in functions rather than relying exclusively on additional modules.

The built-in I/O\*1 comes in sink or source type format and may be chosen based on the application.

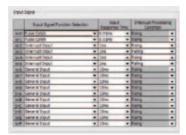
■ L series CPU Built-in I/O Functions

Positionia (Built-in control of		High-Speed Counter (Two channels built-in)	ı	Pulse Catch	Interrupt Input	General Input / Output
	F	unction			Features	
Positioning*2	Numbe	r of axes: Maximum 2 axes	•		Okpulse/s on: 30µs (Shortest activatio n and deceleration are supp	
High-Speed Counter*2			nnels	Maximum counting speed: 200kpulse/s Open collector, Differential line driver input High accuracy ON/OFF measurements with a resolution of 5µs High precision PWM control up to 200kHz (High speed pulse output)		
Pulse Catch	Number of input points: 16 points			Minimum input resp Pulse signals whose		e scan time can be detected.
Interrupt Input	ut Number of interrupt points: 16 points		nts	Built-in CPU provide All input points supp	es high-speed processing. Fort interrupt inputs.	
General Input	Number of high-speed inputs: 6 points Number of standard inputs: 10 points				onse time of high-speed in onse time of standard inpu	
General Output	Number of output points: 8 points			Output response tim	ne: 1µs or less	

<sup>\*1</sup> The L02SCPU, L02CPU L06CPU, L26CPU and L26CPU-BT are sink type, and the L02CPU-P and L26CPU-PBT are source type.
\*2 Points used by the positioning and high speed counting functions are fixed (as in A phase, B phase, near-point dog).

#### Easy setup of built-in I/O functions

Configuring built-in I/O functions can be done easily by setting parameters using the programming tool.



[Built-in I/O function example parameter settings] Pulse Catch: 0.01ms (response time) Interrupt Input: 1ms (response time)

Pulse Output Horse	CN/CCV Horse
Rotation Direction Setting	Denent value Shoement with Forward Fun Tube Output
SAF Strake Upper Limit States	19876004
LOT STORE LINEY LINEY BUILDING	03076366
Speed Limit Value (pulpe(s)	1000
Day Speed at Trent (pulse(s))	
Accresion Decreation System Selection	Priorition Academistra (Decelerator)

[Positioning function example parameter settings]
Pulse Output Mode: CW/CCW mode
Rotation Direction Setting:
Current Value Increment with Forward Run Pulse Output

Operation Note betting	COTTO MODE	_
Count Squite Selection	A Phase & Phase	
Rose Input Hore	i-Phase Hubble of L	
Country Steat Setting	100epps	
2 Place (Franc) Toppe Setting	Riving	
External Preset (2 Phase) Exquest Delection Setting	CRI at detection	
Country Formal	Sinesi Counter	
Function Input Logic Satting	Positive Logic	
Counter Function Swepton	Count Disabling Australia	
Considence Output Time Preset Setting	Rotp-sort	
Considence Detection Shipman at Setting (Counter Visite Concretion No. II)	Netused	
Counteins Devertion Silver up Setting (Counter value Concolence No. 2)	Network	
Samping Time Setting (ms)		
Braquercy November & Waging Processing Count		
Preguency Heapprement Unit Time Setting		
Rotaton Speed Movement Averaging Processing Count.		_
Potation Speed Haustramen Unit Time Setting		
Number of Fulses per Rotation Issues		
Pulse Heasurement Target Setting		

[High-speed counter function example parameter settings]
Pulse Input Mode: 1-Phase Multiple of 1
Counting Speed Setting: 100kpps

Positioning High-Speed Counter

#### Built-in CPU positioning control function

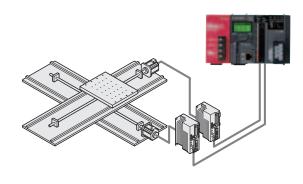
[ Positioning Function ]

The built-in positioning function has a start time of just 30µs with a maximum high speed output of 200k pulses per second.

Furthermore, it supports S-curve acceleration and deceleration for applications that require minimal machine vibration.

#### [ High-Speed Counter Function ]

Two channels support the high speed counting function. The differential line driver inputs support counting speeds up to 200k pulses per second.



<sup>2</sup> Points used by the positioning and high speed counting functions are fixed (as in A phase, B phase, near-point dog Custom points for these functions may not be assigned.

CPL

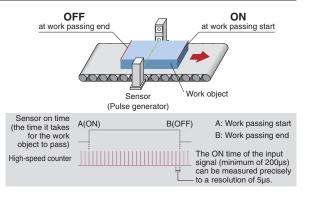


#### Make highly accurate measurements with a resolution of 5µs

**High-Speed Counter** 

Using pulse measurement mode, where the input signal ON/ OFF time is 200µs or greater, highly accurate measurements in units of 5µs or greater are possible.

For example it is possible to calculate length by knowing the "work object passing speed" and measuring the ON time of the sensor.



#### **High-Speed Counter**

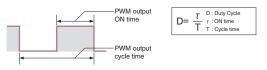
**Pulse Catch** 

#### High precision PWM control up to 200 kHz

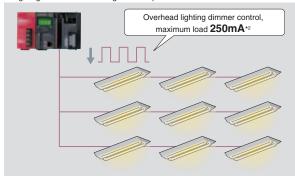
Using the pulse width modulation control function of the high speed outputs, cycle times as fast as 5µs can be created. Simply input the ON time and cycle time to drive a wide range of devices from lighting dimmer control, motors, and heaters to precision inspection equipment requiring high resolution performance.

Setting item	Setting Range	Description
PWM output ON time*1	0 or 10 to 10000000*1 (0.1µs)	Set the ON time of output pulse
PWM output cycle time*1	50 to 10000000*1 (0.1μs)	Set the cycle time of output pulse

<sup>\*1</sup> The PWM output ON time must be  $\leq$  the PWM output cycle time.



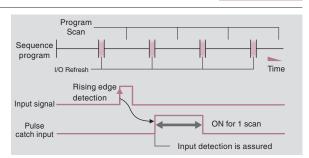
#### ■ Lighting dimmer control using PWM output



\*2 In cases where the first six digits of the serial number are "120722" or later. Previous serial numbers of the CPU module are applied to 100mA.

#### **Guaranteed input pulse detection**

Typical programmable controller input devices are unable to detect pulse signals whose ON time is shorter than the scan time or do not occur during I/O refresh periods. The pulse catch function allows these signals to be reliably detected and passed to the sequence program. This function is different from the interrupt input function in that it does not require any special programming. Pulse catch inputs may be used in programs exactly the same as traditional input (X) signals.



#### CPU with built-in CC-Link network connectivity

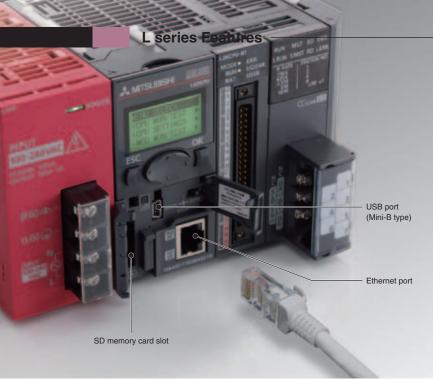
L series CC-Link ready CPUs are compatible with the latest generation of CC-Link devices and support connections with over 1,000 different product types. Without adding a module, these CPUs can perform high-speed communication with a maximum of 128 words\*1 between a master station and a local station. CC-Link is the dominate FA network standard in Asia and continues to gain support worldwide.



# CPUs with built-in CC-Link can function as master or local stations. Local station ≒ Master station Up to 128 words\*1 CC-Link Local stations (Up to 26)

Choose from an extensive range of CC-Link compatible equipment. Up to 64 devices can be connected.

<sup>\*1</sup> When the number of occupied stations is 4 and the extended cyclic setting is octuple in the Remote net Ver.2 mode.



## Convenient communication and storage options come as standard

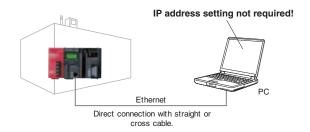
Program, configure, and perform diagnostics on L series systems using either the USB 2.0 or Ethernet connections. The SD Memory Card slot has many uses including the easy backup and restore of programs and parameters.



L02CPU(-P) L06CPU L26CPU L26CPU-(P)BT

#### **USB** and Ethernet connections standard

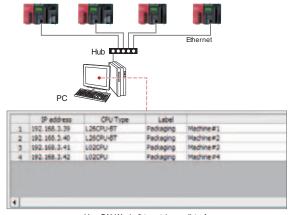
Use the USB 2.0 interface or Ethernet to connect directly at the instillation site. The Ethernet interface supports direct connection with either a cross or straight LAN cable and does not require any configuration of the programmable controller or PC to operate (patent pending).



#### Easy connection through hub

All CPUs connected to the same hub can be searched and displayed in a list.

By selecting the access target CPU from the list, it can be connected to even if the IP address is unknown.

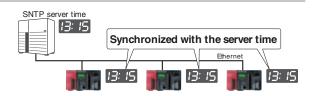


Use GX Works2 to retrieve a list of all CPUs connected to the network.

#### Precise time synchronization

Synchronize systems on an Ethernet network using an SNTP\*1 server. Highly precise time synchronization can be achieved to enable simultaneous operations, quality control, or error tracking.

\*1 SNTP: Simple Network Time Protocol





#### Program-less device data transfer

[ Simple PLC communication function\*1 ]

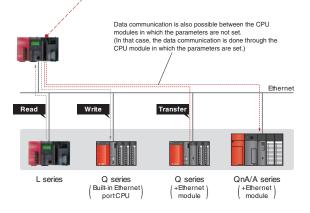
Using the programming tool, a simple parameter setting is all that is needed to transfer device data such as production information with no programming required.

This function makes it possible to easily establish communications not only with L series, but also Q series and QnA/A series controllers.

\*1 CPU module whose first five serial number digits are "13042" or later is required.

Item		Description
Read		Read the data of the specified destination device (transmission source) to the specified device of the host station (transmission destination).
Communication Pattern	Write	Write the data of the specified device of the host station (transmission source) to the specified destination device (transmission destination).
Transfer		Read the data of the specified destination device (transmission source) and write it to another specified destination device (transmission destination).
Communication	Execution Interval	Set between 10ms and 65535ms (1ms unit)
Setting:	Request Contact	Data send/receive is executed at the rising edge (OFF to ON) of the specified device (X, M, B).
	Setting No.	Set between 1 and 64.
Available devices Device points		The maximum number that can be set for each setting No. is 512 words. (Maximum points of a word device: 256 points + Maximum points of a bit device: 4096 points) The total of setting No. 1 to 64 is maximum 4096 words.

■ Simple PLC Communication Setting



#### **SD Memory Card special features**

Use the SD/SDHC compatible memory card to quickly and easily back-up the CPU programs and parameters. The backups can then be just as easily restored or used to program other CPUs. The memory card can also be used to hold data captured with the data logging function\*1.

#### Save/load programs directly into the Programmable Controller

[ Multiple project save/load function\*1 ]

Parameters, program files, etc., can be saved/read onto a SD memory card by simply using the onboard display unit, without having to connect to a separate PC. Once saved on the SD memory card, files can be sent via e-mail, for example, when requiring off-site editing of the files.

\*1 Supported by CPU module whose first five serial number digits are "14042" or later.



#### Incredible performance in a compact design

With a program capacity of 260k steps\*1 and basic operation (LD instruction) speed of 9.5ns, L series CPUs have the performance necessary for highly demanding applications. Furthermore, the double-precision real number operation instruction is also available to reduce operation errors in complicated mathematical formulas.

\*1 60K steps for L06CPU.

		L06CPU	L260	CPU	L26CPU-(P)BT
CPU Modules		L26CPU, L26CPU-BT, L06CPU L26CPU-PBT		L06CPU	
Basic operation pro	Basic operation processing speed		9.5ns		
Floating point operation speed	Single precision	0.057µs			
Addition instruction (E+)	Double precision*2	4.3µs			
MOV instruction		19ns			
Program capacity	Program capacity		ps	6	60k Steps
Total device capacity			413k \	Words	

<sup>\*2</sup> Minimum valu

<sup>\*1</sup> For details about the data logging function, refer to page 11.

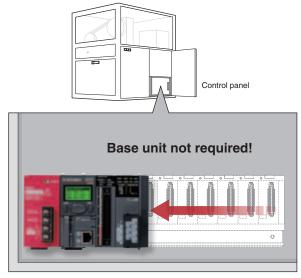


expansion modules for the application.

#### Expand L series systems with no base unit restrictions

L series modules do not require a base unit. The installation space is not restricted by base size, and the system can be installed with minimal required space.

Furthermore, the addition of modules to the system is not restricted by the number of available base unit slots and costs may be reduced due to the elimination of expansion base units.

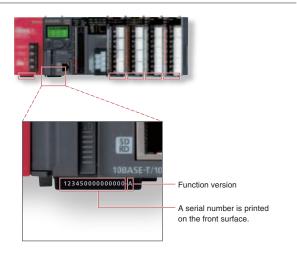


Installation space is reduced in the control panel

#### Identify important information easily

Every L series module has the serial number printed on the front surface of the module to allow viewing even during system operation (modules do not need to be removed).

\*Serial numbers can also be checked using GX Works2.





#### System expandable according to production equipment scale

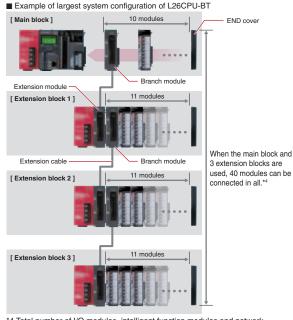
Up to three extension blocks connectable to the main block using branch and extension modules. A maximum of 40 modules\* caters a wide range of production equipment and line scale.

CPU module*2	Number of extension blocks	Number of connectable modules*3	
L02SCPU	Lin to O blooks		
L02CPU(-P)	Up to 2 blocks	Main block: 10 modules	
L06CPU		Extension block: 11 modules	
L26CPU	Up to 3 blocks	Extension block: 11 modules	
L26CPU-(P)BT			

- \*1 In the case of L06CPU, L26CPU, and L26CPU-(P)BT.
- \*2 CPU modules whose first five serial number digits are 13072 or later.
- \*3 Total number of I/O modules, intelligent function modules, network modules and branch modules.

The power supply modules, CPU modules, display units, extension modules, RS-232 adapters and END covers are not included.

When adding a branch module to a fully occupied block, shift one of the other modules to a new block to give way to the branch module.



\*4 Total number of I/O modules, intelligent function modules and network modules, excluding branch modules.

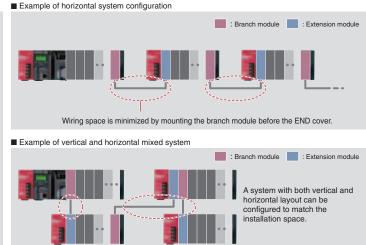
#### Well-organized control panel with minimum wiring

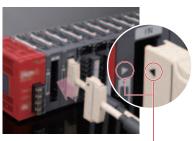
Branch module can be strategically placed in a block to minimize wiring space. Extension cables are available in 0.6-, 1.0- and 3.0-m. The maximum extension length is 3.0 m\*1.

The extension cable is a one-touch type which can be easily connected and disconnected.

\*1 The total length of extension cables should be within 3.0 m.





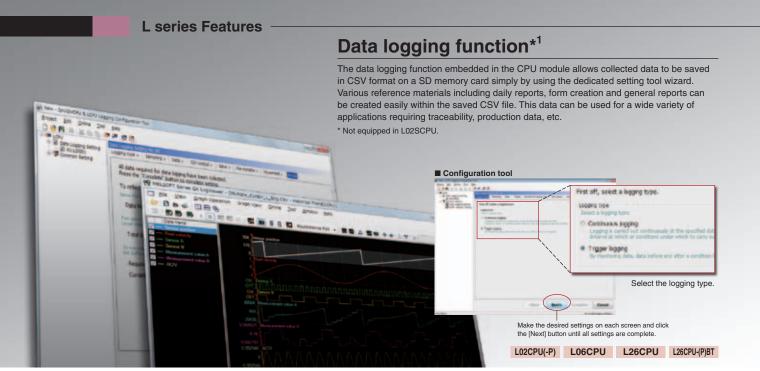


Matching marks on the slot and the cable

Modules	Mounted block	Possible mounting position
Duamah maadula	Main block	Right side of CPU module or left side of END cover
Branch module	Extension block	Right side of extension module or left side of END cover
Extension module	Main block	Impossible
Extension module	Extension block	Right side of power supply module

The modules can be replaced according to the system configuration!

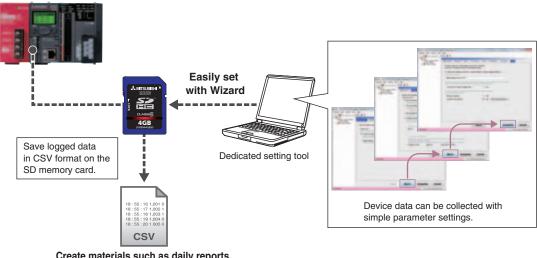
■ Mounting position when branch or extension module is used



#### Easy logging without a program

Logging of device data just by configuring the parameters.

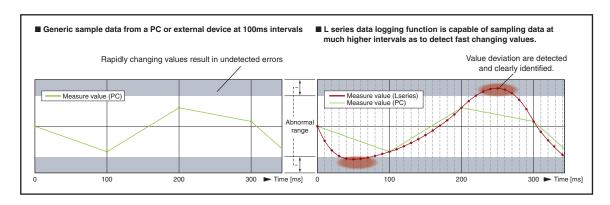
The results can be saved in CSV format on a SD memory card.



Create materials such as daily reports, form creation and general reports

#### Logging of control data variances

Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.

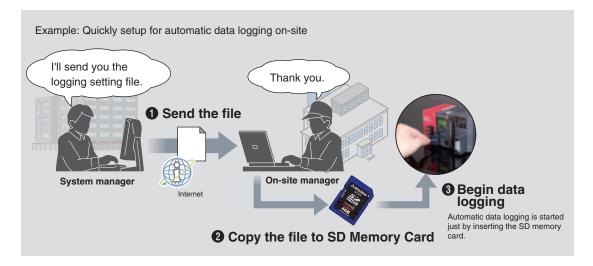


CPU



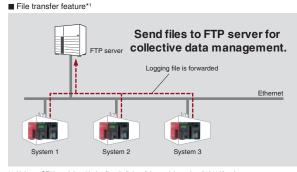
#### Auto logging function

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card (Patent pending).



#### Automatically send logging files to FTP server

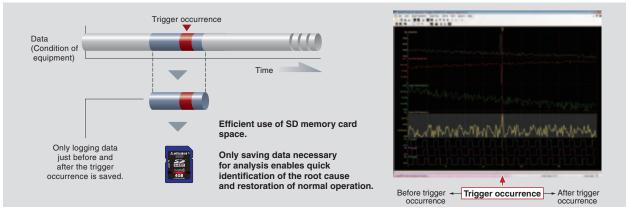
Data logging files saved on the SD memory card can be sent to the FTP server just by making a simple setting with the logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.



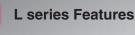
\*1 Using a CPU module with the first 5 digits of the serial number "12112" or later.

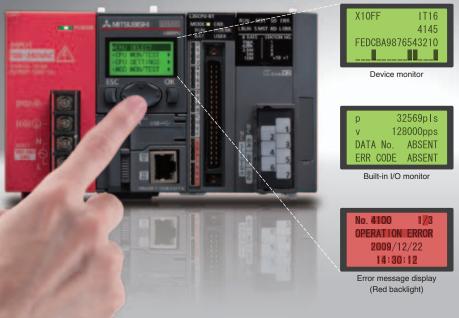
#### **Trigger logging function**

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.



To receive a copy of GX LogViewer, contact your local Mitsubishi Electric representative.





# Feature rich and easy to use display

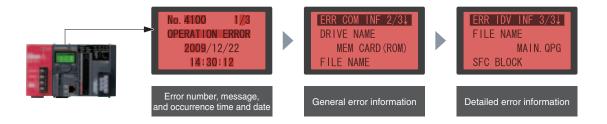
Check the system status and make setting changes directly from the display. Error status is clearly identified and troubleshooting and error investigation can be performed all without the need for any connections or engineering software.

\*1 Not available for L02SCPU.

L02CPU(-P) L06CPU L26CPU L26CPU-(P)BT

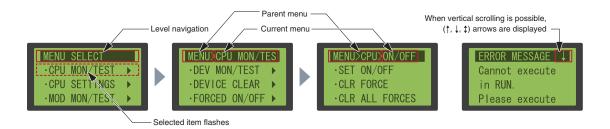
#### Instant error information check

Error history and detailed error information is available directly from the display unit.



#### Intuitive menu navigation

The menu navigation guide shows the current menu tree location and an arrow to indicate the scroll direction at the top of the display.



#### Multilingual operation

The display unit language can be selected (Japanese or English).







MELSEG L series

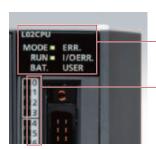
## The L series has been designed from the ground up to be easy to use

The L series module labeling design has been created to ensure clear legibility and identification of information at glance to avoid mistakes.

#### Universal design

[Adopting a universal font]

A high visibility font has been chosen for characters printed on system modules.



■ Regular Gothic font

The characters are thick enough. however the numbers "3, 6, 8, 9" and the alphabet "C" are not clearly distinguishable because the spacing indicated with a red circle is not large

The space indicated with a red circle has been enlarged.

The numbers "3, 6, 8, 9" and the alphabet "C" are clearly distinguishable. Characters are legible even in small print.

#### [Module design]

White and red are used to distinguish inputs from outputs respectively to allow for easy identification of terminal connection type.



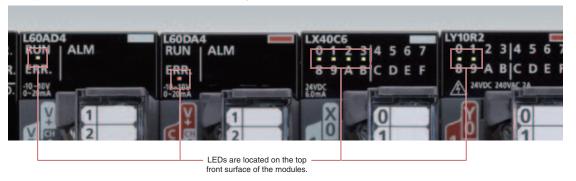




Red for output module

#### Easily identify module status

LEDs display the current status of modules including run and error states.



## **CPU Modules**

■ L02SCP	U
NEW	

Program capacity 20ksteps	Number of I/O points 1024points	Basic operation processing speed 60ns	
RS-232	USB		
General Output Sink type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning 2 axes	Built-in I/O High-Speed Counter 2 ch



\*End cover is enclosed.

Cannot be mounted on display unit (L6DSPU).

#### ■ L02CPU

Program capacity 20ksteps	Number of I/O points 1024points	Basic operation processing speed 40ns	
Ethernet	USB		
General Output Sink type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning <b>2</b> axes	Built-in I/O High-Speed Counter 2 ch



\*END cover is included.

#### ■ L02CPU-P

Program capacity 20ksteps	Number of I/O points 1024points	Basic operation processing speed 40ns	
Ethernet	USB		
General Output Source type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning 2 axes	Built-in I/O High-Speed Counter 2 ch



\*END cover is included.

#### ■ L06CPU NEW

Program capacity <b>60k</b> steps	Number of I/O points 4096points	Basic operation processing speed <b>9.5</b> ns	
Ethernet	USB		
General Output Sink type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning 2 axes	Built-in I/O High-Speed Counter 2 ch



END cover is included

#### ■ L26CPU NEW



Program capacity 260ksteps	Number of I/O points 4096points	Basic operation processing speed 9.5ns	
Ethernet	USB		
General Output Sink type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning 2 axes	Built-in I/O High-Speed Cou 2 ch



\*END cover is included.



#### ■ L26CPU-BT

Program capacity 260ksteps	Number of I/O points 4096points	Basic operation processing speed 9.5ns
Ethernet	USB	CC-Link Ver.2.0
General Output Sink type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning <b>2</b> axes



\*END cover is included.

#### Built-in I/O High-Speed Counter 2 ch

#### ■ L26CPU-PBT

Program capacity 260ksteps	Number of I/O points 4096points	Basic operation processing speed <b>9.5</b> ns	
Ethernet	USB	CC-Link Ver.2.0	
General Output Source type	Built-in I/O 16 inputs / 8 outputs	Built-in I/O Positioning 2 axes	Built-in I/O High-Speed Counter 2 ch



\*END cover is included.

### **CPU** packages

■ L02CPU-SET
Includes CPU (L02CPU), power supply module (L61P), and display unit (L6DSPU).



■ L06CPU-SET NEW Includes CPU (L06CPU), power supply module (L61P), and display unit (L6DSPU).



■ L26CPU-BT-SET Includes CPU (L26CPU-BT), power supply module (L61P), and display unit (L6DSPU).



■ L02CPU-P-SET

Includes CPU (L02CPU-P), power supply module (L61P), and display unit (L6DSPU).



■ L26CPU-SET NEW Includes CPU (L26CPU), power supply module (L61P), and display unit (L6DSPU).



■ L26CPU-PBT-SET Includes CPU (L26CPU-PBT), power supply module (L61P), and display unit (L6DSPU).



#### ■ General specifications

ental specifications in which this product can be installed and operated. Unless otherwise specified, these general specifications apply to all L series products.

*General specifications of jointly develo	oped products are different from	those of MELSEC products. Fe	or more information, please r	efer to the product manuals of	r contact your local Mitsubis	shi Electric representative.	
Item		Specification					
Operating ambient temperature	0 to 55°C						
Storage ambient temperature			-25 to 7	75°C			
Ambient humidity (operating)			5 to 95%RH, no	n-condensing			
Ambient humidity (storage)							
			Frequency	Constant accelration	Half amplitude	Sweep count	
	Compliant with	Under intermittent	5 to 8.4Hz	_	3.5mm	10 times each in	
Vibration resistance	JIS B 3502 and IEC 61131-2	vibration	8.4 to 150Hz	9.8m/s <sup>2</sup>	_	X, Y, and Z directions	
		Under continuous	5 to 8.4Hz	_	1.75mm		
		vibration	8.4 to 150Hz	4.9m/s <sup>2</sup>	_		
Shock resistance		Compliant with JIS B 35	02 and IEC 61131-2 (14	7m/s², 3 times each in X	, Y, and Z directions)		
Operating atmosphere			No corrosiv	e gases			
Operating altitude*1		0 to 2000m					
Installation location	Inside a control panel						
Overvoltage category*2	II or less						
Pollution degree*3			2 or le	ess			
Equipment class			Class	S I			

**■ CPU** module specifications

a or o module s	Item		L02SCPU NEW	L02CPU L02CPU-P	L06CPU NEW	L26CPU NEW	L26CPU-BT L26CPU-PBT
Control method				Sto	red program repeat opera	tion	<u>'</u>
I/O control mode			1)	Direct mode is available b	Refresh mode y specifying the direct acc	ess input/output (DX, DY	´).)
0 0 0	Programming language (sequence control language)		Function block, rela	ay symbol language, MEL	SAP3 (SFC), MELSAP-L,	structured text (ST), logi	c symbolic language
Processing speed*1	LD X0		60ns	40ns		9.5ns	
(sequence instruction)	MOV DO I	D1	120ns	80ns		19ns	
Constant scan				0.5 to 2000ms (Setting	is available in increments	of 0.5ms by parameter.)	
Program size			20k steps (	(80k bytes)	60k steps (240k bytes)	260k steps	(1040k bytes)
	Program r	nemory (drive 0)	80k t	oytes	240k bytes	1040	k bytes
	Memory ca	ard (RAM) (drive 1)			_		
Memory capacity	Memory ca	ard (ROM) (drive 2)	_		Depends on the SD/SDI	HC memory card used.*2	
	Standard	RAM (drive 3)	128k	bytes		768k bytes	
	Standard	ROM (drive 4)	512k	bytes	1024k bytes	2048	k bytes
	Program r	nemory	64 files 124 files			252	2 files
	Memory c	ard (RAM)			_		,
Maximum number of	Memory	SD	_		Root directory: 51 Subdirectory: 6553	, ,	
files stored	card (ROM	SDHC	_	Root directory: 65534 files (maximum) Subdirectory: 65533 files (maximum)			
5	Standard	DAM	4 files (each one of the following files: file register file, local device file, sampling trace file, and module error collection file)				
	Standard ROM		128 files 256 files				
Maximum number of in		Initial setting	2048 pai			4096 parameters	
function module param	0	Refresh	1024 pai			2048 parameters	
Maximum number of m			30			40	
Built-in I/O function	ioddies spe	Cilication		·	L puilt-in I/O specifications =		
Data Logging function			_		efer to the Data Logging fu		201
Built-in Ethernet function	n			110	Refer to the built-in Ether	· · · · · · · · · · · · · · · · · · ·	
Built-in Serial Commun		ction	Refer to the Built-in Serial Communication specifications ⇒ P.22		-	-	•
Built-in CC-Link function			Refer to the CC-Lir Master/Local Modu				Refer to the CC-Link Master/Local Module specifications. → P.57
	Displayed	information	Year, mo	onth, date, hour, minute, s	econd, and day of the we	ek (automatic leap year d	detection)
Clock function	Accuracy		0°C: -2.96 to +3.74s (TYP. +1.42s) per day 25°C: -3.18 to +3.74s (TYP. +1.50s) per day 55°C: -13.20 to +2.12s (TYP3.54s) per day				
	ODLI	With display unit	_	1.00A	1.0	6A	1.43A
5VDC internal current	CPU	Without display unit	0.75A	0.94A	1.0		1.37A
consumption	END cove	r (Accessory)*4			0.04A		1
		With display unit	_		0.40kg		0.50kg
Weight	CPU	Without display unit	0.32kg		0.37kg		0.47kg
	END cove	r (Accessory)*4	3		0.06kg		, ,

<sup>\*1:</sup> Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0m.
Doing so may cause malfunction. When using the programmable controller under pressure, please consult your local Mitsubishi Electric representative.

\*2: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises.
Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300V is 2500V.

\*3: This indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used.
Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally.

<sup>\*1:</sup> Indexing devices does not delay processing time.

\*2: Mitsubishi Electric shall not guarantee the operation of any non-Mitsubishi Electric products.

\*3: The total number of modules that can be mounted to a CPU. Refer to the "Maximum number of modules specification" for each module.

(Power supply modules, CPU module, Display unit, Extension module, RS-232 adapter, END cover, and END cover with error terminal are not included. Note that only one CPU or head module per system is

possible.)
\*4: The END cover is included with the CPU module and must be placed on the right end of the last module in the system.

CPU



■ CPU module device specifications

	Item	L02SCPU NEW	L02CPU L02CPU-P	L06CPU NEW	L26CPU NEW	L26CPU-BT L26CPU-PBT
Number of I/O dev	vice points	OLOG I LINAMA MALEET				
(number of points	available on a program)		81	92 points (X/Y0 to X/Y1FI	FF)	
Number of I/O poi		1024 points (X/Y0 to X/Y3FF) 4096 points (X/Y0 to X/YFFF)				
nternal relay (M)				M0 to M8191) by default		- /
Latch relay (L)				(L0 to L8191) by default (		
Link relay (B)				(B0 to B1FFF) by default		
Timer (T)		2048 points (T0 to T2047) by default (changeable) (Low-speed and high-speed timers available)  Low-speed or high-speed is specified by an instruction.  The measurement unit is set by parameter.  (Low-speed timer: 1 to 1000ms (in increments of 1ms), default: 100ms)  (High-speed timer: 0.1 to 100ms (in increments of 0.1ms), default: 10ms)				
Retentive timer (S	Т)	0 points by default (changeable)(Low-speed and high-speed timers available) Low-speed or high-speed is specified by an instruction. The measurement unit is set by parameter. (Low-speed retentive timer: 1 to 1000ms (in increments of 1ms), default: 100ms) (High-speed retentive timer: 0.1 to 100ms (in increments of 0.1ms), default: 10ms)				
Counter (C)			Normal counter 1024	points (C0 to C1023) by	default (changeable)	
Data register (D)			12288 points	(D0 to D12287) by defaul	t (changeable)	
Extended data reg	gister (D)	32768 points (D12288 to D45055) by default (changeable) (131072 points (D12288 to D143359) by default (changeable)				
Link register (W)			8192 points (	W0 to W1FFF) by default	(changeable)	
Extended link regi	ster (W)		0 p	oints by default (changea	ble)	
Annunciator (F)		2048 points (F0 to F2047) by default (changeable)				
Edge relay (V)		2048 points (V0 to V2047) by default (changeable)				
ink special relay	(SB)			SB0 to SB7FF) by default	· · · · · · · · · · · · · · · · · · ·	
ink special regist	er (SW)		2048 points (S	W0 to SW7FF) by defaul	t (changeable)	
File register	(R)	(Maximum 65536 po	R0 to R32767) pints are available by g blocks.)		2768 points (R0 to R3276 16 points are available by	,
	(ZR)	65536 points (Z (Blocks do not nee	R0 to ZR65535) ed to be switched.)		216 points (ZR0 to ZR393 ks do not need to be switch	,
Step relay (S)		8192 points (S0 to S8191) by default (The points can be changed to 0.)				
ndex register/star	ndard device register (Z)		20	points (Z0 to Z19) (maxim	ium)	
ndex register (Z)	fication of ZR device)			points (Z0 to Z18) (maxim gister is used as a double		
Pointer (P)	nouncil of Erraction	4096 points (PC	to P4095) (The local poin	ter range and the commo	on pointer range can be se	et by parameter)
Interrupt pointer (I	)	4096 points (P0 to P4095) (The local pointer range and the common pointer range can be set by parameter.)  256 points (I0 to I255)  (The fixed scan interval for the system interrupt pointer I28 to I31 can be set by parameter.)  0.5 to 1000ms (in increments of 0.5ms)  Default I28: 100ms, I29: 40ms, I30: 20ms, I31: 10ms				
Special relay (SM)	)			SM2047) (The number of		
Special register (S	<u></u>		. ,	SD2047) (The number of		
unction input (FX				X F) (The number of dev		
unction output (F	<i>'</i>			Y F) (The number of dev		
unction register (				D4) (The number of devi		-
ntelligent function	`	D	evice that directly accesse	, ,	n intelligent function modu	ile
Latch (data retenti	ion during power failure) range	(Tho		points (L0 to L8191) by d	lefault	

#### ■ CPU built-in I/O - Input signal assignment

○: Selectable X: No combination

External input signal	Function				
External input signal	General-purpose input	Interrupt input	Pulse catch	High-speed counter	Positioning
X0(high-speed)	0	O*1	0	Counter CH1 A phase <sup>1</sup>	x.3
X1(high-speed)	0	O*1	0	Counter CH1 B phase <sup>-1</sup>	x*3
X2(high-speed)	0	O*1	0	Counter CH2 A phase <sup>1</sup>	x.3
X3(high-speed)	0	○*1	0	Counter CH2 B phase <sup>-1</sup>	X*3
X4(high-speed)	0	0	0	Counter CH1 Z phase <sup>-2</sup>	Axis #1 Zero signal <sup>2</sup>
X5(high-speed)	0	0	0	Counter CH2 Z phase <sup>+2</sup>	Axis #2 Zero signal <sup>2</sup>
X6(standard)	0	0	0	Counter CH1 Function input <sup>2</sup>	Axis #1 External command signal*2
X7(standard)	0	0	0	Counter CH2 Function input <sup>2</sup>	Axis #2 External command signal*2
X8(standard)	0	0	0	Counter CH1 latch counter <sup>-2</sup>	Axis #1 Drive module READY signal <sup>2</sup>
X9(standard)	0	0	0	Counter CH2 latch counter <sup>-2</sup>	Axis #2 Drive module READY signal*2
XA(standard)	0	0	0	X*3	Axis #1 Near-point dog dignal*2
XB(standard)	0	0	0	X*3	Axis #2 Near-point dog dignal*2
XC(standard)	0	0	0	X*3	Axis #1 Upper limit signal <sup>-2</sup>
XD(standard)	0	0	0	X*3	Axis #2 Upper limit signal*2
XE(standard)	0	0	0	x*3	Axis #1 Lower limit signal*2
XF(standard)	0	0	0	X*3	Axis #2 Lower limit signal*2

<sup>\*1:</sup> When using CH1 for the high-speed counter function, X0 and X1 cannot be used as interrupt inputs. Also, when using CH2 for the high-speed counter function, X2 and X3 cannot be used as interrupt inputs. Other functions such as the general-purpose input can be used.

\*2: When this signal is not required, the input signal can be used for other functions such as the general-purpose input.

\*3: When the high-speed counter function or positioning function is selected, this signal is not used for that function. This input signal may be used for another function such as a general-purpose input.

#### ■ CPU built-in I/O - Output signal assignment

O: Selectable X: No combination

Estamation deliment	Function					
External input signal	General-purpose output	High-speed counter	Positioning			
YO	0	CH1 Coincidence output No.1*1	X*3			
Y1	0	CH2 Coincidence output No.1*1	X*3			
Y2	0	CH1 Coincidence output No.2*2	Axis #1 Deviation counter clear*1			
Y3	0	CH2 Coincidence output No.2*2	Axis #2 Deviation counter clear*1			
Y4	0	×*3	Axis #1 CW/PULSE/A phase output*1			
Y5	0	×*3	Axis #2 CW/PULSE/A phase output*1			
Y6	0	X*3	Axis #1 CCW/SIGN/B phase output*1			
Y7	0	×*3	Axis #2 CCW/SIGN/B phase output*1			

■ CPII built-in I/O function - input execifications (general input/interrupt input/pulse catch function)

Item			Description
	Points		10
	Input voltage/current		24VDC 4.1mA (TYP.)
Standard input	The minimum input response time		100µs
	Input response time setting		0.1ms/1ms/5ms/10ms/20ms/70ms
	Common terminal arrangement		10 points/common (Positive or negative common)
	Points		6
	Input voltage/current	DC input	24VDC 6.0mA (TYP.)
		Differential input	EIA Standard RS-422-A Differential line driver level
High-speed input		Dillerential input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent
	The minimum input response time		10μs
	Input response time set	ting	0.01ms/0.1ms/0.2ms/0.4ms/0.6ms/1ms
	Common terminal arrangement		Independent

<sup>\*\*</sup>T: This signal must be used depending on parameter settings.

When this signal is not used, the output signal can be used for the general-purpose output function.

\*2: When this signal is not used, the output signal can be used for the general-purpose output function.

\*3: When the high-speed counter function or positioning function is selected, this signal is not used for that function.

This input signal may be used for another function such as a general-purpose output.

MELSEG L series

■ CPU built-in I/O function - output specifications (general output function)

Item		Description
Points		8
Output voltage/current		5 to 24VDC 0.1A
Response time	OFF to ON ON to OFF	1μs or less (rated load, resistance load)
Common terminal arrangement		L02SCPU NEW, L02CPU, L06CPU NEW, L26CPU NEW, L26CPU-BT: 8 points/common (Sink type) L02CPU-P, L26CPU-PBT: 8 points/common (Source type)

■ CPU built-in I/O function - positioning function specifications

Item			Description		
Number of controlled axes Control unit			2		
			pulse		
On a seation in a	. tta	PTP*1 control	Available		
Operation pa	allem	Path control	Not usable		
Number of p	ositioning data		10 data/axis		
	Desitioning control	PTP*1 control	ABS/INC		
	Positioning control method	Speed/position switching control	INC		
		PTP*1 control	-2147483648 to 2147483647 pulses		
ositioning ontrol	Positioning range	Speed/position switching control	0 to 2147483647 pulses		
	Speed command		0 to 200 kpulses/s		
	Acceleration/decelera	tion system selection	Automatic trapezoid acceleration/deceleration and S-curve acceleration/deceleration		
	Acceleration/decele	eration time	0 to 32767 ms		
PR method	1		6 types		
		1)	Trapezoid acceleration/deceleration (single-axis start): 30 μs/axis		
tarting time	(1-axis linear contro	1)	S-curve acceleration/deceleration (single-axis start): 35 µs/axis		
	Pulse output method		L02SCPU NEW, L02CPU, L06CPU NEW, L26CPU NEW, L26CPU-BT: 5 to 24VDC (Sink type)  L02CPU-P, L26CPU-PBT: 5 to 24VDC (Source type)		
ommand	Pulse output mode		4 types		
ulse output	Maximum output pulse		200 kpulses/s		
	Maximum connection of	distance with drive unit	2 m		
		DC input	24VDC 6.0 mA (TYP.)		
	Zero signal	Differential inner	EIA RS-422-A differential line driver level		
		Differential input	(AM26LS31 (by Texas Instruments Japan Limited.) or equivalent)		
	Speed/position swit	ching signal			
xternal	Near-point dog sign	nal	24VDC 4.1 mA (TYP.)		
put	Upper and lower lin	nit signal	24VDC 4.1 MA (11F.)		
	Drive unit ready sig	nal			
			Zero signal: 10 μs		
	Input response time	9	Speed/position switching control, near-point dog signal: 100 μs		
			Upper and lower limit signal, drive unit ready signal: 2 ms		
External	Deviation counter c	lear signal	L02SCPU NEW, L02CPU, L06CPU NEW, L26CPU NEW, L26CPU-BT: 5 to 24VDC 0.1A (Sink type) L02CPU-P, L26CPU-PBT: 5 to 24VDC 0.1A (Source type)		
output	Response time OFF to ON ON to OFF		1 µs or less (rated load, resistive load)		

<sup>\*1:</sup> Abbreviation for "Point to Point." This is a type of position control.

■ CPU built-in I/O function - high-speed counter specifications

CPU bu		- nign-spe	ed counter specifications	
	Item		Description	
Number of c	hannels		2	
	Phase		1-phase input (1 multiple/2 multiples)	
			CW/CCW,	
Count input			2-phase input (1 multiple/2 multiples/4 multiples)	
signal		DC input	24VDC 6.0mA (TYP.)	
	Signal level	Differential	EIA Standard RS-422-A Differential line driver level	
		input	(AM26L31(manufactured by Texas Instruments Incorporated) or equivalent)	
	Maximum counting speed	i	200k pulse/s (for 2 multiples of 1 phase and 4 multiples of 2 phases)	
	Counting range		-2147483648 to 2147483647	
	Model		UP/DOWN preset counter (with ring counter function)	
Counter	Minimum count pulse	1 phase	5µs	
	width (Duty ratio 50%)	2 phases	10µs	
	Min. phase differential for	2-phase	5µs	
	input		<u> </u>	
		DC input	24VDC 6.0mA (TYP.)	
	Phase Z (preset)	Differential	EIA Standard RS-422-A Differential line driver level	
External		input	(AM26L31(manufactured by Texas Instruments Incorporated) or equivalent)	
input	Function start		24VDC 4.1mA (TYP.)	
iiiput	Latch		24VDC 4.11IIA (TT.)	
	Input response time		Phase Z: 10µs	
	Imput response time		Function start, latch: 100μs	
	Output format		L02SCPU NEW, L02CPU, L06CPU NEW, L26CPU NEW, L26CPU-BT: Sink type	
	- Cutput Ionnat		L02CPU-P, L26CPU-PBT: Source type	
		Coincidence		
External		output No. 1 /	5 to 24 VDC / 0.25 A*1	
output	Output voltage / current	PWM output		
output		Coincidence	5 to 24 VDC / 0.1 A	
		output No. 2	0.021.029,0.17.	
	Response time	OFF to ON	1µs or less (Rated load, resistance load)	
	Tiooponoo umo	ON to OFF	THE OFFICE (Material Back, Total Back)	
	Comparison range		-2147483648 to 2147483647	
Coincidence			Set value < Counted value	
output	Comparison result		Set value = Counted value	
output			Set value > Counted value	
	I/O points		2 points / channel	
	Output frequency range		DC to 200kHz	
PWM	ON width		1µs	
output	Duty ratio		On width can be set in increments of 0.1µs.	
	I/O points		1 point / channel	
- 1 15	Measurement item		Pulse width (On width: 200µs or more, Off width: 200µs or more)	
Pulse width	Measurement resolution		5µs	
measurement	Measurement points		1 point/channel	

<sup>\*1:</sup> For units where the first six digits of the serial number are "120722" or later. The specification for previous serial numbers is 5 to 24 VDC / 0.1 A.

■ CPU Data logging function specifications

		tem	L02CPU L02CPU-P	L06CPU NEW	L26CPU NEW	L26CPU-BT L26CPU-PBT	
Number of data logging settings			10				
Data logging	g buffer capa	acity	For each setting, any of 32 to 4832 k bytes (in units of 1 k byte) can be specified.  The total value of settings No.1 to No.10 is up to 5120 k bytes.				
Data storage	e location			Standard ROM (configuration	on files only), SD Memory Card		
Logging typ	е			<ul> <li>Continuous loggin</li> </ul>			
Data	Sampling in	nterval	• (	<ul> <li>Each scanning cycle condition specification (Device</li> </ul>	<ul> <li>Time specification specification, Step No. specification</li> </ul>	on)	
	No. of data	sampling points		Up to 1280 (128	3 points per setting)		
sampling	AND conjui	nction	In the Sampling interval se	0,	der "Condition specification" can bonjunction).	pe specified in combination	
		Trigger condition	• When	ition specification (Device char trigger instruction executed data logging trigger activated	nge specification, Step No. specifi	cation)	
Data	Trigger	AND conjunction	In the Trigger setting, Device data change and Step No. under "Condition specification" can be specified in combination (AND conjunction).				
processing	logging	Trigger logging range	Data of the specified number of records are logged before and after a trigger.				
		Number of triggers	1				
	Number of trigger logging records			Up to	1000000		
	File Name		• File num		rs can be used for the following. racter string (name)*2 • Date at	nd time*2	
	File format				SV file		
File output	Data type			• Word (unsigned) ouble precision] • Double word • Character significant characters	0 , (0 ,	-	
	Data outpu	t format (CSV file)	Decimal	ormat • Hexadecimal for	ormat • Exponential format	t	
Handling of	File	File switching timing		No. of record	ds • File size		
output files	switching	Number of saved files		1 to	65535		

<sup>\*1:</sup> Part of the saved file name, this number is automatically assigned.
\*2: Optional data to be appended to the saved file name.



**■ CPU** built-in Ethernet function specifications

Item			L02CPU L02CPU-P	L06CPU NEW	L26CPU NEW	L26CPU-BT L26CPU-PBT		
	Data transfer spee	ed		100 or 10 Mbps				
	Communication m	ode	Full-duplex or half-duplex					
Transmission	Transmission meth	nod	Base band					
specifications Maximum distance between hub and node			100 m					
	Maximum number of	10BASE-T		Cascade connection: Up to four				
	nodes/connection	100BASE-TX	Cascade connection: Up to two					
Number of	TCP/IP		Total of 1	6 for socket communications, M	ELSOFT connections, and MC	C protocol.*1		
connections	UDP/IP			One fo	or FTP			
Connection	10BASE-T			Ethernet cable of category 3	or higher (STP/UTP cable)*3			
cable*2	100BASE-TX		Ethernet cable of category 5 or higher (STP cable)					

- \*1: Only the OnA-compatible 3E frame may be used.
  \*2: Straight through cable. Also, when the CPU is connected directly with a GOT, a cross cable (category 5e or less) may be used.
  \*3: The use of STP (Shielded Twisted Pair) cables is recommended in noisy environments.

**■ CPU** built-in serial communication function specifications

ltown	L02SCPU
Item	NEW NEW
Communication mode	Full duplex
Synchronization method	Start-stop synchronization method
Transmission speed	9.6kbps, 19.2kbps, 38.4kbps, 57.6kbps, 115.2kbps
	Start bits: 1
Data format	Data bits: 8
Data format	<ul> <li>Parity bits: Odd number</li> </ul>
	Stop bits: 1
MC protocol format *1 (automatic judgment)	Formats 4 (ASCII)
ivic protocor formati * (automatic judgment)	• Formats 5 (Binary)
Frame *1	QnA compatible 3C frame
ridille '	QnA compatible 4C frame
Transmission control	DTR/DSR control
Transmission distance (Overall distance) Maximum 15m	

<sup>\*1:</sup> Information relevant to the MC protocol format and frame are shown below.

			: Supported x: Not supported
Function		Formats 4	Formats 5
Communication with	QnA compatible 3C frame	0	×
ASCII code	QnA compatible 4C frame	0	×
Communication with binary code	QnA compatible 4C frame	0	0

#### ■ How to read the product code

Built-in I/O output format

## **CPU - P BT - SET**② ③ ⑤ ⑥ 1 2

Р

Number	Item	Code	Specification
		02	20k steps
1	Program memory capacity	06	60k steps
		26	260k steps

Number	Item	Code	Specification
② Comr	Communication interface	Blank	Built-in Ethernet model
	communication interface	S	Built-in RS-232 model

3	3 Type of module		CPU module
Number	Item	Code	Specification
<b>A</b>	Built in I/O output format	Blank	Sink type

Number	Item	Code	Specification
(5)	Built-in CC-Link function	Blank	_
		BT	/

Source type

Number	Item	Code	Specification
Product set	Blank	-	
	Product set	SET	Set includes a power supply module (L61P) and display unit (L6DSPU)

## **Branch / Extension Module**

■ L6EXB

For extension system (branch)

■ L6EXE

For extension system (extension)





#### ■ Specifications for branch and extension modules

Item	L6EXB [ Branch module ]	L6EXE [ Extension module ]
5VDC internal current consumption	0.08A	0.08A
Weight	0.12kg	0.13kg

#### ■ Specifications for extension cables

Item	LC06E	LC10E	LC30E
Cable length	0.6m	1.0m	3.0m
Weight	0.19kg	0.23kg	0.45kg

## **Power Supply Modules**

■ L61P

Input 100 to 240VAC Output **5VDC**, **5A** 



■ L63P

Input 24VDC Output **5VDC, 5A** 



#### ■ Power supply module specifications

Item	L61P	L63P
Input power supply	100 to 240VAC (-15% to +10%)	24VDC (-35% to +30%)
Input frequency	50/60Hz (-5% to +5%)	_
Input voltage distortion	Within 5%	_
Maximum input apparent power	130VA	_
Maximum input power	_	45W
Inrush current	20A, within 8ms	100A, within 1ms (24VDC input)
Rated output current (5VDC)		5A
Overcurrent protection (5VDC)	5.5A or more	
Overvoltage protection	5.5 to 6.5V	
Efficiency	70% or more	
Allowable momentary power failure time	Within 10ms	Within 10ms (24VDC input)
Weight	0.32kg	0.29kg

# MELSEG L series

#### RS-232 Adapter

■ L6ADP-R2

RS-232	Transmission speed 115.2kbps
For GOT connection	MELSOFT*1 connectable

<sup>\*1:</sup> Refer to each MELSOFT product manual for details on the supported software.



■ RS-232 adapter specifications

=			
Item	Specification		
Maximum data transmission speed	115.2kbps		
5VDC internal current consumption	0.02A		
Weight	0.10kg		

## END Cover with Error Terminal

■ L6EC-ET

Error output Relay



■ END cover with error terminal specifications

	Item		Specification	
	Rated switching voltage, current		24VDC 0.5A	
	Minimum switching load		5VDC, 1mA	
	Response time	OFF to ON	10ms or less	
ERR. terminal	nesponse time	ON to OFF	12ms or less	
Enn. tellilliai	Life	Mechanical	20 million times or more	
		Electrical	Rated switching voltage/current: 10 million times or more	
	Surge suppressor		_	
	Fuse		_	
Applicable wire size			0.3 to 2.0mm² (AWG22 to 14) (Twisted wire/Solid wire)	
External connections			Spring clamp terminal block	
5VDC internal current consumption		n	0.06A	
Weight			0.11kg	

## **Display Unit**

■ L6DSPU

Number of display characters

16 characters x 4 lines

Language selection

Japanese or English

Backlight display

Green or Red



■ Display Unit specifications

Display Offic specifications	
Item	Specification
Number of displayed characters	16 one-byte characters × 4 lines
	Alphanumeric (two-byte/one-byte character)
	<ul> <li>Katakana (two-byte/one-byte character)</li> </ul>
Displayed characters	<ul> <li>Hiragana (two-byte character)</li> </ul>
	Chinese character (two-byte character)
	<ul> <li>Symbol (two-byte/one-byte character)</li> </ul>
Language	Japanese/English
Backlight	Green (normal), red (error)
Weight	0.03kg

## Input Modules

LX10	
AC inpu	ı

Number of inputs 16points	Rated input voltage 100 to 120vac
Response time 20ms or less	External connections 18-point terminal block



■ LX28 AC input

Number of inputs <b>8points</b>	Rated input voltage 100 to 240vAC
Response time 20ms or less	External connections 18-point terminal block



■ LX40C6 DC input

Number of inputs 16points	Rated input voltage <b>24VDC</b>	Positive/Negative common
Response time 1 to 70ms or less	External connections 18-point terminal block	



■ LX41C4 DC input

Number of inputs 32points	Rated input voltage <b>24VDC</b>	Positive/Negative common
Response time 1 to 70ms or less	External connections 40-pin connector	



■ LX42C4 DC input

Number of inputs 64points	Rated input voltage <b>24VDC</b>	Positive/Negative common
Response time 1 to 70ms or less	External connections 40-pin connector ×2	



CPU



#### Positive or negative common

LX40C6 LX41C4 LX42C4

All DC input modules are capable of using both positive or negative common connections; separate modules are not necessary.

#### Adjustable sensing speed

LX40C6 LX41C4 LX42C4

For all DC input modules, match the response speed to the connected devices. Choose from 1, 5, 10, 20 or 70ms.

## ■ Input module specifications

#### [ AC input module ]

Ite	em	LX10	LX28
Number of inpu	ut points	16 points	8 points
Rated input vol	tage, frequency	uency 100 to 120VAC (+10%/-15%), 50/60Hz (±3Hz) 100 to 240VAC (+10%/-15%), 50/60Hz(±3	
Input voltage distortion Within 5%		n 5%	
Rated input cui	rrent	8.2mA (100VAC, 60Hz), 6.8mA (100VAC, 50Hz)	16.4mA (200VAC, 60Hz), 13.7mA (200VAC, 50Hz), 8.2mA (100VAC, 60Hz), 6.8mA (100VAC, 50Hz)
Inrush current		Max. 200mA within 1ms	Max. 950mA within 1ms
ON voltage/ON	l current	80VAC or higher/5mA	or higher (50Hz, 60Hz)
OFF voltage/O	FF current	30VAC or lower/1.7mA or lower (50Hz, 60Hz)	
Input impedance	ce	12.2kΩ (60Hz), 14.6kΩ (50Hz)	
Response	OFF to ON	15ms or less (100VAC 50Hz, 60Hz)	15ms or less (100VAC 50Hz, 60Hz) 10ms or less (200VAC 50Hz, 60Hz)
time	ON to OFF	20ms or less (100VAC 50Hz, 60Hz)	20ms or less (100/200VAC 50Hz, 60Hz)
Common termin	nal arrangement	16 points/common	8 points/common
Maximum num specification	ber of modules	Counts as 1 module	
Number of occ	upied I/O points	16 points (I/O assignment: input 16 points)	
External conne	ctions	18-point screw	terminal block
5VDC internal consumption	current	90mA (TYP. all points ON) 80mA (TYP. all points ON)	
Weight		0.17kg	0.15kg

#### [ DC input module ]

[			
Item	LX40C6	LX41C4	LX42C4
Number of input points	16 points	32 points	64 points
Rated input voltage		24VDC (+20%/-15%, ripple ratio within 5%)	
Rated input current	6.0mA TYP. (at 24VDC)	4.0mA TYP.	(at 24VDC)
ON voltage/ON current	15V or higher/4mA or higher	15V or higher/4mA or higher 19V or higher/3mA or higher	
OFF voltage/OFF current	8V or lower/2mA or lower 9V or lower/1.7mA or lower		
Input impedance	3.8kΩ	5.7	kΩ
Response time OFF to ON ON to OFF	1ms/5ms/10ms/20ms/70ms or less Initial setting is 10ms.		
Common terminal arrangement	16 points/common 32 points/common		
Maximum number of modules specification		Counts as 1 module	
Number of occupied I/O points	16 points (I/O allocation: input 16 points)	32 points (I/O assignment: input 32 points)	64 points (I/O allocation: input 64 points)
External connections	18-point screw terminal block	40-pin connector	40-pin connector ×2
5VDC internal current consumption	90mA (TYP. all points ON)	100mA (TYP. all points ON) 120mA (TYP. all points ON)	
Weight	0.15kg 0.11kg 0.12kg		

## **Output Modules**

#### ■ LY10R2 Contact output

·	
Number of outputs 16points	Max. switching load 264vac/125vDc
Rated switching current 2A/point	Response time 12ms or less
External connections 18-point terminal block	



#### ■ LY20S6 Triac output

Number of outputs 16points	Rated load voltage 100 to 240vAC
Max. load current 0.6A/point	Response time  1ms + 0.5cycles  or less
External connections 18-point terminal block	



#### ■ LY40NT5P Transistor output

Number of outputs 16points	Rated load voltage 12 to 24VDC
Max. load current <b>0.5A/point</b>	Response time  1 ms or less
Sink type	Protection Function
External connections	



#### ■ LY41NT1P Transistor output

Number of outputs 32points	Rated load voltage 12 to 24VDC
Max. load current 0.1A/point	Response time  1 ms or less
Sink type	Protection Function



18-point terminal block

## ■ LY42NT1P Transistor output

Number of outputs 64points	Rated load voltage 12 to 24VDC
Max. load current 0.1A/point	Response time  1 ms or less
Sink type	Protection Function
External connections 40-pin	



## ■ LY40PT5P Transistor output

External connections

40-pin connector

Source type	Protection Function
Max. load current 0.5A/point	Response time 1 ms or less
Number of outputs 16points	Rated load voltage 12 to 24VDC



4U-pin connector ×2

#### ■ LY41PT1P Transistor output

Number of outputs 32points	Rated load voltage 12 to 24VDC
Max. load current 0.1A/point	Response time 1 ms or less
Source type	Protection Function



#### ■ LY42PT1P Transistor output

External connections 18-point terminal block

40-pin connector ×2

Number of outputs 64points	Rated load voltage 12 to 24VDC
Max. load current 0.1A/point	Response time 1 ms or less
Source type	Protection Function
External connections	



#### Module protection features

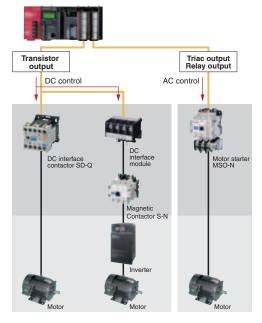
LY40NT5P LY41NT1P LY42NT1P LY40PT5P LY41PT1P LY42PT1P

Modules are built with countermeasures in case of external load short-circuits to protect against over-current and overheating.

#### Direct drive of magnetic contactors

The SD-Q series (DC interface contactor) includes a small VA coil which can be directly driven from the programmable controller without requiring an amplifying relay.

The MS-N series (magnetic contactor) is suitable for a wide range of motor capacities by adding the DC interface module.



		Prog	rammable controller output module	type
		Transistor output	Relay output	Triac output
DC interface contactor SD-Q series	DC control	0	0	_
Magnetic contactor MS-N series	AC control	(Using DC/AC interface module)	0	0
M5-N Series	DC control	0	×	_

<sup>\*</sup> This table shows information relative to the programmable controller output module type and operation interface. There may be restrictions according to the type of frame size, etc., that can be used. Refer to the MS-N series catalog and MS-T series leaflet for the types of magnetic Contactor and models that can be used.

#### ■ Output module specifications

[ Contact output module ]

Contact out	Item	LY10R2			
Number of autout		16 points			
Number of output points		24VDC 2A (resistive load)/point, 8A/common			
Rated switching vo	oltage, current				
Minimum and a later	- 11	240VAC 2A (COS¢=1)/point, 8/ 5VDC 1mA	A/COMMON		
Minimum switching	•				
Maximum switchin	•	264VAC 125VDC			
Response time	OFF to ON	10ms or less			
	ON to OFF	12ms or less			
	Mechanical	20 million times or mor	e		
		Usage environment	Switching life		
		Rated switching voltage/current, rated load	100 thousand times		
Life		200VAC 1.5A, 240VAC 1A (COS $\phi$ = 0.7)	100 thousand times		
	Electrical	200VAC 0.4A, 240VAC 0.3A (COS $\phi$ = 0.7)	300 thousand times		
	Liectrical	200VAC 1A, 240VAC 0.5A (COS $\phi$ = 0.35)	100 thousand times		
		200VAC 0.3A, 240VAC 0.15A ( $COS\phi = 0.35$ )	300 thousand times		
		24VDC 1A, 100VDC 0.1A (L/R = 7ms)	100 thousand times		
		24VDC 0.3A, 100VDC 0.03A (L/R = 7ms)	300 thousand times		
Maximum switchin	ng frequency	3600 times/hour			
Surge suppressor		_			
Fuse		_			
Common terminal	arrangement	16 points/common			
Maximum number	of modules specification	Counts as 1 module			
Number of occupie	ed I/O points	16 points (I/O assignment: 16 in	put points)		
External connection	ons	18-point terminal block			
5VDC internal curi	rent consumption	460mA (TYP. all points C	ON)		
Weight	·	0.21kg	,		

[Triac output module 1

Triac output me	odule j		
	Item	LY20S6	
Number of output points		16 points	
Rated load voltage, fre	equency	100 to 240VAC (+10%/-15%), 50/60Hz(±3Hz)	
Maximum load current	t	0.6A/point, 4.8A/common	
Load voltage distortion	n ratio	Within 5%	
Maximum load voltage	)	264VAC	
Minimum load voltage	/current	24VAC/100mA, 100VAC/25mA, 240VAC/25mA	
Maximum inrush current		20A/cycle or less	
Leakage current at OF	F	3mA or lower (at 240V, 60Hz), 1.5mA or lower (at 120V, 60Hz)	
Maximum voltage drop	p at ON	1.5V or lower (at load current of 0.6A)	
Response time	OFF to ON	Total of 1ms and 0.5 cycles or less	
nesponse unie	ON to OFF	Total of 1ms and 0.5 cycles or less (rated load, resistive load)	
Surge suppressor		CR absorber	
Fuse		None (Attaching a fuse to each external wiring is recommended.)	
Common terminal arra	angement	16 points/common	
Maximum number of r	nodules specification	Counts as 1 module	
Number of occupied I/	O points	16 points (I/O assignment: output 16 points)	
External connections		18-point terminal block	
5VDC internal current	consumption	300mA (TYP. all points ON)	
Weight		0.22kg	

[Transistor output module (Sink type)]

[ Iransistor outp	ut module (Sink type	9) ]					
	Item	LY40NT5P	LY41NT1P	LY42NT1P			
Number of output point	S	16 points	32 points	64 points			
Rated load voltage		12 to 24VDC (+20%/-15%)					
Maximum load current		0.5A/point, 5A/common 0.1A/point, 2A/common					
Maximum inrush currer	nt	Curre	ent is limited by the overload protection fun	ction.			
Leakage current at OF	F		0.1mA or less				
Maximum voltage drop at ON 0.2VDC(TYP.)0.5A, 0.1VDC (TYP.) 0.1A, 0.3VDC(MAX.)0.5A 0.2VDC (MAX.) 0.1A							
Danier time	OFF to ON		0.5ms or less				
Response time ON to OFF			1ms or less (rated load, resistance load)				
Surge suppressor			Zener diode				
Fuse		_					
Protection function	Overload protection	Limited current when detecting overcurrent (overload protection):  1.5 to 3.5A/point.  Activated in increments of 1 point.  Overcurrent detection/overload protection limit current: 1 to 3A/point, Activated in increments of 1 point					
	Overheat protection						
Estamal a succession	Voltage	12 to 24VDC (+20%/-15%, ripple ratio within 5%)					
External power supply	Current	9mA (at 24VDC)/common	13mA (at 24VDC)/common	9mA (at 24VDC)/common			
Common terminal arran	ngement	16 points/common	32 points	s/common			
Maximum number of m	odules specification		Counts as 1 module				
Number of occupied I/O	) points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points)			
External connections		18-point terminal block	40-pin connector	40-pin connector ×2			
5VDC internal current of	consumption	100mA (TYP. all points ON)	140mA (TYP. all points ON)	190mA (TYP. all points ON)			
Weight		0.15kg	0.11kg	0.12kg			

[Transistor output module (Source type)]

Transistor outp	at module (Source	type) ]				
	Item	LY40PT5P	LY41PT1P	LY42PT1P		
Number of output points		16 points	32 points	64 points		
Rated load voltage			12 to 24VDC (+20%/-15%)			
Maximum load current		0.5A/point, 5A/common	0.5A/point, 5A/common 0.1A/point, 2A/common			
Maximum inrush currer	nt	Curre	nt is limited by the overload protection fun-	ction.		
Leakage current at OFF			0.1mA or less			
Maximum voltage drop	at ON	0.2VDC(TYP.)0.5A, 0.3VDC(MAX.)0.5A	0.1VDC (TYP.) 0.1A, 0.2VDC (MAX.) 0.1A			
D	OFF to ON 0.5ms or less					
Response time	ON to OFF 1ms or less (rated load, resistance load)					
Surge suppressor			Zener diode			
use			_			
Protection function	Overload protection	Overcurrent detection: 1.5A or more/point. Activated in increments of 1 point.	1 to 3A/point			
	Overheat protection	Activated in increments of 1 point.	Activated in increments of 2 point.			
	Voltage	12 t	o 24VDC (+20%/-15%, ripple ratio within 5	5%)		
External power supply	Current	17mA (at 24VDC)/common	20mA (at 24V	/DC)/common		
Common terminal arrar	ngement	16 points/common	32 points	s/common		
Maximum number of m	odules specification		Counts as 1 module			
Number of occupied I/C	) points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points		
External connections		18-point terminal block	40-pin connector	40-pin connector ×2		
5VDC internal current of	onsumption	100mA (TYP. all points ON)	140mA (TYP. all points ON)	190mA (TYP. all points ON)		
Weight		0.15kg	0.11kg	0.12kg		

MELSEG L series

#### ■ How to read the product code

# L Y 4 0 NT 5 P 6

Number	Item	Code	Specification
•	① Module type	Χ	Input
1	Module type	Υ	Output

					Specification		
Number	Item	Code	Input n	nodule		Output module	
			AC input	DC input	Contact output	Triac output	Transistor output
		1	100 to 120VAC	_	24VDC/240VAC	_	_
2	Voltage specification	2	100 to 240VAC	_	_	100 to 240VAC	_
		4	_	24VDC	_	_	12 to 24VDC

Number	Item	Code	Specification
	I/O points	0	16 points
3		1	32 points
(3)	I/O points	2	64 points
		8	8 points

Number	Item	Code	Specification
		Blank	AC input
		С	DC input (positive / negative shared common)
<b>(4</b> )	I/O hans	NT	Transistor output module (Sink type)
4)	I/O type	PT	Transistor output module (Source type)
		R	Contact output
		S	Triac output

					Specification		
Number	Item	Code	Input r	nodule		Output module	
			AC input	DC input	Contact output	Triac output	Transistor output
		1	_	_	_	_	0.1A
		2	_	_	2A	_	_
(5)	Current specification	4	_	4mA	_	_	_
		5	_	_	_	_	0.5A
		6	_	6mA	_	0.6A	_

Number	Item	Code	Specification
<u>6</u>	Extra Specifications	P	Includes protection function

## **Analog Input Module**

■ L60AD4

Number of inputs 4 points (channels)	Input voltage -10 to 10vDc	Input current 0 to 20mADC
Conversion speed 20µs/ch	Resolution 1/20000	Accuracy ±0.1%
Scaling function	Shift function	Logging function
Difference conversion function	Input signal error detection extension function	Input range extended mode function
Flow amount integration function	Conversion speed switch function	Warning output function Process alarm
GX Works2		



## **Dual channel Isolation Analog Input Module**

■ L60AD4-2GH NEW

Number of inputs 4 points (channels)	Input voltage -10 to 10vpc	Input current 0 to 20mADC
Conversion speed 40µs/2ch	Resolution 1/32000	Accuracy ±0.05%
Scaling function	Digital filter function	Primary delay function
Shift function	Logging function	Difference conversion function
Input signal error detection extension function	Input range extended mode function	Warning output function Process alarm/rate alarm
Dual channel isolation	Trigger conversion function	Flow amount integration function
GX Works2 Error history		



## **Analog Output Module**

■ L60DA4

Number of outputs 4 points (channels)	output voltage -10 to 10vDc	output current 0 to 20mADC
Conversion speed 20µs/ch	Resolution 1/20000	Accuracy ±0.1%
Scaling function	Warning output function	Analog output HOLD/CLEAR function



CPU



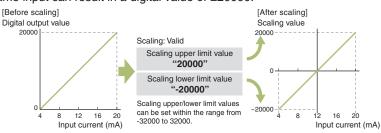
#### Reduce programming man-hours using the scaling function

L60AD4 L60AD4-2GH L60DA4

#### [Scaling function]

The scaling function converts values directly to easy-to-understand units without requiring any programming. Since a separate conversion program is not required, the number of overall programming steps can be reduced. Scaling settings example (L60AD4)

Normally an analog input of 4 to 20mA is converted to a digital value from 0 to 20000. Using the scaling feature, the same input can result in a digital value of ±20000.



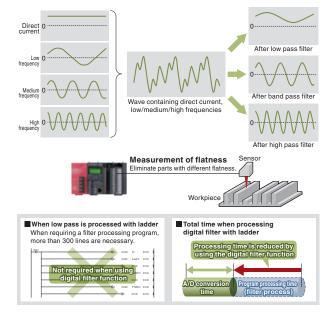
Input current (mA)	Digital output value	Scaling value
4	0	-20000
8	5000	-10000
12	10000	0
16	15000	10000
20	20000	20000

#### [ Digital filtering function\*1 NEW ]

This function eliminates unnecessary frequency elements with simple parameter settings. Select from low pass filter, high pass filter or band pass filter.

Programming steps can be further reduced as extra ladder code is not required to achieve the filter processing.

The filtered A/D conversion program is available at the same time as conversion completion, reducing the overall conversion to filter process time.



#### [ Time lag filter function\*1 NEW ]

The primary delay filter constant outputs a digital value which filters out (smooths) the excessive noise.

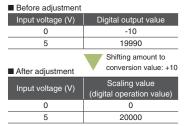
#### Easily and finely adjust the system startup time with the shift function.

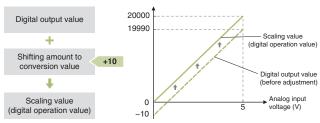
L60AD4 L60AD4-2GH

#### [ Shift function\*1]

Using this function, the set shifting amount to conversion value can be added (shifted) to the digital output value. When the shifting amount to conversion value is changed, it is reflected to the scaling value (digital operation value) in real time. Therefore, fine adjustment can be easily performed when the system starts.

\*1 Compatible with L60AD4 analog input modules starting with serial No. "13041" or higher. For L60AD4





<sup>\*1</sup> Supported only with L60AD4-2GH.

#### Log data for up to 10,000 points

L60AD4 L60AD4-2GH

[Logging function\*1]

or MX Sheet.

Data is continuously collected at the set cycle and stored in the buffer memory.

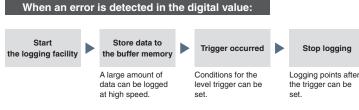
Data stored in the buffer memory can be used for debugging, and to periodically confirm data variations.

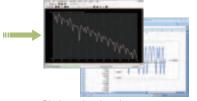
The logging data can be analyzed with the GX LogViewer

ltem ·	Description		
nem	L60AD4	L60AD4-2GH	
Collectable points	10000 pc	10000 points (ch)	
Collectable data	Digital output value or scaling value (digital operation value)		
Logging cycle*2	80 to 32767μs 1 to 32767ms 1 to 3600s	40 to 32767μs 1 to 32767ms 1 to 3600s	
Conversion speed	80µs, or 1ms	40µs / 2ch	
Level trigger condition	Above, Below, Pass Through		
Logging points after trigger	1 to 10000		

<sup>\*1</sup> Compatible with L60AD4 analog input modules starting with serial No. "13041" or higher.

Ex.) When using the sampling processing: Conversion cycle = conversion speed × number of channels in use.



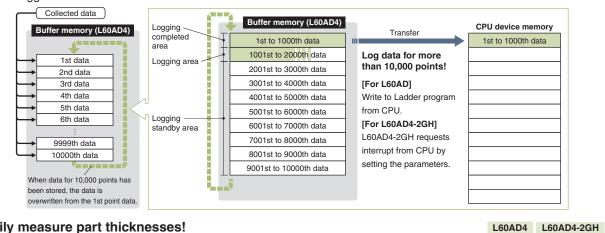


Display and analyze data with GX LogViewer or MX Sheet

Logging data can be transferred to the CPU device memory while still logging.

Logging and data transmission can be executed simultaneously so the next logging session can be started right away. [Logging for 10,000 points and greater]

When logging of 1001 - 2000 points of data commences, the first 1000 points (1 - 1000) are stored into the CPU device memory. By storing every 1000 points of data in the CPU, overall logging of total data larger than 1000 points can be logged.

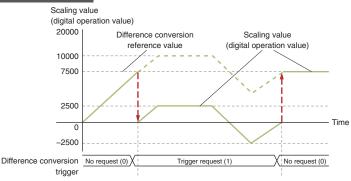


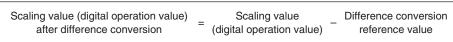
#### Easily measure part thicknesses!

[ Difference conversion function\*1 ]

When the difference conversion starts, the scaling value (digital operation value) at that time is determined as the difference conversion reference value. The value acquired by subtracting the difference conversion reference value from the scaling value (digital operation value) is stored as the scaling value (digital operation value) after difference conversion.

#### For L60AD4





<sup>\*1</sup> Compatible with L60AD4 analog input modules starting with serial No. "13041" or higher.

<sup>\*2</sup> The actual logging cycle is "an integral multiple of the conversion cycle of each A/D conversion method".

CPU



#### Extend the detection method according to applications

L60AD4 L60AD4-2GH

[Input signal error detection extension function\*1]

Using this function, the detection method of the input signal error detection function can be extended. Use this function to detect an input signal error only at the lower or upper limit, or to execute the disconnection detection.

[Input range extended mode function\*1]

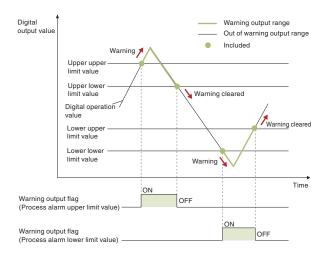
The input range can be extended. By combining this function with the input signal error detection function, simple disconnection detection can be executed.

\*1 This function is compatible with analog input modules starting with serial No. "13041" or higher.

#### [ Warning Output function ]

#### ■ Process Alarm\*1

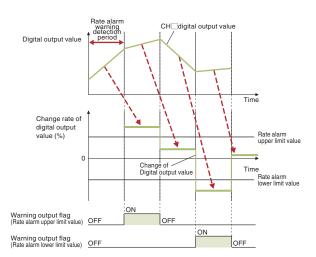
Outputs an alarm when the digital output value exceeds a preset range.



#### ■ Rate alarm\*2 NEW

An alarm is generated if the digital output value's variation rate is larger than the rate alarm upper limit value, or if it is smaller than the rate alarm lower limit value.

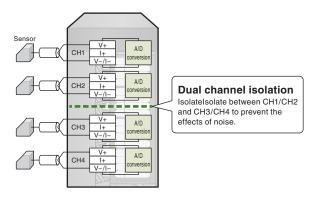
- \*1 Compatible with L60AD4 analog input modules starting with serial No. "13041" or higher.
- \*2 Supported only with L60AD4-2GH.



#### Noise isolation for smoother system operation

#### [ Dual channel isolation NEW ]

Noise interference is prevented by isolating every two channels resulting in far more stable measurements.



L60AD4-2GH

#### A/D variable conversion timing

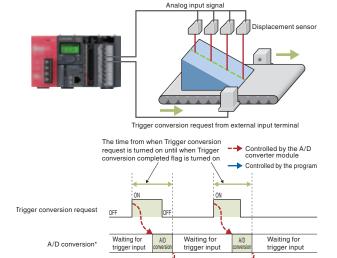
L60AD4-2GH

[ Trigger conversion function NEW ]

A/D conversion is processed at the rising edge of the trigger position timing.

This function enables easier use of the converter and enhances the overall program performance.

There are two types of trigger conversion request: "External trigger conversion request (external input terminal)" or "internal trigger conversion request (buffer memory)".



\* Carried out in order with combination of CH1, CH3 and CH2, CH4.

1st conversion value

#### Quickly calculate and record flow amount

L60AD4 L60AD4-2GH

2nd conversion value

[ Flow amount integration function\*1 ]

This function performs the A/D conversion of analog input value (voltage or current) from a flow meter and others, and integrates the scaling value (digital operation value) by every integration cycle. In this function, integral processing is performed regarding the scaling value (digital operation value) as the instantaneous flow amount.

Digital operation value

Trigger conversion completion flag

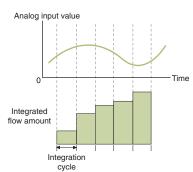
Trigger conversion complete clear request

■ Concept of integral processing

With this function, integral processing is performed using the following formula.

$$\begin{array}{l} \text{Integrated} \\ \text{flow amount} \end{array} = \left( \begin{array}{c} \text{Instantaneous} \\ \text{flow amount} \end{array} \times \frac{\Delta T}{T} \times \text{Unit scaling} \right) + \text{Previous amount} \end{array}$$

<sup>\*1</sup> This function is compatible with analog input modules starting with serial No. "13041" or higher.



Item		Description		
Integrated flow amount	Result of integral processing	g		
Instantaneous flow amount	Instantaneous flow amount	Instantaneous flow amount value output in analog from flow meter		
ΔΤ	Integration cycle (ms)			
	Conversion value to conver	t time unit of instantaneous flow amount to ms unit		
	Range of flow meter	Setting value to specify flow amount time unit	T (ms)	
Т	/s	0	1000	
	/min	1	60000	
	/h	2	3600000	
	Unit scaling for integrated fluid This is used when the value	ow amount e of instantaneous flow amount $\times \Delta T/T$ is 0 to 1.		
	Se	tting value to specify unit scaling	Unit scaling	
		0	1	
Unit scaling		1	10	
		2		
		3		
	4		10000	
Previous amount	Stored integrated flow amou	unt value before integral processing		

CPU



### Realize fast and smooth continuous analog output L60DA4

[ Wave Output function\*1 ]

The industry's first\*2 waveform output function is included. (Patent pending)

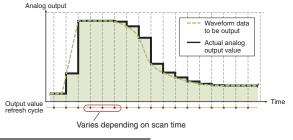
This function enables control wave data that is faster than the program control to be directly registered in the D/A converter module and output the data at a set conversion cycle.

Therefore, the analog output value is not affected by the scan time of the CPU module resulting in faster and smoother analog control

- \*1 Supported by CPU module whose first five serial number digits are "14041" or later.
- \*2 Mitsubishi Electric survey dated April 2012.

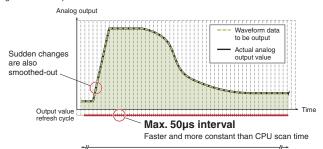
### Analog output from sequence program.

Analog values are output at each scan time.



### Analog output with waveform output function

Analog values are output at set interval.

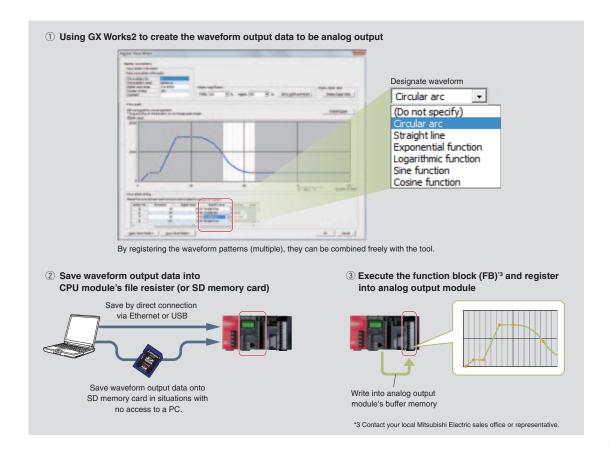


Register up to 50000 points of waveform output data

The actual waveform and the output waveform deviate.



The output waveform is closer to the actual waveform (less deviation).



### Easily adjust waveform output data

L60AD4

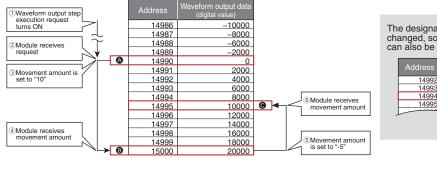
[ Wave output step action function\*1 ]

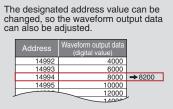
The waveform output data can be changed even when the analog output module is in conversion This provides a good way of adjusting the waveform output while in operation. (Patent pending)

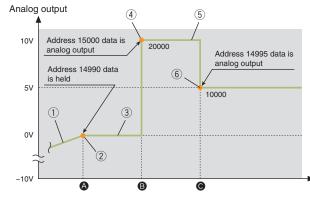
\*1 Supported by CPU module with first five serial number digits are "14041" or later.

### Analog output a designated buffer memory's address value

If current address is "14990" ((A)) the output range is set to -10 to 10V range and receives "waveform output step execution request", the address 15000 (B) and address 14995 (O) data is executed.







Address can be moved to data to be output and the output value can be output

### High-speed conversion L60AD4 L60AD4-2GH L60DA4

High performance analog processing fully utilizing the CPU capability is possible with the 40 $\mu$ s/2ch (L60AD4-2GH) and 20 $\mu$ s/ch (L60AD4, L60DA4) high-speed conversion.

### High resolution L60AD4 L60AD4-2GH L60DA4

Ideal for high-end control.

The 1/32000 (L60AD4-2GH) or 1/2000 (L60AD4, L60DA4) resolution can be realized in all ranges.

### High conversion accuracy L60AD4 L60AD4-2GH L60DA4

The conversion accuracy is high at  $\pm 0.05\%$  (L60AD4-2CH) and  $\pm 0.1\%$  (L60AD4, L60DA4). Realize very accurate control.

### Ensure stability with variable conversion speed L60AD4

The conversion speed can be switched between 20µs/ch, 80µs/ch, and 1ms/ch. By selecting the appropriate conversion speed according the connected device's specifications, stable analog input signals can be obtained even in noisy environments.

MELSEG L series

Management   Man		Item		[ Anal	L60AD4 og input modul	e 1	١,		AD4-2GH NEW	-		[ Ana	L60DA4 log output modu	ıle 1
Analog   Very   Control	Number of a	analog input/output points		[ Allah	og input modul	<u> </u>	1 [			ilpat module j	l	[ Alla	log output mout	ne j
Digital					-10 to	10VDC (Input	resis							
March   Common		Current			0 to 2	0mADC (Input	resis	tance value 250	ΙΩ)				_	
Comparing   Comp	Digital			-20	0480 to 20479			-3:	2000 to 32000				_	
Contract		_				-32768	to 3	2767					_	
Victorial content   Vict	District						_					-2	20480 to 20479	
Analog   Current	-	_										-3	32768 to 32767	
Output   Current   Fig.   Current	Analog						_				-10 to 10VD0	: (Exten	nal load resistance v	value 1kO to 1MO)
Ancient production   Producti							_					_		
10 to 10 to 10 to 2000   250 pt/				Analog input	Digital output	Resolution		Analog input	Digital output	Resolution		`		
O characteristics, resolution   Fig.   0 to 500   0 t													J	
To SV   2000   5000   5000   1000   1000   2000   1000   2000   1000   2000											11		0 to 20000	
10 characteristics, resolution   10 to 90   20000   20000   20000   10 to 90   20000   20000   20000   20000   20000   20000   200000   20000   20000   20000   20000   20000   20000   20000   200000   20000   20000   20000   20000   20000   20000   20000   200000   20000   20000   200000   20000   2000000   200000   200000   200000   200000   200000   200000   2000000   200000   200000   200000   200000   200000   200000   2000000   200000   200000   200000   200000   200000   200000   2000000   200000   200000   200000   2000000   200000   2000000   200000   2000000   2000000   200000000					0 to 20000	<u> </u>			0 to 32000		≤ 1 to			
Between registration			_	1 10 5 V	-20000 to	200μν	_		-32000 to	125µV	- 10 to		-20000 to	500μν
Between registration			'oltag		20000	500μV	'oltag	-10 to 10V	32000	312.5µV	II I	-	20000	
Ambient temperature   2000   1000AH,   10 to 20000   1000AH,   10 to 20000   1000AH,   10 to 20000	I/O charae	cteristics, resolution	O			200μV	e	1 10 0 1		125µV	0 to 2		0 to 20000	
Setting   20000   1000nA   10 20000   10				- 1		307uV*1		1		200μV* <sub>1</sub>	Users		-20000 to	
Accuracy   Conversion speed				_	20000	·		_	32000	·		ing	20000	700HA ·
Ambient temperature   25.5 PK   Users range   -20000 to   1230nA**					0 to 20000				0 to 32000					
Users range			Curr	4 to 20mA			Curr	4 to 20mA						
Accuracy			ent			000181	ent		32000	000.01				
25±5°C						1230nA*1			0 to 32000	400nA*1				
Accuracy of Testing Services (1997)  Accuracy of Testing Services (1997)  Reference accuracy				Within	±0.1% (±20dig	it)*2			_		Within ±0.	1% (vo	Itage: ±10mV, cu	ırrent: ±20μA)*3
Temperature coefficient   High speed: 20µs/ch   Adol.ppm/°C or less**   —	Accuracy	Ambient temperature		Within	+0.2% (+40dia	it)*2					Within ±0.3	3% (vo	Itage: ±30mV. cu	urrent: +60uA)*3
Temperature coefficient	Accuracy			***************************************			$\vdash$	Within	+0.05% (+16dic	nit)*4	***************************************	370 (10		
High speed: 20µs/ch   Medium speed: 80µs/ch**/ Low speed: Handler speed: 80µs/ch**/ Low speed: 1ms/ch**/**   College: ±15V, Current: 30mA***   College: ±15V, Current: 30mA***   College: ±15V, Current: 30mA***   College: 1ms/ch**/**   College: ±15V, Current: 30mA***   College:														
Low speed: 1ms/ch****   Offset/gain setting count   Up to 50000 counts   Up to 100000 counts   Up to 50000 counts   Up to 50000 counts   Up to 100000 counts   Up to 50000 counts   Up to 50000 counts   Up to 100000 counts   Up to 50000 cou				High	speed: 20µs/c	h								
Display a setting count   Up to 50000 counts   Up to 100000 counts   Up to 50000 counts	Conversion	on speed							40μs/2ch				20μs/ch	
Between I/O terminals and programmable controller power supply: photocoupler isolation Between analog input channels: dual channel transformer insulation   Between I/O terminals and programmable controller power supply: photocoupler isolation Between analog input channels: dual channel transformer insulation   Between I/O terminals and programmable controller power supply: \$00VAC for minute Between analog input channels: 1000VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute Between I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminals and programmable controller power supply: \$00VAC for minute I/O terminal	Absolute	maximum input				Voltage: ±15V,	Cur	rent: 30mA*9					_	
Between I/O terminals and programmable controller power supply: photocoupler isolation Between input channels: no insulation Between input channels: notation insulation Between input channels: no insulation Between input channels: notation insulation insulation Between input channels: notation insulation insulation insulation Between input channels: notation insulation Between	Offset/gai	n setting count		Up t	o 50000 count	S		Up to	100000 count	s		Up		s
Between I/O terminals and programmable controller power supply; photocoupler isolation Between input channels: no isolation Between analog input channels: dual channel transformer isolation Between apply: 500VAC for minute Between controller power supply: 500VAC for minute Between information insulation in set in substantial programmable controller power supply: 500VAC for minute Between information insulation resistance   Between I/O terminals and programmable controller power supply: 500VAC for minute Between examal programmable controller power supply: 500VAC for minute Between information insulation resistance   Between I/O terminals and programmable controller power supply: 500VAC for minute Between information insulation resistance   Between I/O terminals and programmable controller power supply: 500VAC for minute Between information insulation insulation resistance   Between I/O terminals and programmable controller power supply: 500VAC for minute Between information insulation insulation resistance   Courts as 1 module   Between I/O terminals and programmable controller power supply: 500VAC for 1 minute Between information insulation	Output sh	ort protection					_				_			
Between I/O terminals and programmable controller power supply: 500VAC/ms for 1 minute Between analog input channels: 1000VAC for minute Between analog input channels: 1000VAC for 1 minute Between incomplete power supply: 500VAC/ms for 1 minute Between analog input channels: 1000VAC for 1 minute Between I/O terminals and programmable controller power supply: 500VDC 10MΩ or higher	Isolation r	nethod		ntroller power s	supply: photoco	upler isolation	controller power supply: photocoupler isolation Between analog input channels: dual channel			controller Betwe	power en out ternal	supply: photoco put channels: no power supply an	oupler isolation insulation d analog output:	
Insulation resistance controller power supply: 500VDC 10MΩ or higher controller controller controller controller controller controller controller controller controll	Dielectric	withstand voltage		ntroller power su	ipply: 500VACri	ms for 1 minute	power supply: 500VAC for minute			controller power supply: 500VACrms for 1 minute Between external power supply and analog output:				
Specification   Number of occupied I/O points   16 points (I/O assignment: 16 points for intelligent)					r supply: 500VI	-	cc							
Number of occupied I/O points   16 points (I/O assignment: 16 points for intelligent)   24VDC (+20%/-15%)     24VDC (+20%/-15%)								Cou	nts as 1 module	Э				
Ripple, spike 500mV <sub>p.p</sub> or lower								points (I/O assig	nment: 16 poin	ts for intelligent	)			
—         Inrush current: 4.3A, 1000μs or shorter           Current consumption: 0.18A           External connections         18-point terminal block           5VDC internal current consumption         0.52A         0.76A         0.16A           Weight         0.19kg         0.20kg         0.20kg           Input points         —         1 point         —           Rated input voltage         —         (+20%/-15%, ripple ratio: within 5%)         —           External trigger input         ON voltage/ON current         —         13V or more, 3mA or more         —           OFF voltage/OFF current         —         8V or less, 1.6mA or less         —           Input resistance         —         3.9kΩ         —           Response         OFF ~ON         —         40µs         —           *1: Maximum resolution in users range settings.			$\vdash$								Rir			,
External connections         18-point terminal block           5VDC internal current consumption         0.52A         0.76A         0.16A           Weight         0.19kg         0.20kg         0.20kg           External trigger input         Input points         —         1 point         —           Rated input voltage         —         24VDC (+20%/-15%, ripple ratio: within 5%)         —           Rated input current         —         6mA         —           ON voltage/ON current         —         13V or more, 3mA or more         —           OFF voltage/OFF current         —         8V or less, 1.6mA or less         —           Input resistance         —         3.9kΩ         —           Response         OFF→ON         —         40µs         —           *1: Maximum resolution in users range settings.	External p	power supply									Inrush	currer	nt: 4.3A, 1000µs	or shorter
5VDC internal current consumption         0.52A         0.76A         0.16A           Weight         0.19kg         0.20kg         0.20kg           External trigger input         Input points         —         1 point         —           Rated input voltage         —         (+20%/-15%, ripple ratio: within 5%)         —           External trigger input         —         6mA         —           ON voltage/ON current         —         13V or more, 3mA or more         —           OFF voltage/OFF current         —         8V or less, 1.6mA or less         —           Input resistance         —         3.9kΩ         —           Response         OFF→ON         —         40µs         —           *1: Maximum resolution in users range settings.	_		<u> </u>				_					Current	t consumption: (	D.18A
Neight   0.19kg   0.20kg   0.20kg   0.20kg					0.504		Т	18-pc		CK			0.104	
Input points		nai current consumption	$\vdash$				$\vdash$							
Rated input voltage	vveignt	Input points												
Rated input current   —   6mA   —								/.000//	24VDC	Maria FOA				
External trigger input         ON voltage/ON current         —         13V or more, 3mA or more         —           OFF voltage/OFF current         —         8V or less, 1.6mA or less         —           Input resistance         —         3.9kΩ         —           Response time         OFF→ON ON→OFF         —         40μs         —           *1: Maximum resolution in users range settings.         —         *         —								(+20%/-15%		itnin 5%)				
trigger input         current         BV or less, 1.6mA or less         —           OF voltage/OFF current         —         8V or less, 1.6mA or less         —           Input resistance         —         3.9kΩ         —           Response time         OFF→ON         —         40μs         —           *1: Maximum resolution in users range settings.         —         40μs         —		ON voltage/ON			_			13V or		nore			_	
Response time         OFF→ON ON→OFF         —         40μs         —           *1: Maximum resolution in users range settings.         —         40μs         —					_			8v or I		USS			_	
time         ON→OFF         —         40μs         —           *1: Maximum resolution in users range settings.		<u> </u>	$\vdash$				$\vdash$							
*1: Maximum resolution in users range settings.					_								_	
*? Accuracy for the maximum digital output value. Except when influenced by noise		um resolution in users					_							

<sup>\*2:</sup> Accuracy for the maximum digital output value. Except when influenced by noise.

<sup>\*3:</sup> Accuracy for the maximum analog output value. Except when influenced by noise. Power on (warm-up) the module for 30 minutes to satisfy the accuracy shown in the table.

<sup>\*4:</sup> Accuracy under the ambient temperature when the offset/gain setting is performed.

<sup>\*5:</sup> Accuracy when the temperature changes 1°C.

Example: Accuracy when the temperature changes from 25°C to 30°C

0.05% + 0.00401%/°C (temperature coefficient) × 5°C (temperature change) = 0.070%

<sup>\*6:</sup> The default value is 80µs/channel.

<sup>\*7:</sup> The logging function can be used only in the middle speed (80µs/channel) or low speed (1ms/channel).

<sup>\*8:</sup> The flow amount integration function can be used only in the low speed (1ms/channel).

<sup>\*9:</sup> Maximum instantaneous current value that will not cause destruction of the internal components. The maximum constant input current value is 24mA.

### **Temperature Control Modules**

■ L60TCTT4
Thermocouple

Temperature input points 4 points (channels)	Standard control	Heating-cooling control	
Self-tuning function	Peak current suppression function	Simultaneous temperature rise function	Selectable sampling cycle
Temperature input mode	Temperature control mode		
GX Works2 Error history			



■ L60TCTT4BW
Thermocouple

Temperature input points 4 points (channels)	Standard control	Heating-cooling control	
Self-tuning function	Peak current suppression function	Simultaneous temperature rise function	Selectable sampling cycle
Temperature input mode	Temperature control mode	Heater disconnection detection function	
GX Works2 Error history			



■ L60TCRT4
Platinum RTD

Temperature input points 4 points (channels)	Standard control	Heating-cooling control	
Self-tuning function	Peak current suppression function	Simultaneous temperature rise function	Selectable sampling cycle
Temperature input mode	Temperature control mode		
GX Works2 Error history			



■ L60TCRT4BW Platinum RTD

Temperature input points 4 points (channels)	Standard control	Heating-cooling control	
Self-tuning function	Peak current suppression function	Simultaneous temperature rise function	Selectable sampling cycle
Temperature input mode	Temperature control mode	Heater disconnection detection function	
GX Works2 Error history			



CPL



### Highly stable temperature control

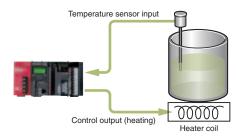
[Standard control/heating and cooling control]

Prevent overheating and overcooling in devices that require a high level of temperature stability, such as in an extrusion molding machine.

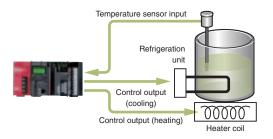
The following control methods can be selected according to the target device.

- Standard control (heating or cooling)
- Heating/cooling control (heating and cooling)
- Mix control (combination of standard control and heating-cooling control)

# ■ Example: Standard control (heating only) The temperature of the object is controlled by adjusting the heater output based on the PID calculations resulting from the temperature sensor input.



# ■ Example: Heating-cooling control (heating and cooling elements controlled simultaneously) Heating is performed when the control object's temperature is lower than the target temperature, and cooling is performed when it is hotter or the humidity needs to be reduced.



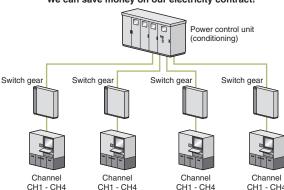
### Reduce running costs by taking advantage of the energy-saving effect

[ Peak current control function ]

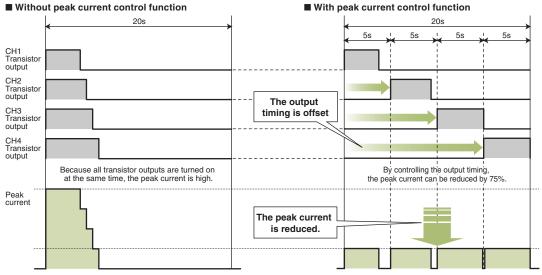
The peak current control function reduces the peak current by automatically changing the upper limit output limiter value for each channel, while dividing the transistor output timing 1. The energy conserved by reducing the peak current, such as a reduction in system power capacity and reduction in contracted power, can help to reduce running costs.

\*1. The timing can be split between two to four outputs.

The maximum power supply capacity requirement is lowered. We can save money on our electricity contract!



When two or more loads are being controlled, the peak current can be minimized by spreading the total load out over time.



### **Ensures uniform temperature control**

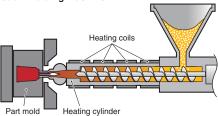
[ Simultaneous temperature rise function ]

Ensures uniform temperature control by synchronizing the temperature arrival times from multiple loops.

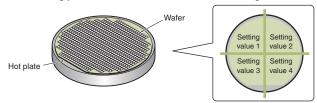
Perform a uniform temperature rise using two or more control loops without going over temperature or resulting in unexpected thermal expansion.

A "no idling" format increases energy efficiency and reduces running costs.

■ Example: Temperature control of injection molding machine

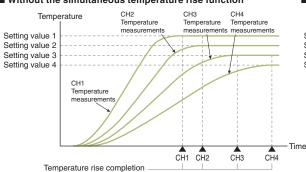


### ■ Example: Wafer heating process for semiconductor manufacturing

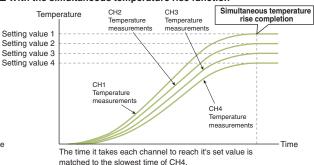


### The running costs is reduced!

### ■ Without the simultaneous temperature rise function



### ■ With the simultaneous temperature rise function

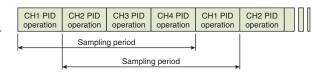


Using this function, it is possible to coordinate the control of two or more loops to reach their target values (SV) at the same time. Control the simultaneous rise in temperature of separate loops by setting a channel group (Max. 2 groups). This is an effective way to control applications where differing target temperature arrival times can result in undesirable temperature differentials.

### Support a range of system requirements

[ Sampling cycle change function ]

Choose a sampling cycle of 250 ms/4 channels or 500 ms/4 channels.

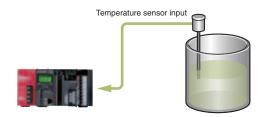


Sampling period: The time it takes to execute a PID operation for all channels (CHn) before beginning the PID operation of the present channel (CHn) again is called a sampling period.

### Temperature input mode

This function allows the temperature control module to be used as a standard temperature input module.

Using the switch setting, it is possible to easily change the input mode.



MELSEG L series

■ Specifications

	Ite	em	L60TCTT4	L60TCTT4BW	L60TCRT4	L60TCRT4BW	
Control outpo	ut			Transist	or output		
Number of te	emperature input points			4 poin	its (ch)		
Applicable te	emperature sensors		Therm	ocouple	Resistive th	nermal device	
		Ambient temperature: 25 ± 5°C		Full scale	× (±0.3%)		
	Indication accuracy	Ambient temperature: 0 to 55°C		Full scale	× (±0.7%)		
		Temperature process value (PV):	Within	± 1.0°C			
Accuracy*1	Cold junction temperature compensation accuracy:	-100°C or more Temperature process value (PV):					
	(ambient temperature:	-150 to -100°C	Within	± 2.0°C	_		
	0 to 55°C)	Temperature process value (PV): -200 to -150°C	Within	± 3.0°C			
Sampling cyc	cle				channels channels		
Control outp	ut cvcle			0.5 to			
Input impeda	<u> </u>				ΜΩ		
Input filter				0 to 100s (0: Ir			
	ection value setting			· · · · · · · · · · · · · · · · · · ·	50.00%		
	sensor input disconnection				processing		
	control method			PID ON/OFF pulse of			
romperature	, control metriou	PID constants setting			y auto tuning.		
		Proportional band (P)		0.0 to 1000.0% (0: 7			
PID constant	ts range						
		Integral time (I)		0 to 3600s (set 0 for P			
0		Derivative time (D)			control and PI control.)		
	V) setting range		Within the temperature range set in the thermocouple/platinum resistance thermometer to be used				
Dead band s	setting range		0.1 to 10.0%				
		Output signal		ON/OF			
		Rated load voltage	10 to 30VDC				
		Max. load current	0.1A/point, 0.4A/common				
Transistor ou	utput	Max. inrush current	0.4A 10ms				
		Leakage current at OFF		0.1mA	or less		
		Max. voltage drop at ON		1.0VDC (TYP) at 0.1A	2.5VDC (MAX) at 0.1A		
		Response time	OFF→ON: 2ms or less, ON→OFF: 2ms or less				
Number of a	ccesses to non-volatile mer	mory	Max. 10 <sup>12</sup> times				
Insulation me	ethod		Between input terminal and programmable controller power supply: Transformer insulation Between input channels: Transformer insulation				
Dielectric wit	thstand voltage		Between input	terminal and programmable of Between input channel	controller power supply: 500\ s: 500VAC for 1 minute	/AC for 1 minute	
Insulation res	sistance		Between input t	erminal and programmable co Between input channels:	ntroller power supply: 500VI : 500VDC 20MΩ or more	DC 20MΩ or more	
Heater disco detection spe		Current sensor	-	* CTL-12-S36-8 (0.0 to 100.0A)*2 *3 * CTL-12-S36-10 (0.0 to 100.0A)*2 * CTL-12-S56-10 (0.0 to 100.0A)*2 * CTL-6-P (0.00 to 20.00A)*2 *3 * CTL-6-P-H (0.00 to 20.00A)*2	_	• CTL-12-S36-8 (0.0 to 100.0A)*2 *3 • CTL-12-S36-10 (0.0 to 100.0A)*2 • CTL-12-S56-10 (0.0 to 100.0A)*2 • CTL-6-P (0.00 to 20.00A)*2 *3 • CTL-6-P-H (0.00 to 20.00A)*2	
		Input accuracy		Full scale × (±1.0%)	1	Full scale × (±1.0%)	
		Number of alert delay		3 to 255		3 to 255	
Maximum nu	umber of modules specificat	ion	Counts as 1 module	Counts as 2 modules	Counts as 1 module	Counts as 2 modules	
	ccupied I/O points			<del> </del>	ent: Intelligent 16 points)		
External con			18-point terminal block	18-point terminal block × 2	18-point terminal block	18-point terminal block ×	
	al current consumption		0.30A	0.33A	0.31A	0.35A	
Weight		ethod (only when it is not affected by noise	0.18kg	0.33kg	0.18kg	0.33kg	

\*\*1: Calculate the accuracy in the following method (only when it is not affected by noise).

\*\*Accuracy (°C) = full scale × indication accuracy + cold junction temperature compensation accuracy

EX. Accuracy at the input range of 38 (-200.0 to 400.0 °C), the operating ambient temperature of 35 °C, and the temperature process value (PV) of 300 °C

(Full scale) × (indication accuracy) + cold junction temperature compensation accuracy

= (400.0 °C - (-200.0 °C)) × (±0.007) + (±1.0 °C)

= ± 5.2 °C

\*\*2: U.R.D.Co., LTD. For more information, visit http://www.u-rd.com/

\*\*3: The CTL-12-S36-8 and CTL-6-P can be used although they have been discontinued.

### ■ Control mode

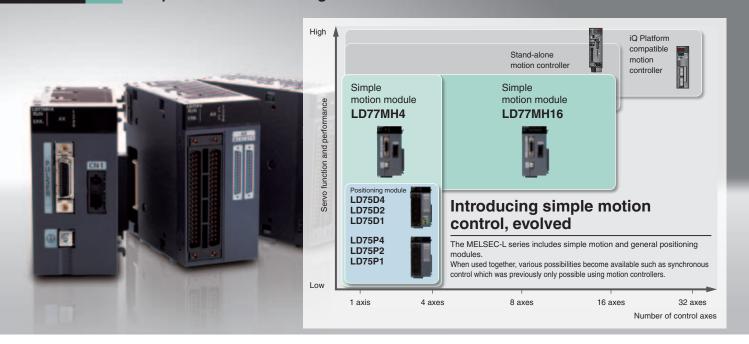
= Control Illoac		
Control mode	Contents	Number of controllable loops
Standard control	Performs the standard control of four channels.	Standard control 4 loops
Heating-cooling control (normal mode)	Performs the heating-cooling control. CH3 and CH4 cannot be used.	Heating-cooling control 2 loops
Heating-cooling control (expanded mode)	Performs the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Heating-cooling control 4 loops
Mix control (normal mode)		Standard control 2 loops Heating-cooling control 1 loop
		Standard control 2 loops Heating-cooling control 2 loops

### Control for each channel is as follows.

Channel	Standard control	Heating-coo	oling control	Mix c	ontrol
Charmer	Standard Control	Normal mode	Expanded mode	Normal mode	Expanded mode
CH1	Standard control	Heating-cooling control	Heating-cooling control	Heating-cooling control	Heating-cooling control
CH2	Standard control	Heating-cooling control	Heating-cooling control	*1	Heating-cooling control*2
CH3	Standard control	*1	Heating-cooling control*2	Standard control	Standard control
CH4	Standard control	*1	Heating-cooling control*2	Standard control	Standard control

<sup>\*1:</sup> Only temperature measurement using a temperature input terminal can be performed.
\*2: Heating-cooling control is performed using an output module in the system.

### **Simple Motion / Positioning**



### **Simple Motion Modules**

■ LD77MH4

Number of control axes 4 axes	Connection system SSCNET III -compatible	Positioning data 600 data/axis	
Positioning control function	Speed/torque control function	4-axis interpolation (Linear interpolation)	2-axis interpolation (Circular interpolation)
Synchronous control function <b>External encoder</b>	Synchronous control function Cam	Synchronous control function  Phase compensation	
Manual pulse generator operation function	OPR control function	4	SSCNETIII SERVO SYSTEM CONTROLLER NETWORK



■ LD77MH16

Number of control axes 16 axes	Connection system SSCNET III -compatible	Positioning data 600 data/axis	
Positioning control function	Speed/torque control function	4-axis interpolation (Linear interpolation)	2-axis interpolation (Circular interpolation)
Synchronous control function  External encoder	Synchronous control function Cam	Synchronous control function  Phase compensation	
Manual pulse generator operation function	OPR control function	4	SSCNETIII SERVO SYSTEM CONTROLLER NETWORK





### Countless applications are possible

A variety of control types including positioning control, speed control, torque control, cam control and synchronous control can be implemented easily with simple parameter settings and a sequence program.

### [ Positioning control ]

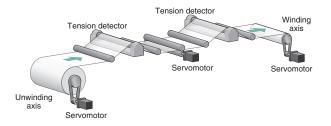
- Support for a multitude of applications thanks to a wide variety of control formats including linear interpolation control (up to 4 axes), 2-axis circular interpolation control, fixed feed control and continuous orbit control.
- Use a sequence program to set the positioning address, speed, etc. for easy automatic operation.
- Quickly implement powerful auxiliary functions such as step operation, target position change, M codes, and the skip function.

### [ Speed control and torque control ]

- Tension control applications such as winding and rewinding are supported.
- Switch from positioning control, to speed and torque control, and back to positioning control.
   Because the present location is tracked even in speed and

Because the present location is tracked even in speed and torque control mode, it is possible to maintain the current absolute position when returning to positioning control.

# XY table Sealant application 2-axis linear interpolation 3-axis linear interpolation Continuous orbit control Continuous orbit control Continuous orbit control Continuous orbit control Linear/circular interpolation

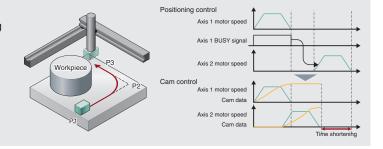


### [ Cam control ]

• Cam control may be used alone or combined with synchronous control.

### Example application for cam control:

To create a movement path around a workpiece using positioning control, axis 2 waits for axis 1 to complete the move from P1 to P2 before it begins moving from P2 to P3. By using cam control, axis 2 does not need to wait for axis 1 to complete its movement and the in position time can be shortened.



### Many functions in a compact design

[ Use a synchronous encoder with synchronous control ]

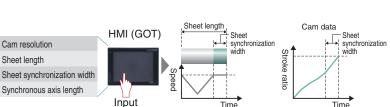
- Input pulses from a synchronous encoder can be used to perform synchronous control and cam control.
- The incremental synchronous encoder can be used by using the LD77MH built-in interface. An option unit is not required.
- To Further improve the synchronization accuracy, the phase compensation function, designed to compensate for synchronous encoder delays, can be used.

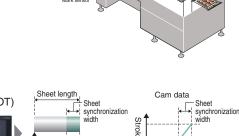
### [ Standard mark detection function ]

 The built-in mark detection signal interface allows these units to be used in packaging systems for example, without additional option modules.

### [ Automatic cam data generation for rotary cutter ]

 Complicated cam data for rotary cutters can be automatically generated just by specifying a few parameters like the sheet length and synchronization width.

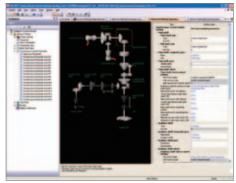




### Perfect synchronous control is easy to achieve

Replace mechanical gears, shafts, speed change gears, cams, etc. and generate synchronous control operations using software.

- Complicated programs are unnecessary for synchronous control because it can be implemented easily using parameter settings.
- Start and stop synchronous control for each axis.
   Use the synchronous control axis and positioning control axis together.
- Convey the travel value of main shaft to the output axis via the clutch.

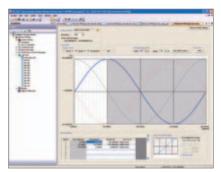


Synchronous Control Parameter Settings

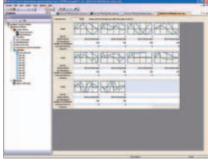
### Cam control made simple

Create cam data patterns easily.

- Create cam profiles unrestricted by existing concepts of electronic cam control.
- Change the acceleration, speed, stroke, and jerk while simultaneously seeing how it effects the profile.
- Easily check created cam data by viewing them as thumbnails.
- Import and export cam data in CSV format.



Cam Data



Cam Data List

### Simplified debugging and commissioning

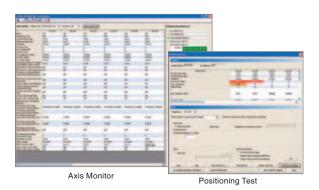
[ Digital oscilloscope function ]

- Collection of data from the Simple Motion Module is synchronized with the operation cycle and waveform displays to facilitate an efficient start up.
- The assistant function explains each step.
- Use the purpose-based probe setting to easily set frequentlyviewed data.
- Sample 16CH word and 16CH bit data and display 8CH words and 8CH bits in real time.

Digital Oscilloscope

[ Monitor and test functions ]

- Complete the system installation and perform operational checks easily using powerful monitor and test functions.
- Select items to be displayed on the monitor using a wealth of information monitoring options.
- The test function can be used to check basic operations without a sequence program.



MELSEG L series

■ Specifica							
Number of contr	Ite	m	LD77MH4 4 axes	LD77MH16[NEW] 16 axes			
Operation cycle	UI axes		0.88ms	0.88ms/1.77ms*1			
Interpolation fun	ction		Linear interpolation(Up to 4 axes), Circular interpolation				
Control system			PTP (Point To Point) control, path control (both linear and ar torque control, speed-position switching control, position	** •			
Acceleration/ded	eleration p	process	Trapezoidal acceleration/deceleration, S-pattern acce				
Compensation f	unction		Backlash compensation, Electronic gear, Near	pass function			
Synchronous co	ntrol		External encoder, Cam, Phase Compensation, Cam go	enerated automatically			
Control unit			mm, inch, degree, pulse	-0			
Positioning data Backup			600 data (positioning data No. 1 to 600)/ axis (Can be set with GX Work:  Parameters, positioning data, and block start data can be saved o				
OPR control	Machine (	OPR control	Near-point dog method, Count method 1), Count method 2), Data set met				
OPR CONTROL	Sub funct						
Linear control			OPR retry, OP shift  1-axis linear control, 2-axis linear interpolation control, 3-axis linear interpolation control  (Connection 4-axis linear interpolation control)				
	Position	Fixed-feed control	(Composite speed, Reference axis spaced, 1-axis fixed-feed control, 2-axis fixed-feed control, 3-axis fixed-feed				
	control	2-axis circular					
		interpolation control	sub point designation, center point desi	gnation			
Position control	Speed co		1-axis speed control, 2-axis speed control, 3-axis speed co	ontrol, 4-axis speed control			
1 OSITION CONTROL		sition switching control	INC mode, ABS mode				
	Position-s	Current value changing	INC mode	n a new current value using the start No.			
	Other	Current value changing  NOP instruction	Changing to a new current value using the positioning data , Changing to Provided	o a new current value using the start ino.			
	control	JUMP instruction	Unconditional JUMP, Conditional JU	IMP			
		LOOP,LEND	Provided				
High-level positi			Block start, Condition start, Wait start, Simultaneous	start, Repeated start			
	JOG oper		Provided				
Manual control	Inching of	peration	Provided				
	Manual p	ulse generator operation	Possible to connect 1 module (Increm Unit magnification (1 to 10000time				
Expansion control	· .	rque control	Speed control without positioning loops, Torque control without positioning loops				
Absolute positio		,	Connect a battery to the servo amplifier to ensu				
Synchronous en	Internal in		Up to 4 channel (total of internal interface and inte 1channel (Incremental)	rrace via the CPU)			
		nit function	Speed limit value, JOG speed limit v	alue			
	<u> </u>	nit function	Torque limit value_same setting, torque limit value				
Functions that limit control	<u> </u>	op function	valid/invalid setting				
IIIIII COITIIOI	Software	stroke limit function	Movable range check with current feed value, movable range check with machine feed value				
		stroke limit function	Provided				
		ange function	Provided				
Functions that	Override t	ion/deceleration time	Provided				
change control	change fu		Provided				
details		ange function	Provided				
	Target po	sition change function	Target position address and target position speed	d are changeable			
		utput function	Provided				
Other functions	Step func		Deceleration unit step, Data No. unit				
	Skip funct Teaching		Via sequence CPU, Via external comma Provided	na signal			
	reaching	lunction	Mark detection mode (Continuous Detection mode, Specified Number	of Detections made. Ring Ruffer made)			
Mark detection	Mark dete	ection signal	4points				
function		ection setting	4	16			
Optional data m			4points/axis				
Master-slave op			Provided				
Amplifier-less of			Provided  bit data :8channels, word data: 4channels bit data	- 11Cabannala ward data: 1 Cabannala *2			
Digital oscillosco	pe iuriciio	П	,	a :16channels, word data: 16channels *2			
			1-axis linear control	_			
			1-axis speed control 2-axis linear interpolation control (Composite speed)	_			
			2-axis linear interpolation control (Composite speed)	_			
			2-axis circular interpolation control				
Starting time*3			2-axis speed control	0.88ms			
			3-axis linear interpolation control (Composite speed)				
			3-axis linear interpolation control (Reference axis speed	)			
			3-axis speed control				
			4-axis linear interpolation control				
			4-axis speed control				
		nce between drive units	50m				
		les specification	Counts as 2 modules				
Number of occu			32 points (I/O assignment: Intelligent 32				
Servo amplifier			SSCNET III-compatible (50Mbps	0.70A			
5VDC internal c	urrent cons	sumption	0.55A	U./UA			
Weight			0.22kg				

<sup>\*1:</sup> Default value is 1.77 ms. If necessary, check the operation time and change to 0.88 ms.
\*2: 8CH word data and 8CH bit data can be displayed in real time.
\*3: The starting time varies with conditions. For details, refer to the manual.

### **Positioning Modules**

### ■ LD75P1 Open collector

Number of control axes  1 axis	Max. output pulse 200kpulse/s
Positioning data 600 data/axis	Max. connection distance 2m
Positioning control function	Speed control function



### ■ LD75D1 Differential driver

Number of control axes  1 axis	Max. output pulse 4Mpulse/s	
Positioning data 600 data/axis	Max. connection distance 10m	
Positioning control function	Speed control function	



### ■ LD75P2 Open collector

Number of control axes 2 axes	Max. output pulse 200kpulse/s
Positioning data 600 data/axis	Max. connection distance 2m
Positioning control function	Speed control function
OPR control function	GX Works2 Error history



### ■ LD75D2 Differential driver

Number of control axes 2 axes	Max. output pulse 4Mpulse/s
Positioning data 600 data/axis	Max. connection distance 10m
Positioning control function	Speed control function



### ■ LD75P4 Open collector

Number of control axes 4 axes	Max. output pulse 200kpulse/s
Positioning data 600 data/axis	Max. connection distance 2m
Positioning control function	Speed control function



### ■ LD75D4 Differential driver

Number of control axes 4 axes	Max. output pulse 4Mpulse/s
Positioning data 600 data/axis	Max. connection distance 10m
Positioning control	Speed control
function	function



LD75D1 LD75D2 LD75D4

### High-speed control of high resolution devices

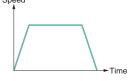
Control high resolution devices such as linear servos and direct drive motors without compromising speed.

	Max. output pulse	Max. connection distance
LD75D1, LD75D2, LD75D4	4Mpulse/s	10m
LD75P1, LD75P2, LD75P4	200kpulse/s	2m

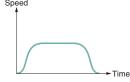
### Reduce machine vibration by using the optimal acceleration/deceleration system

Chosen between trapezoidal acceleration/deceleration or S-curve acceleration/deceleration in accordance with machine characteristics such as the amount of load or vibration characteristics.

\*S-curve acceleration/deceleration cannot be used with stepping motors.



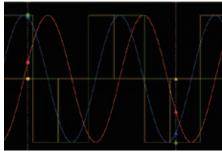
Trapezoidal acceleration/deceleration Is a system in which the acceleration and deceleration changes linearly based on acceleration/deceleration time and the speed-limit value set by users.



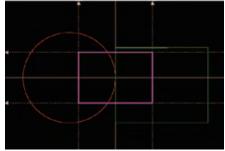
S-curve acceleration/deceleration Is a system in which acceleration/ deceleration changes gradually based on acceleration/deceleration time, speed-limit, and the S-curve ration value (1 to 100%).

### Visualize positioning module buffer data

Monitor online or save and review command data such as speed, simultaneous start, and dual axis interpolation routines using customizable graphs.



Trace function - waveform display



Trace function - location trace display

### Configure modules without the need to reference a manual

GX Works2 contains support tools to help configure intelligent function modules. All of the required information to configure and revise complicated parameter settings is included so it is not necessary to reference a manual.

Set according to the machine and applicable motor when system is started up.
(This parameter become valid when the PLC READY signal [Y0] turns from OFF to ON)

Configure modules easily and with no manual thanks to the included settings information.



# ■ Specifications [ Open collector ]

		Item	LD75P1	LD75P2	LD75P4		
Number o	f control axe		1 axis	2 axes	4 axes		
Interpolation function				2-axis linear interpolation	2-axis/3-axis/4-axis linear interpolation		
			<u> </u>	2-axis circular interpolation	2-axis circular interpolation		
			PTP (Point To Point) control,				
Control sy	/stem		path control (both linear and arc can be set),				
Some System			speed control, speed-position switching control,				
			position-speed switching control				
control un	nm, inch, degree, pulse						
ositionin	g data	600 data (positioning data No.1 to 600)/axis (Can be set with peripheral device or sequence program.)					
Backup			,	, and block start data can be saved on fla			
аскир		PTP*1 control	r arameters, positioning date	INC system, ABS system	311 HOW (battery-less backup)		
	Positioning	Speed-position switching control		INC system, ABS system*2			
	control	Position-speed switching control		INC system			
	system	Path control	INC system, ABS system				
		T day control		-214748364.8 to 214748364.7 (μm)			
				-21474.83648 to 21474.83647 (inch)			
		In ABS system		0 to 359.99999 (degree)			
				-2147483648 to 2147483647 (pulse)			
				-214748364.8 to 214748364.7 (µm)			
	D iti i	In INIC avatam		-21474.83648 to 21474.83647 (inch)			
	Positioning control	In INC system		-21474.83648 to 21474.83647 (degree)			
				-2147483648 to 2147483647 (pulse)			
ositioning	range	In speed-position switching		0 to 214748364.7 (µm)			
control		control (INC mode)/		0 to 21474.83647 (inch)			
		position-speed switching control		0 to 21474.83647 (degree)			
			0 to 2147483647 (pulse)				
		In speed-position switching control (ABS mode)*2	0 to 359.99999 (degree)				
				0.01 to 20000000.00 (mm/min)			
	Speed command		0.001 to 2000000.000 (inch/min)				
			0.001 to 2000000.000 (degree/min)				
			1 to 4000000 (pulse/s)				
	Acceleration	/deceleration system selection	Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration		ion/deceleration		
	Acceleration	n/deceleration time	F	1 to 8388608ms	de este valiera dise		
	0 11 1		Four patterns ca	n be set for each of acceleration time and	deceleration time		
PR meth		p deceleration time		1 to 8388608ms			
rn IIIeli	iou			6 types			
			1-axis linear contro		1.5ms		
			1-axis speed contr		1.5ms		
				olation control (Composite speed)	1.5ms		
				ol (Reference axis speed)	1.5ms		
			2-axis circular inte		2.0ms		
Starting time*3			2-axis speed contr		1.5ms		
tarting til	ű			olation control (Composite speed)	1.7ms		
starting ti			2 avia linear intern	olation control (Reference axis speed)	1.7ms		
Starting til			<u> </u>				
starting ti			3-axis speed contr		1.7ms		
tarting ti			3-axis speed contr 4-axis linear interp	olation control	1.8ms		
tarting ti			3-axis speed contr	olation control			
	put method		3-axis speed contr 4-axis linear interp	olation control	1.8ms		
ulse outp	put method output pulse	3	3-axis speed contr 4-axis linear interp	olation control	1.8ms		
ulse outp	output pulse	) distance between drive units	3-axis speed contr 4-axis linear interp	olation control ol Open collector output	1.8ms		
ulse outp laximum laximum	output pulse		3-axis speed contr 4-axis linear interp	olation control ol Open collector output 200k pulse/s	1.8ms		
Pulse outp Maximum Maximum Maximum	output pulse	distance between drive units nodules specification	3-axis speed contr 4-axis linear interp 4-axis speed contr	olation control ol Open collector output 200k pulse/s 2m	1.8ms 1.8ms		
Pulse outp Maximum Maximum Maximum Maximum Jumber o	output pulse connection of number of m	distance between drive units nodules specification	3-axis speed contr 4-axis linear interp 4-axis speed contr	Olation control  Open collector output  200k pulse/s  2m  Counts as 2 modules	1.8ms 1.8ms		
Pulse outp Maximum Maximum Maximum Vumber o External c	output pulse connection of number of m of occupied I/O	distance between drive units nodules specification	3-axis speed contr 4-axis linear interp 4-axis speed contr	Open collector output  200k pulse/s 2m  Counts as 2 modules 2 points (I/O assignment: Intelligent 32 poi	1.8ms 1.8ms		

<sup>\*1:</sup> The abbreviation for Point To Point, referring to position control.

\*2: In speed-position switching control (ABS mode), "degree" is the only control unit available.

\*3: Starting times may vary depending on conditions. For details, refer to the manual.

CPU

MELSEG L series

# ■ Specifications [ Differential driver ]

		Item	LD75D1	LD75D2	LD75D4		
Number of control axes		S	1 axis	2 axes	4 axes		
Interpolation function			_	2-axis linear interpolation	2-axis/3-axis/4-axis linear interpolatio		
				2-axis circular interpolation	2-axis circular interpolation		
Control system			PTP (Point To Point) control,				
			path control (both linear and arc can be set),				
			speed control, speed-position switching control, position-speed switching control				
ontrol ur	nit			mm, inch, degree, pulse			
				600 data (positioning data No.1 to 600)/ax	ris		
ositionin	itioning data (Can be set with peripheral device or sequence program.)						
ackup				a, and block start data can be saved on fla			
		PTP*1 control	3	INC system, ABS system	, , , , , , , , , , , , , , , , , , , ,		
	Positioning	Speed-position switching control		INC system, ABS system*2			
	control	Position-speed switching control		INC system			
	system	Path control		INC system, ABS system			
		r aar como	-214748364.8 to 214748364.7 (μm)				
				-21474.83648 to 21474.83647 (inch)			
		In ABS system		0 to 359.99999 (degree)			
				-2147483648 to 2147483647 (pulse)			
				-214748364.8 to 214748364.7 (μm)			
	D Minutes	In INC system		-21474.83648 to 21474.83647 (inch)			
	Positioning			-21474.83648 to 21474.83647 (degree)			
	control range			-2147483648 to 2147483647 (pulse)			
Positioning control	lange	In speed-position switching		0 to 214748364.7 (µm)			
		control (INC mode)/		0 to 21474.83647 (inch)			
		position-speed switching control		0 to 21474.83647 (degree)			
				0 to 2147483647 (pulse)			
		In speed-position switching control (ABS mode)*2	0 to 359.99999 (degree)	9.99999 (degree)			
	Speed command		0.01 to 20000000.00 (mm/min)				
			0.001 to 2000000.000 (inch/min)				
			0.001 to 2000000.000 (degree/min)				
	Acceleration/deceleration system selection		1 to 4000000 (pulse/s)				
	Acceleration	/deceleration system selection	Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration				
	Acceleration	n/deceleration time	1 to 8388608ms  Four patterns can be set for each of acceleration time and deceleration time				
	Suddon etor	deceleration time	i oui patterns ca	1 to 8388608ms	deceleration time		
PR meth		deceleration time		6 types			
TTTTTE	100						
			1-axis linear contro		1.5ms		
			1-axis speed contr		1.5ms		
				polation control (Composite speed)	1.5ms		
				ol (Reference axis speed)	1.5ms		
			2-axis circular inte	-	2.0ms		
tarting ti	me*3		2-axis speed contr		1.5ms		
				olation control (Composite speed)	1.7ms		
			-	olation control (Reference axis speed)	1.7ms		
			3-axis speed contr		1.7ms		
			4-axis linear interp		1.8ms		
			4-axis speed contr	rol	1.8ms		
ulse out	out method			Differential driver output			
	output pulse			4M pulse/s			
	<u>'</u>			10m			
Maximum connection distance between drive units				Counts as 2 modules			
	Maximum number of modules specification  Number of occupied I/O points		32		nts)		
laximum	f occupied I/0		32 points (I/O assignment: Intelligent 32 points)				
laximum umber o		o pointo		onnector	40-pin connector ×2		
laximum umber o xternal c	onnections			onnector 0.62A	40-pin connector ×2 0.76A		

<sup>\*1:</sup> The abbreviation for Point To Point, referring to position control.
\*2: In speed-position switching control (ABS mode), "degree" is the only control unit available.
\*3: Starting times may vary depending on conditions. For details, refer to the manual.

### **High-Speed Counter Modules**

■ LD62 DC input

Number of channels <b>2ch</b>	5/12/24vdc input	Max. counting speed 200kpulse/s	
Linear counter function	Ring counter function	Coincidence output function	Preset function
Disable count function	Latch counter function	Sampling counter function	Periodic pulse counter function



■ LD62D Differential input

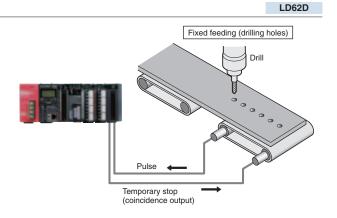
Number of channels <b>2ch</b>	Differential driver input	Max. counting speed 500kpulse/s	
Linear counter function	Ring counter function	Coincidence output function	Preset function
Disable count function	Latch counter function	Sampling counter function	Periodic pulse counter function



### High-speed pulse measurement of 500kpulse/s

It is easy to achieve accurate measurement of high speed pulses using the LD62D.

Due to the wide range of supported pulse speeds, the module is capable of supporting many different applications including various conveyor systems, work piece length measurement, and processing speed measurement.



### Configure modules without the need to reference a manual

LD62D

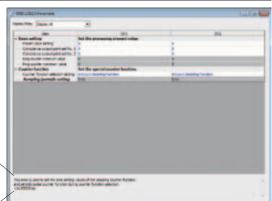
LD62

GX Works2 contains support tools to help configure intelligent function modules. All of the required information to configure and revise complicated parameter settings is included so it is not necessary to reference a manual.

This area is used to set the time setting values of the sampling counter function and periodic pulse counter function during counter function selection.

1 to 65535 ms

Configure modules easily and with no manual thanks to the included settings information.



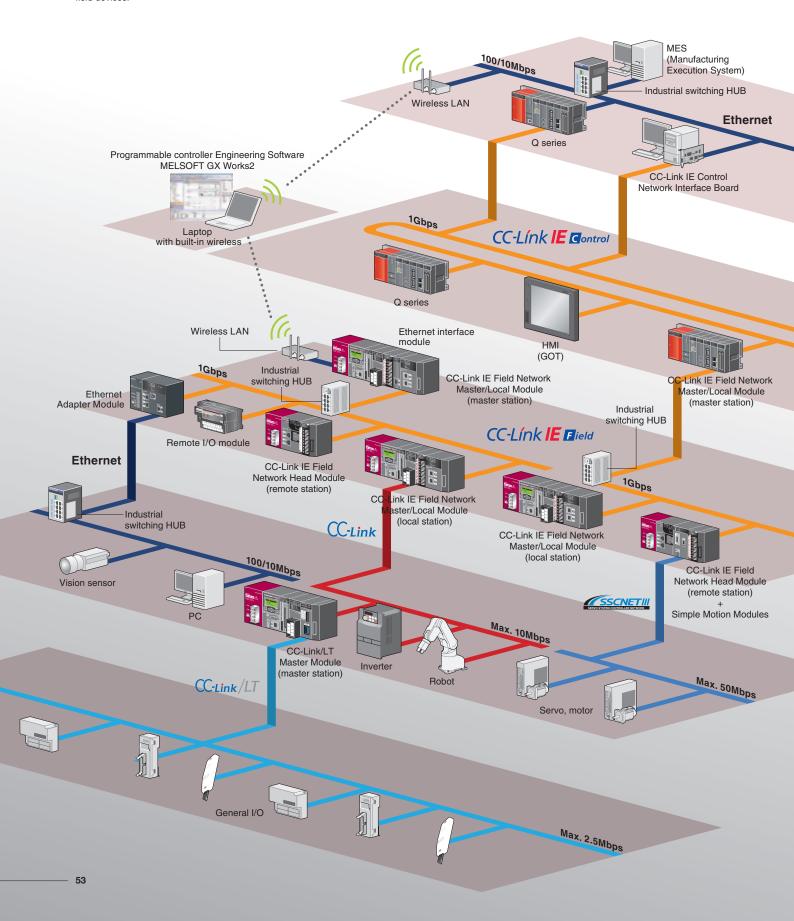
MELSEG L series

Item			LD62 [DC input]	LD62D [Differential input]		
Number of channels			2	2ch		
Counting speed switch setting			10kpulse/s, 100kpulse/s, 200kpulse/s 10kpulse/s, 100kpulse/s, 200kpulse/s, 500kpulse/s			
Count input	Phase		1-phase input (multiple of 1/2), CW/CCW, 2-phase input (multiple of 1/2/4)			
signal	Signal level (A, B)		5/12/24VDC 2 to 5mA	EIA Standard RS-422-A differential type line driver level (Equivalent with AM26LS31 (manufactured by Texas Instruments Japan Limited))		
	Maximum counting speed*1		200kpulse/s	500kpulse/s		
	Counting range		-2147483648	to 2147483647		
	Туре		UP/DOWN preset counter	r and ring counter functions		
			10kpulse/s 50µs	10kpulse/s 50μs		
	Minimum count pulse wid	th	100kpulse/s 5μs	100kpulse/s 5µs		
Counter	(Duty ratio 50%)		200kpulse/s 2.5µs	200kpulse/s 2.5μs		
Counter				500kpulse/s 1μs		
			10kpulse/s 25µs	10kpulse/s 25µs		
	Minimum phase differenti	al for 2-phase	100kpulse/s 2.5µs	100kpulse/s 2.5μs		
	input	·	200kpulse/s 1.25μs	200kpulse/s 1.25μs		
				500kpulse/s 0.5μs		
	Comparison range		Binary with 32-bit code (-2147483648 to 2147483647)			
Coincidence output				: Count value		
output	Comparison result			Count value		
			Set value >	Count value		
	Preset		5/12/24VDC 2 to 5mA	5/12/24VDC 2 to 5mA (Differential type line drivers		
External	Function start	055 . 011		conforming to EIA standard RS-422-A are also applicable.)		
input	Minimum input	OFF to ON		start: 0.5ms		
	response time Coincidence output	ON to OFF		start: 1ms s/channel		
Cutomal	Output voltage/current		P. C.	VDC 0.5A		
External output	Output voitage/current	OFF to ON	12 to 24	VDC 0.5A		
output	Output response time	ON to OFF	— 0.1 ms or less (rated load, resistive load)			
Maximum number of modules specification			Counts as	s 1 module		
	occupied I/O points			ent: Intelligent 16 points)		
External cor				connector		
	al current consumption		0.31A	0.36A		
Weight			0.1	13kg		
			1 1 5 1 1 2 1 1 2 1 1 2 1 1 2 1 1 1 1 1	*		

<sup>\*1:</sup> The counting speed is affected by the rising/falling pulse speed. For details, refer to the corresponding manual.

### Seamless integration of multiple networks

Today there is an increasing demand from production facilities for high speed control, effective management of data, flexible wiring, easy parameter settings, and predictive maintenance. To answer these demands, Mitsubishi Electric has teamed up with the CC-Link Partner Association to provide reliable, open-standards networks that operate seamlessly with one another. Together, These and other Mitsubishi networks allow for flexible integration at any network level. The latest addition to the CC-Link portfolio is IE Field; an Ethernet based gigabit network designed to provide cost-effective, reliable connectivity to field devices.

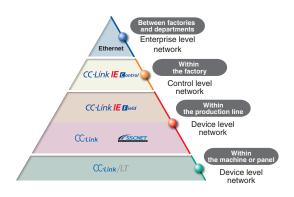




### **Seamless communication**

L series combines enterprise, control, and device level networks together through Ethernet, MELSECNET/H, and CC-Link networks to allow easy access to information, no matter where it resides on the network. It is possible to "drill down" from the top Ethernet layer, through multiple networks, and access programmable controllers using GX Works2 or other engineering tools.

In addition, many devices supporting SLMP\* such as vision sensors and RFID controllers may be connected to the CC-Link IE Field Network. \*SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.



# CC-Línk IE Control

This highly-reliable control network is designed to transfer large amounts of data at real-time speeds between programmable controllers. The CC-Link IE Control Network includes a variety of functions and allows seamless communications among other CC-Link networks.

- 1 Gbps high-speed communication
- · Maximum number of link points per network: Link relays (LB): 32768 points Link registers (LW): 131072 points Link inputs/outputs (LX, LY): 8192 points each
- · Maximum number of connected stations per network: max. 120 units
- · Maximum overall distance: 66km
- \*L series does not support the CC-Link IE Controller Network.

# CC-Línk IE Flield

This versatile field network integrates distributed control, I/O control, and motion control. Its flexible wiring design allows for star, line, star and line mixed, or ring topology to ensure the network can meet the needs of any production line or equipment layout.

- 1 Gbps high-speed communication
- · Maximum link points per network: Remote inputs/outputs (RX, RY): 16384 points Remote registers (RWw): 8192 points, (RWr): 8192 points
- · Maximum overall distance: 12km

# C-Link

CC-Link is Semiconductor Equipment and Materials International (SEMI®) certified and provides an open device level network that allows great flexibility in system design and configuration. CC-Link provides the means to link controllers to numerous devices while reducing wiring costs and adding additional benefits such as improved diagnostic capabilities.

- · Communication speeds up to 10 Mbps
- 8192 link device remote I/O points and 2048+2048 remote register
- · Connect with over 1,000 different 3rd party CC-Link compatible products
- Maximum overall distance: 100m(10mbps)

## **M** SSCNETIII

This high-speed, high-performance servo system controller network incorporates optical fiber cables. Long-distance wiring can be handled flexibly.

- Communication cycle: 0.88ms
- · Connect up to 16 axes per system

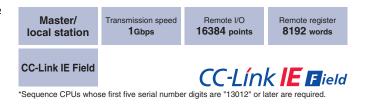
# CC-Link/LT

At the bottom of the network hierarchy, sensor level networks can reduce wiring costs inside panels between simple discrete devices such as push-buttons and sensors, CC-Link/LT accomplishes this and is fully supported by L series. Achieve tremendous flexibility and cost savings through innovative connection technology, which does not require cutting/stripping of the network cable to make connections.

- Make connections quickly and easily using dedicated connectors
- Use I/O points efficiently by using 'number of points mode' (4 points, 8 points, 16 points).
- Connect up to 1024 link points in 16-point mode.
- Up to 39m from master station(2.5Mbps)

### **CC-Link IE Field Network Master/Local Module**

### ■ LJ71GF11-T2





### Easy to configure settings

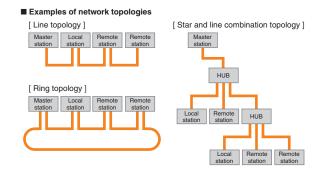
Network parameters are configured using the engineering tool, GX Works2. Only the master station needs to be configured, thereby greatly simplifying the network setup. Updating the system configuration is a breeze.

# Master station settings are all that is required! Master station Transfered CC-Link IE Gield Station #1 Station #2 Station #3

### Flexible network topology

Various network topologies are supported including star, line, star and line combination, and ring. When hubs\*1 are used, new equipment can be added and machine layouts can be changed easily.

\*1 Hubs cannot be used in a ring configuration.



Item			LJ71GF11-T2	
Transmission speed			1Gbps	
Maximum overall cable distance		Line topology	12000m (when cables are connected to 1 master station and 120 slave stations)	
(Maximum transmiss		Star topology	Depends on the system configuration	
(Maximum transmiss		Ring topology	12100m (when cables are connected to 1 master station and 120 slave stations)	
Maximum number of o	connected	Master station Local station	1 station (Up to 120 slave stations can be connected to the master station)	
stations	stations		120 stations	
		Remote register (RWw)	8192 points, 16KB	
Maximum link points	nor station	Remote register (RWr)	8192 points, 16KB	
Maximum link points	per station	Remote input (RX)	16384 points, 2KB	
		Remote output (RY)	16384 points, 2KB	
		Remote register (RWw)	8192 points, 16KB	
	Master	Remote register (RWr)	8192 points, 16KB	
	station	Remote input (RX)	16384 points, 2KB	
Maximum link		Remote output (RY)	16384 points, 2KB	
points per station		Remote register (RWw)	8192 points, 16KB (also including the send range of own station)	
	Local	Remote register (RWr)	8192 points, 16KB	
	station	Remote input (RX)	16384 points, 2KB	
		Remote output (RY)	16384 points, 2KB (also including the send range of own station)	
Network topology			Line topology, star topology (Coexistence of line topology and star topology is possible.),	
			and ring topology	
Communication met			Token passing method	
Communication port			CC-Link IE Field Network port x 2	
RAS function			Automatic return, Slave station disconnection, Loopback function	
Connection cable*1			Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000BASE-T standard	
Maximum number of	· · · · · · · · · · · · · · · · · · ·	ecification	Counts as 2 modules	
Number of occupied			32 points (I/O assignment: Intelligent 32 points)	
5VDC internal curre	nt consumption	on	0.89A	
Weight			0.27kg	

<sup>\*1:</sup> Straight through cable

# MELSEG L series

### **CC-Link IE Field Network Head Module**

### ■ LJ72GF15-T2

Intelligent device station	Transmission speed  1Gbps	Remote I/O 2048 points
Remote register 1024 words	Max. number of connected modules 120	
RAS function  System monitor	RAS function Remote RESET	RAS function Self-diagnosis
CC-Link IE Field	CC-Lín	k IE Flield



\*END cover is included.

### **CC-Link IE Field Network remote I/O station**

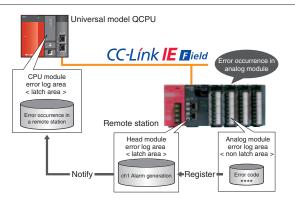
L series I/O and intelligent function modules can be connected to the remote I/O head module without a dedicated CPU. There are many benefits to using intelligent device stations including reduced CPU and wiring costs, great flexibility in selecting I/O and intelligent function modules, and compact unit size.



Modules compatible with the CC-Link IE Field Network head module			
	Item		
I/O module	Input		
i/O module	Output		
A complete control of	Analog input		
Analog module	Analog output		
Temperature Control module			
Simple Motion Module			
Positioning Module			
High-speed counter module			
	CC-Link		
Network module	CC-Link/LT		
	Serial communication		

### RAS (Reliability, Availability, Serviceability) functions

One feature of RAS is to store all remote station error histories in the master station's latched memory. This preserves the error information in one place in the event of power loss and allows for easy troubleshooting. Other RAS features include network event logging, unit error logging, and testing and monitoring capabilities.



Item		LJ72GF15-T2		
Transmission speed		1Gbps		
Maximum overall cable	Line network topology	12000m (with 1 master and 120 slaves connected)		
distance (Maximum transmission distance)	Star network topology Depends on the system configuration			
uistarice)	Ring network topology	12100m (with 1 master and 120 slaves connected)		
Transmission path		Line, star, line and star mixed, or ring topology		
Communication method		Deterministic (token passing)		
Maximum number of modul	es specification*1	10		
Communication port		CC-Link IE Field Network port x 2		
RAS function		Network event logging, unit error logging, testing, monitoring, and error history preservation function		
Connection cable*2		Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000BASE-T standard		
5VDC internal current consu	ımption	1.00A		
Weight		0.23kg		

<sup>\*1:</sup> The total number of modules that can be mounted to a CC-Link IE Field Network head module. (END cover and power supply module are not included.)

<sup>\*2:</sup> Straight through cable

### **CC-Link Master/Local Module**

### ■ LJ61BT11

Master/ local station	Max. transmission speed 10Mbps	Remote I/O 8192 points*	Remote register 2048 words*
CC-Link Ver.2.0	Standby master station function	Local station Transmission speed auto-tracking function	

<sup>\*</sup>Link points for CC-Link Ver.2.0 master station

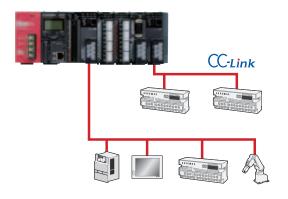




# Connect with a huge selection of device types using CC-Link

With such a large selection of CC-Link open network compatible devices, constructing a control system is easy.

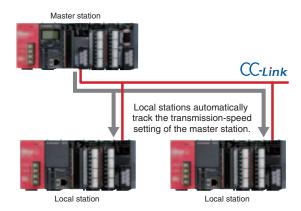
Even applications requiring vast amounts of data transmissions can be satisfied because CC-Link Ver.2.0 is supported.



# Local stations do not require transmission speed settings

### [Transmission speed auto-tracking function]

When used as a local station, no transmission speed setting is required; the setting is made through automatic detection of the master station setting. The current transmission speed in is indicated by an LED on the front surface of the module.



- opecinications			
lte.	em	LJ61BT11	
Transmission speed		156kbps/625kbps/2.5Mbps/5Mbps/10Mbps	
Maximum overall cable distance (Maximum transmission distance)		1200m (without repeater, varies according to the transmission speed)	
Maximum number of connect	cted stations (master station)	64	
Number of occupied stations (local station)		1 to 4 stations (The number of stations can be switched using the GX Works2 parameter setting)	
	Remote I/O (RX, RY)	2048 points	
Maximum number of	Remote register (RWw)	256 points (master station → remote device station/local station/intelligent device station/standby master station)	
nk points per system*1	Remote register (RWr)	256 points (remote device station/local station/intelligent device station/standby master station → master station)	
	Remote I/O (RX, RY)	32 points (local station is 30 points)	
Number of link points per	Remote register (RWw)	4 points (master station → remote device station/local station/intelligent device station/standby master station)	
station*1	Remote register (RWr)	4 points (remote device station/local station/intelligent device station/standby master station → master station)	
Communication method		Broadcast polling method	
Synchronous method		Frame synchronization method	
Encoding method		NRZI method	
Fransmission path		Bus (RS-485)	
Fransmission format		Conforms to HDLC	
Error control system		CRC (X16+X12+X5+1)	
		Automatic return function	
RAS function		Slave station cut-off function	
		Error detection via link special relay/register	
Connection cable		CC-Link dedicated cables compatible with Ver.1.10	
Maximum number of mod	ules specification	Counts as 1 module	
lumber of occupied I/O p	oints	32 points (I/O assignment: Intelligent 32 points)	
SVDC internal current con	sumption	0.46A	
Veight		0.15kg	
tt. Indiantan tha mumbau	of limbs mainte for Damata mat	A Van 1 mada	

<sup>\*1:</sup> Indicates the number of link points for Remote net Ver.1 mode.

# MELSEG L series

### **CC-Link/LT Master Module**

■ LJ61CL12

Master station	Max. transmission speed 2.5Mbps	Remote I/O 1024 points*
CC-Link/LT	No parameter settings	Remote station Transmission speed auto-tracking function
*In the 16-point mode		$\overline{\gamma}$ $/IT$

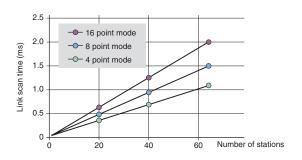




### High speed equipment response

CC-Link/LT has an excellent response time. With 64 stations and a transmission speed of 2.5Mbps, the maximum link scan time is just 1.2ms. According to the transmission distance required, it is possible to select speeds of 2.5Mbps, 625kbps, or 156kbps.

### ■ CC-Link/LT link scan time (using a transmission speed of 2.5Mbps)



### Simple networking that 'just works'

There are no confusing parameters settings to make, and with remote I/O, only the master station needs to set the transmission speed.

Item		LJ61CL12				
Point mode				4-point mode	8-point mode	16-point mode
	Maximum link points			256 points	512 points	1024 points
	(the same I/O address used)		ed)	(512 points)	(1024 points)	(2048 points)
	Link points			4 points	8 points	16 points
	(the same I/O address used)			(8 points)	(16 points)	(32 points)
			Points	128 points	256 points	512 points
Control		32 stations	2.5Mbps	0.7ms	0.8ms	1.0ms
specifications		connected	625kbps	2.2ms	2.7ms	3.8ms
	Link scan		156kbps	8.0ms	10.0ms	14.1ms
	time		Points	256 points	512 points	1024 points
		64 stations	2.5Mbps	1.2ms	1.5ms	2.0ms
		connected	625kbps	4.3ms	5.4ms	7.4ms
			156kbps	15.6ms	20.0ms	27.8ms
	Transmission speed			2.5Mbps/625kbps/156kbps		
	Communication method			BITR method (Broadcastpolling + Interval Timed Response)		
	Network topology			T-branch type		
Communication	Error control system			CRC		
specifications	Number of connectable modules		nodules	64		
specifications	Remote station number			1 to 64		
	Installation position of master station		ster station	End of a trunk line		
	RAS functio	n		Network diagnostics, internal loopback diagnostics, slave station cutoff function, automatic return function		
	Connection	Connection cable*1		Dedicated flat cable (0.75mm² x 4)², VCTFcable'³, flexible cable'²		
Maximum nu	mber of mod	ules specificati	ion		Counts as 1 module	
Number of o	ccupied I/O p	ooints*4		16, 32, 48, 64, 128, 256, 512, or 1024 points (I/O assignment: Intelli.)		
5VDC intern	al current cor	nsumption		0.16A		
		Voltage			20.4 to 28.8VDC	
24VDC power	er supply⁵⁵	Current cons	sumption		0.03A	
		Current on s	startup		0.07A	
Weight					0.12kg	
*1: When the ca	1: When the cables other than dedicated flat cables, VCTF cables, and flexible cables are used, performance of CCLink/LT is not guaranteed.					

<sup>23:</sup> Use the dedicated flat cables and flexible cables accredited by CC-Link Partner Association. Chink Partner Association website: http://www.cc-link.org/

23: Refer to the manual for details regarding VCTF cable specifications.

43: Set the number of occupied I/O points using the operation setting switch. Refer to the manual for details.

45: 24VDC power supply is supplied through the dedicated power supply or power supply adapter.

### **Ethernet Interface Module**



Transmission speed 100Mbps / 10Mbps	MELSOFT connection	MC protocol communications
Fixed buffer communications	Random access buffer communications	E-mail function
Web function		



### **Connection with MELSOFT and GOT**

With the MELSOFT Ethernet connection, it is possible to monitor/program/test the sequence program (MELSOFT connection), and monitor the programmable controller from the GOT.

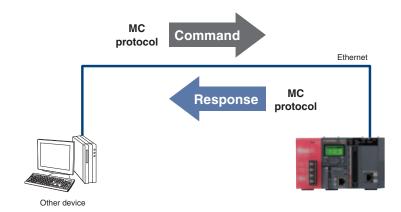
Remote operations making full use of the Ethernet capability of long-distance connectivity and high-speed communications.



### Modify/collect CPU data from other devices

[ MC protocol communications ]

MC Protocol enables other devices connected on Ethernet to gain access to the control system. The Ethernet module can communicate with a PC and HMI (Human Machine Interface), for example, as long as the connected devices can receive/send messages in the MC protocol communication format. In addition to this, by using the separate tool, MX Component, communication with the control system can be achieved without requiring detailed knowledge of the communication protocol.

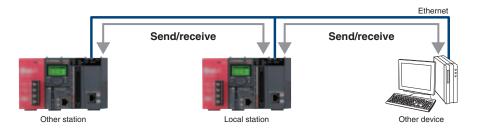




### Exchange of data with connected devices

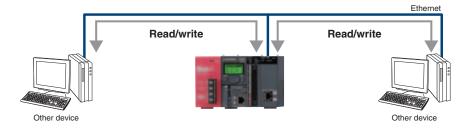
[ Communications using a fixed buffer ]

Up to 1K-word data can be exchanged between programmable controllers or between programmable controller and the host system. While MC protocol communications are passive, fixed buffer communications are an active protocol. If an error occurs in equipment or certain conditions are met, the programmable controller can send data to the host system. Using an interrupt program allows the CPU module to quickly retrieve data.



[ Communications using a random access buffer ]

Up to 6K-word of communication data is possible. This is useful when the data size is too large for communications using fixed buffer communication (capacity: 1K word).



### E-mail send/receive

[ E-mail function ]

This function enables sending/receiving of e-mails to a connected device via the Internet.

### Exchanging data by e-mail

[ Web function ]

The system administrator can monitor a CPU module remotely via the Internet using a commercially available Web browser.

Item			LJ71E71-	100 NEW	
Standard			100BASE-TX	10BASE-T	
	Data transmission speed		100Mbps	10Mbps	
	Interface		RJ45 (AUTO MDI/MDI-X)		
Transmission	Communication m	ode	Full duplex / Half duplex	Half duplex	
specifications	ons Transmission method		Base	band	
	Maximum segment length		100m (length between a hub and node)*1		
	Maximum number of cascade connections		Cascade connection (maximum of 2 levels)*2	Cascade connection (maximum of 4 levels)*2	
	Number of simultaneous open connections		16 connections (Connections usable on a program)		
Sending/	Fixed buffer		1k word × 16		
receiving data storage	Random access buffer		6k words × 1		
memory	E-mail	Attachment	6k wor	rds x 1	
momory	E-maii	Main text	960k wo	ords × 1	
Maximum nu	Maximum number of modules specification		Counts as 1 module		
Number of occupied I/O points			32 points (I/O assignment: Intelligent 32 points)		
5VDC internal current consumption		tion	0.60A		
Weight			0.18kg		

<sup>\*1</sup> For the maximum segment length (a length between hubs), consult with the manufacturer of the switching hub used.
\*2 This applies when a repeater hub is used. For the number of levels that can be constructed when a switching hub is used, consult with the manufacturer of the switching hub used.

### **Serial Communication Modules**

### ■ LJ71C24

Interface RS-232	Interface RS-422/485	Max. transmission speed 230.4kbps*	
Communication system  MC protocol	Communication system Pre-defined protocol	Communication system Nonprocedural protocol	Communication system Bidirectional protocol
GX Works2 Error history			

<sup>\*</sup>Available for only channel 1



### ■ LJ71C24-R2

Interface RS-232 x 2	Max. transmission speed 230.4kbps*		
Communication system  MC protocol	Communication system Pre-defined protocol	Communication system Nonprocedural protocol	Communication system Bidirectional protocol
GX Works2 Error history			

<sup>\*</sup>Available for only channel 1

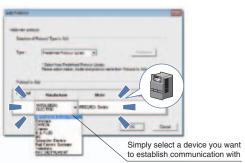


### Quick connection using pre-defined protocols

Establish communication with devices quickly by simply selecting a device from the pre-defined protocol library included in GX Works2.

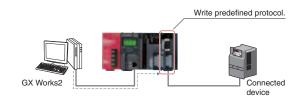
① Select the manufacturer and model (series) of the device to be connected.

There is no need for complicated predefined protocol setting for the device. Simply select the device from the prepared predefined protocol library.



### 2 Write the predefined protocol to the module.

Write the set predefined protocol to Serial communication module. Up to 128 protocols can be set in one module.



Communication starts.

### 3 Execute the protocol with ladder program.

With ladder program, communication with any external device can be made only by executing a dedicated predefined protocol starting instruction.



CPU

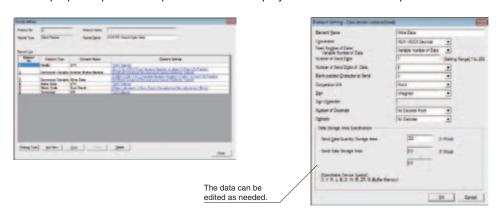


### Easy to prepare and edit predefined protocol

Even if the device to be connected is not contained in the predefined protocol library, the device can be added easily.



The contents of the prepared predefined protocol can be displayed in a list form. The protocol can be edited easily.



Item		LJ71C24 LJ71C24-R2		-R2			
Interface	ch1	RS-232 compliant (D-Sub 9P female)		RS-232 compliant (D-	Sub 9P female)		
interiace	ch2	RS-422/485 compliant (2-piece terminal block)		RS-232 compliant (D-	Sub 9P female)		
	Line	Full-duplex/half-	duplex communicati	ons			
	MC protocol	Half-duple	x communications				
Communication	Pre-defined protocol						
system	Nonprocedural protocol	Full-duplex/half-	Full-duplex/half-duplex communications				
	Bidirectional protocol						
Synchronization me	thod	Start-stop syr	chronization method	d			
		50bps/300bps/600bps/1200bps	/2400bps/4800bps/9	9600bps/14.4kbps/			
		19.2kbps/28.8kbps/38.4kb	os/57.6kbps/115.2kb	pps/230.4kbps			
Transmission speed	d	Transmission speed 230.4h					
		Total transmission speed of two					
		Total transmission speed of two interfaces is available up to		communication data r	monitoring function is used.		
	Start bits		1				
Data foramat	Data bits		7 or 8				
Data Ioramat	Parity bits	1 (vertical	I parity) or none				
	Stop bits	1 or 2					
	MC protocol	Processes one request during installed C24 CPU module END processing.  (Number of scans that must be processed/number of link scans depends on the contents of the request.)					
Access cycle	Pre-defined protocol	Sends or receives data when reques	Sends or receives data when requested with the dedicated instruction (CPRTCL).				
	Nonprocedural protocol	Condo coch time a cond very	et is issued. Can us	anius at anuttima			
	Bidirectional protocol	Sends each time a send request is issued. Can receive at any time.					
	Parity check	All protocols and when ODD/EVEN is selected by parameter.					
Error detection		MC protocol/bidirectiona					
Lifer detection	Sum check code	For the pre-defined protocol, whether or not a sun			elected protocol.		
		Nonprocedural prote	col selected by user	r frame.			
			RS-232	RS-422/485			
		DTR/DSR (ER/DR) control	Enabled	Disabled			
		RS/CS control	Enabled	Disabled			
Transmission contro	ol	CD signal control	Enabled	Disabled			
		DC1/DC3 (Xon/Xoff) control	Enabled	Enabled			
		DC2/DC4 control	Lilabieu	Lilabled			
		DTR/DSR signal control and DC code control are selected by the user.					
Transmission distance RS-232		Ma	rimum 15m				
(Overall distance) RS-422/485		Maximum 1200m (overall distance)		_			
Maximum number of modules specification		Count	s as 1 module				
Number of occupied	d I/O points	32 points (I/O assig	nment: Intelligent 32	points)			
5VDC internal curre	nt consumption	0.39A		0.26A			
Weight		0.17kg		0.14kg	9		
		-		,			

### **Ethernet and CC-Link IE Field related products**

■ Wireless LAN Adapter Ethernet

NZ2WL-US (U.S.A)\*1\*2, NZ2WL-EU (Europe)\*1\*2, NZ2WL-CN (China)\*1\*2, NZ2WL-KR (Korea)\*1\*2, NZ2WL-TW (Taiwan)\*1\*2

- Wireless LAN (Ethernet) in the factory provides flexibility in installing new line or alteration layouts. Wireless saves your wiring costs.
- Simply installing wireless LAN adapters makes existing FA equipment wireless.
- Compatible with the latest security standards of WPA2/WPA. The security prevents unauthorized access from outside.
- \*1 Each product can be used only in the respective countries.
  \*2 Supported both Access point and Station. They can be used by changing the setting.

The wireless LAN adapters were developed and are produced with CONTEC Co., ltd.

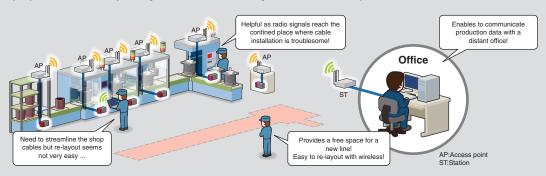
Please note that the general specifications and guarantee conditions of these products are different from those of programmable controllers (such as MELSEC series) and CONTEC products.

Refer to the manual for details on the product.



### Wireless LAN needs no cables!

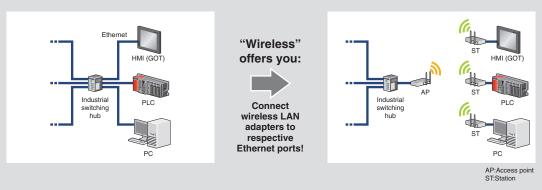
• Easy to work without being bothered by cable routing. Factory layouts can be easily changed, and costs for wiring can be substantially reduced.



### Easily adapt existing FA devices to wireless connections!

• Programmable controllers, displays and PCs can be easily added to an existing Ethernet network just by attaching wireless LAN adapters.

[Note] Ethernet data communication through wireless LAN could be unstable compared to wired one due to packet loss depending on peripheral conditions and place of installation. Be sure to confirm it works as intended



### Trustworthy security

• Compatible with the latest security standards of WPA2/WPA. The security prevents unauthorized access such as bugging and falsification of data from outside.

MELSEG L series

### ■ Industrial Switching HUB CC-Link IE Field NZ2EHG-T8 / NZ2EHF-T8\*1

- NZ2EHG-T8 is compatible with transmission rates of 10 Mbps, 100 Mbps, and 1 Gbps.
- NZ2EHF-T8 is compatible with transmission rates of 10 Mbps and 100 Mbps.
- These switching hubs comply with IEEE802.3ab (1000 BASE-T), IEEE802.3u(100 BASE-TX), IEEE802.3 (10 BASE-T) standards.
- AutoMDI/MDI-X and auto-negotiation are available.
- The automatic power adjustment function can reduce power consumption by up to 80
- These hubs do not use cooling fans, and yet a wide ambient-temperature operating range is permissible (0 to 50°C).
- Quick detach mechanism allows easy DIN rail attachment and detachment.
- \*1 This model may not be connected directly to the CC-Link IE Field Network (1 Gbps). An Ethernet adapter module NZ2GF-ETB is
- required. For direct use with the CC-Link IE Field Network, please use NZ2EHG-18.

  2F For comparison, power consumption was measured when all 8 ports were used and when none of them were used. This function is only available for NZ2EHG-18.

This series was developed and is produced with Contec Co. Ltd. Please note that the specifications and guarantee conditions of these products are different from those of MELSEC products. Please refer to the product manual for details.



[1Gbps]

[100Mbps]

### ■ CC-Link IE Field Network Ethernet Adapter Module CC-Link IE Field Ethernet NZ2GF-ETB

### Features

- Using Seamless Message Protocol (SLMP\*1), a variety of Ethernet devices such as vision sensors and RFID controllers can be connected to the CC-Link IE Field Network.
- Use a web browser to set station numbers, Ethernet options, and view error history.
- This Ethernet adapter module is compatible with transmission rates of 100 Mbps and 1
- \*1 SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.

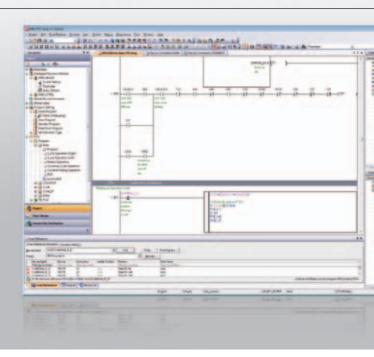


# Increase productivity and lower the total cost of ownership.

Introducing the next generation of IA programming software:

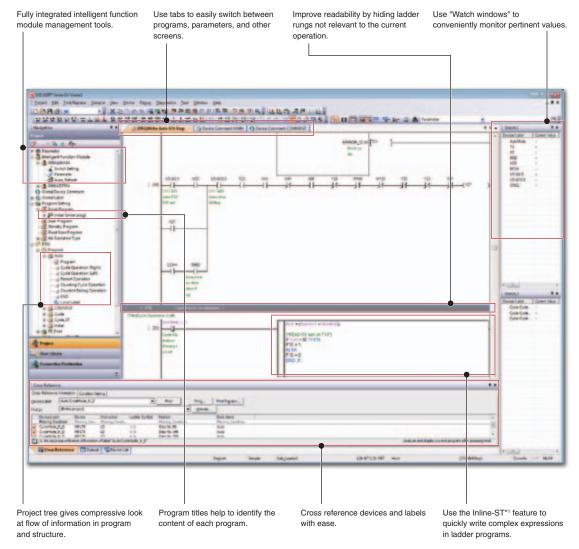
# GX Works2

GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.



### User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.

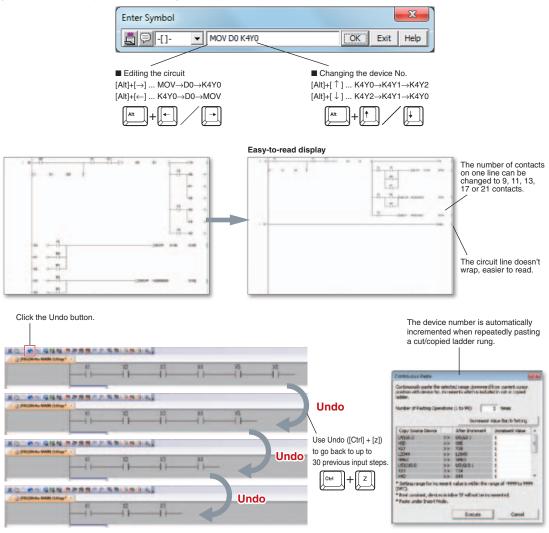


 $^{\star}1\,$  In-line ST can be only be created in projects that use labels.



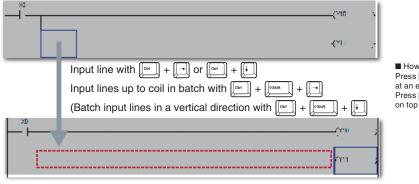
### Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [Alt] + [ $\leftarrow$ ] / [ $\rightarrow$ ] or [Alt] + [ $\uparrow$ ] / [ $\downarrow$ ] keys.



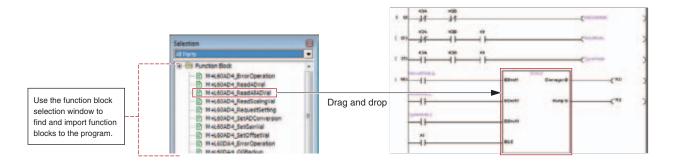
### Efficiently edit lines with keyboard

Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.



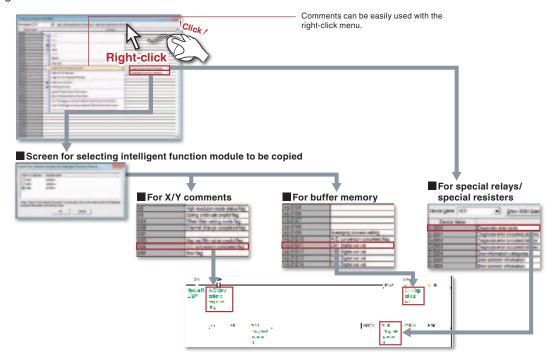
### Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.



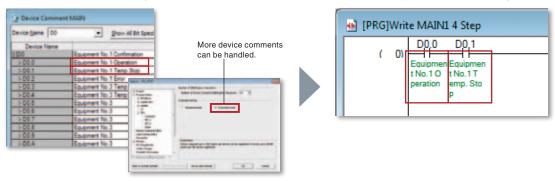
### Use sample comments to eliminate the need to input comments

Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.



### **Quickly identify similar devices**

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.



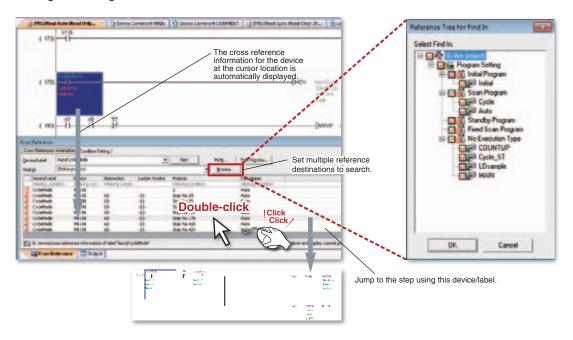
CPU

Function



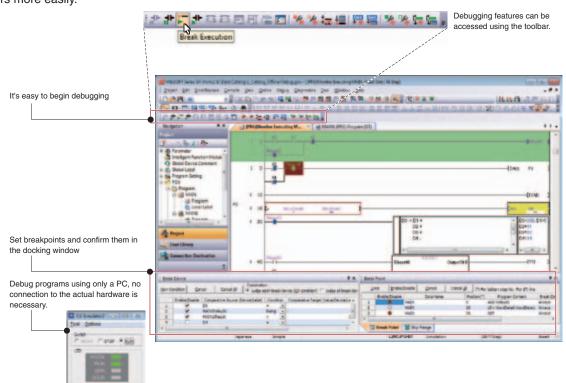
### Cross referencing interlinked with circuit displays

Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.



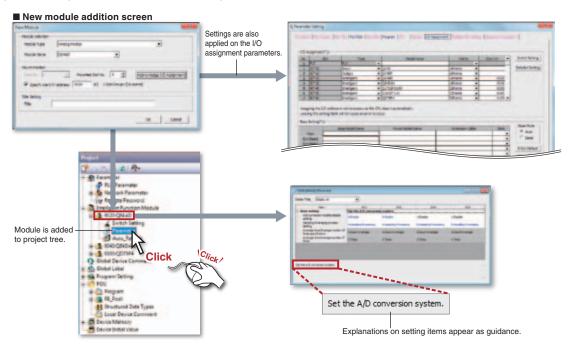
### Offline debug without physical hardware

The simulation function is now integrated. The program can be executed in a step-by-step method, finding program errors more easily.



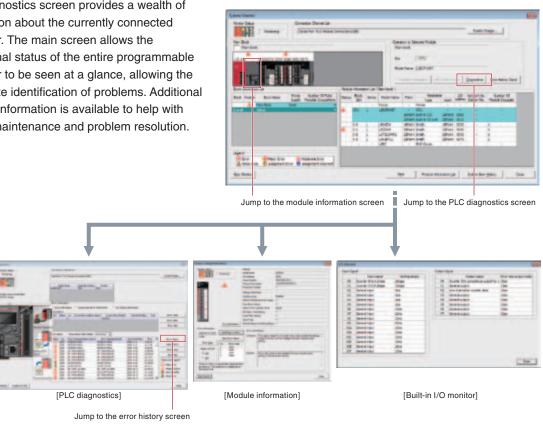
### Integrating the intelligent function module setting tool (GX Configurator)

The intelligent function module's setting functions have been unified with GX Works2. Manage the intelligent function module's setting with a GX Works2 project.



### Advanced PLC diagnostics

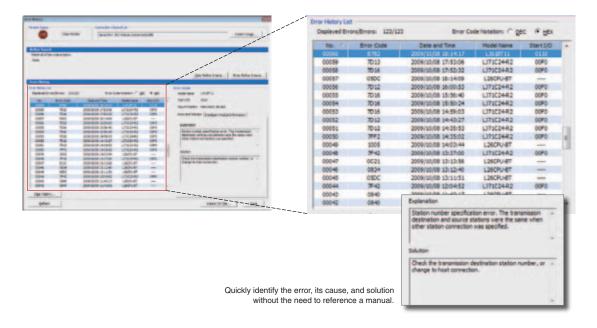
The diagnostics screen provides a wealth of information about the currently connected controller. The main screen allows the operational status of the entire programmable controller to be seen at a glance, allowing the immediate identification of problems. Additional detailed information is available to help with routine maintenance and problem resolution.





### Time-stamped error history list

Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.



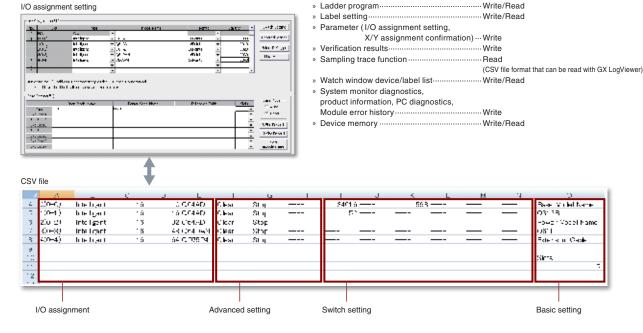
### Save and edit labels and parameters with Excel®

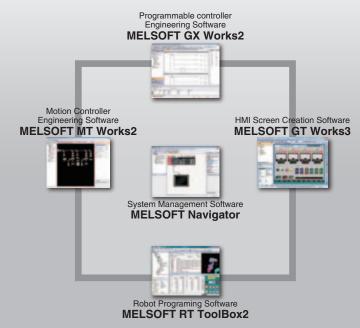
Various program data can be exported in CSV file format.

Exporting to CSV format has various advantages, as shown below:

- Data can be utilized on a PC even if GX Works2 is not installed
- Data can be saved directly on the PC
- Data can be sent and utilized off-site
- Utilization of data for creating documents and graphs are possible using Excel®
- Can use in other software that support CSV format

### ■ Example of I/O assignment setting CSV file





# MELSOFT iQ Works

# **Next Generation Seamless Engineering Environment**

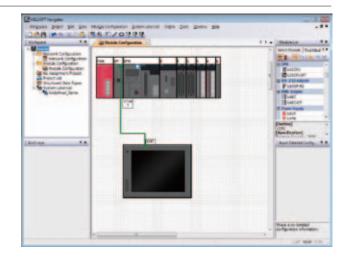
iQ Works is the combination of Mitsubishi engineering software (GX Works2, MT Works2, GT Works 3, RT ToolBox2) that allows for the sharing of design information to improve programming efficiency and reduce TCO.

### **Graphical Project Management**

The entire control system is represented using the "Network Configuration" and "Module Configuration" windows.

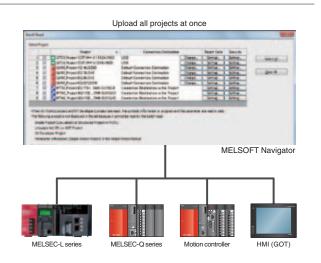
System components are easily added using a drag & drop interface and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc.

Different project types can be grouped together (for example by factory, line, and cell) for central management.



### Read project data for multiple devices in a batch

Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.



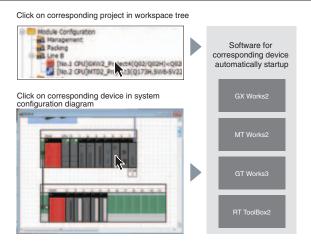
5

CPU



#### Automatically startup the relevant maintenance software with a single click

Just click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.

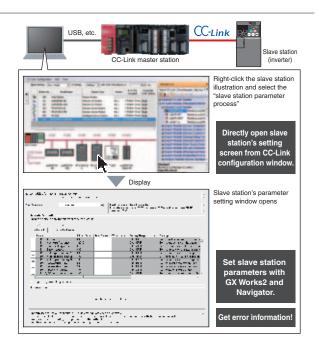


#### **Setup CC-Link slave stations**

There's no need to prepare a dedicated tool to check or change the parameter settings for the CC-Link slave station on-site.

The latest version of iQ Works includes CC-Link slave station setting utility. Therefore, it is possible to directly confirm the inverter parameters or change the settings for changing the speed directly from the CC-Link configuration window, for example.

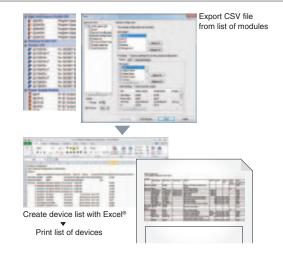
In addition, error information can also be read easily.

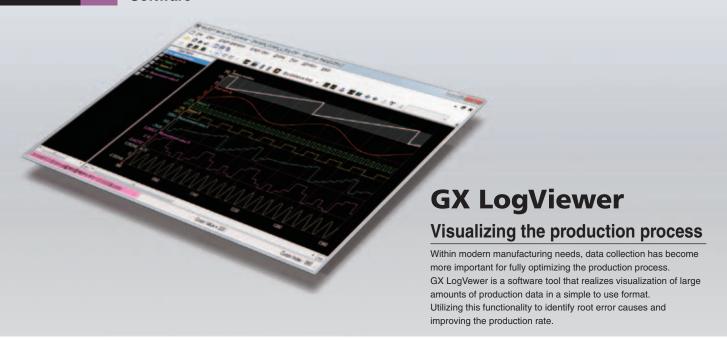


#### Prepare a device from the system configuration diagram with no manual inputs

A list of modules used can be exported as a CSV file from the system configuration diagram.

This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel®, etc.

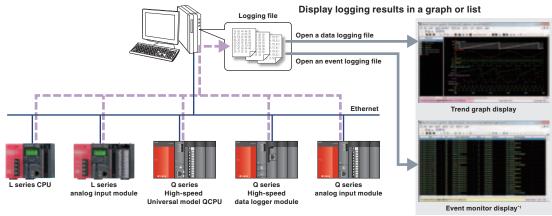




#### Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q series or MELSEC-L series.

The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.

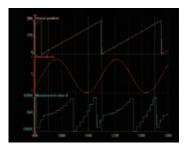


\*1 The event monitor display is supported only with the Q series high-speed logger module.

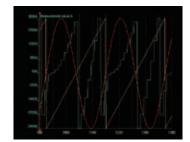
#### Easily adjust graphs without referring to the setup manual

[ Arranging graphs ]

Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.



[ Overlapping graphs ]
With this it is possible to overlap
each graph over one another.
OMultiple graphs can be compared
enabling easier data analysis and
comparison.



[ Automatically adjusting graphs ] Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.

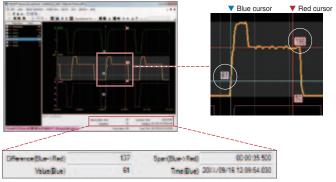


CPU



#### Easily confirm changes in data with dual cursors

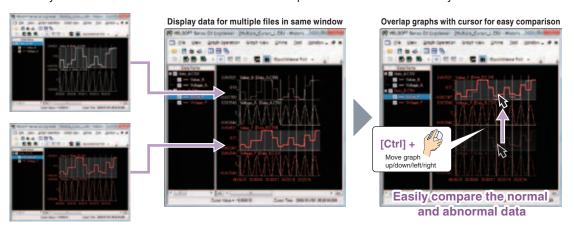
Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multi-cursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.



The difference in time and value between the cursors is automatically calculated and displayed.

#### Display data for multiple files within one graph area for easy comparison

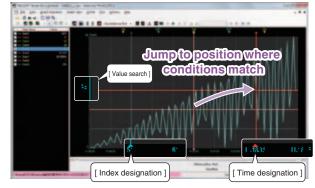
Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.



#### Quickly jump cursor to designated position

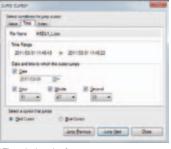
#### [ Cursor jump ]

Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.

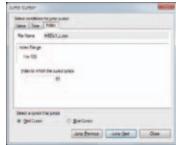




[ Value search ] Values are searched, and the cursor jumps to the position where the conditions match.



[ Time designation ]
The cursor jumps to the designated time.

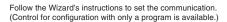


The cursor jumps to the designated index.



#### **Easily set communication conditions with Wizard**

The Wizard style communication configuration utility facilitates access to the programmable controller's CPU. The communication configuration utilities saves the set programmable controller CPU's logic station number, making it simple to access the programmable controller's CPU just by setting the station number.

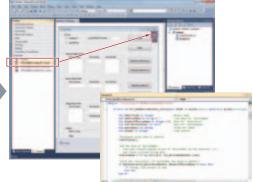




Paste the MX Component control icon into the form.

The set communication path No. is set in the pasted control's properties.

After setting the communication path No., write the program for reading the device.



#### Data collection by VBA

Real time graph display applications can be created using VBA programming in Excel® and Access®. Logged programmable controller device data can be collected and saved in real-time.



#### Reduce man-hours by developing programs with labels

Devices can be set according to the assigned label.

Labels enable intuitive configuration of the program within MX Sheet or directly in the program itself. Therefore, if changes are made to the devices, there is no need to further change the program or MX Sheet file.





## MX Sheet Ver. UP

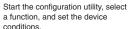
## Easy data collection using Excel®

Enables monitoring of the programmable controller or motion controller, log data, collect alarm information, and changing setting values, etc., using familiar Excel® software.

#### Simple and program-less setting

MX Sheet operation conditions can be set from Excel®. Therefore, a communication program is not required to communicate between programmable controller and Excel®.



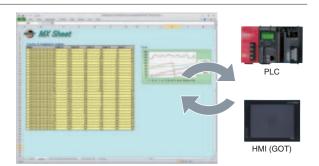




Then, data collection will be started only by arranging the screen and executing the function.

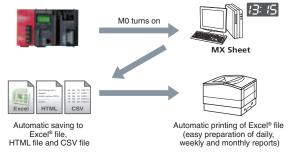
#### Direct connection between office and field

The device data in the programmable controller is monitored and logged real time before being written to Excel®. Recipe data can also be transferred to programmable controller directly from Excel®.



#### **Auto-generate periodic reports**

The data displayed on Excel® is automatically saved or printed at the specified time or as requested by the programmable controller. Periodic reports and test result lists are generated automatically.



Daily reports and monthly reports can be automatically saved and printed according to various conditions.



## Combination with GOT for all scenes from startup to maintenance

To start the equipment more quickly and minimize the downtime.

To create the value of time, GOT1000 has successively realized solutions as more than just an HMI.

Now the cooperation with programmable controller is

Now the cooperation with programmable controller is strengthened through the quick operability and functionality of the HMI.

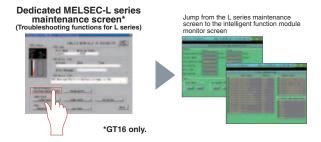
Enhanced functions required on site are reflected on its clear screen to realize advanced productivity and workability.

For details, refer to the "Mitsubishi Graphic Operation Terminal GOT1000 Series Catalog" catalog.



#### Harness the power of L series and GOT combined

When connected to an L series system, Mitsubishi Graphic Operation Terminals are capable of advanced system maintenance and diagnostic functions that can reduce downtime.



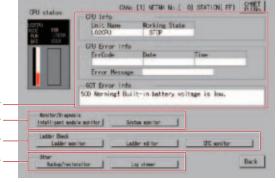
#### Save time by performing system maintenance functions directly from the GOT

Graphic Operation Terminals include maintenance screens dedicated for the L series that let the user check CPU status and error information. No PC is required and no special screens need to be created for the GOT. Jump directly from the L series maintenance screen to other maintenance screens such as the intelligent function module monitor.

GT16



General system information and combined error history



emory card,

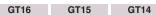
Restore

Copy saved program files to a new CPU..

CPU exchange

#### [Backup / Restore]

Using this feature, it's easy to create backups of sequence programs and other CPU data. It can even be configured for automatic operation. Create backups after programs are updated and restore programs in case of trouble. Because the data are stored on the GOT, no PC is required.



[Intelligent Module Monitor]

Monitor and test built-in I/O and expansion modules.

This feature works with nearly all expansion module types from analog I/O to high speed counters and positioning.



#### Use GT Works3 templates to easily create screens

Select a template from the library and put it on the editor screen, and you can easily create a simple motion module\*1 operation monitor or error history screen, etc.

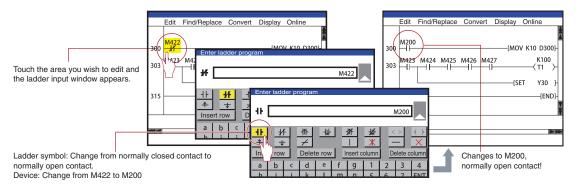


\*1 LD77MH4 only



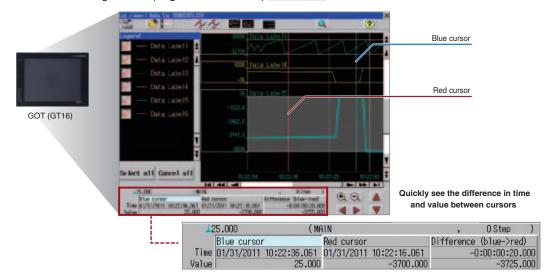
#### Make simple corrections to ladder programs using a GOT

GOTs enable ladder programs to be edited without the need for a PC. Furthermore, because it is possible to perform write during run operations using the GOT, ladder programs may be corrected without stopping the machine, even if it is in operation. (Ladder editing function) GT16 GT15



#### View logging data without a PC

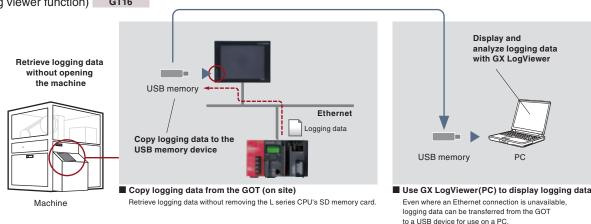
Logging data can be confirmed with the GOT (GT16) even if a PC is not available on-site, allowing problems to be troubleshooted quickly. Changes in the data can be quickly confirmed with the dual cursors (multi-cursors) that are displayed similar to GX LogViewer. (Log viewer function) GT16



#### Retrieve logging data without opening any panels

Using the front mounted USB port on the GT16 Series, L series users can easily copy logging data from the LCPU to a USB memory device.

Logging data can be retrieved easily without opening any control panels or removing the SD memory card from the CPU. (Log viewer function) GT16





## Man, machine and environment in perfect harmony

MELSERVO-J4 — trusted technology makes an evolutionary leap forward.

Introducing the MELSERVO-J4 series. Offering more than just improved performance, these servos are designed to drive the industries of tomorrow. Backed by Mitsubishi leadership in all-digital technology, MELSERVO has become one of the most globally respected names in factory automation. And now — with the safety, ease of use, and energy-efficient design of the new MELSERVO-J4 series — man, machine and environment can at last work together in perfect harmony.



For details, refer to the "MELSERVO-J4" catalog.

# MELSERVO-J4



#### Servo amplifier

SSCNET II/H compatible, CC-Link IE Field Network interface with Motion compatible, and general-purpose interface compatible servo amplifiers are available. MR-J4W2-B/MR-J4W3-B multi-axis servo amplifiers achieve energy conservation, space-saving and reduced wiring. MR-J4-B(-RJ)/MR-J4W2-B/MR-J4-A(-RJ) servo amplifiers are compatible with fully closed loop control system.



SSCNET III/H compatible servo amplifier MR-J4-B(-RJ)



SSCNET III/H compatible 2-axis servo amplifierr MR-J4W2-B



SSCNET III/H compatible 3-axis servo amplifier MR-J4W3-B



CC-Link IE Field Network servo amplifier with Motion MR-J4-B-RJ010\* + MR-J3-T10

\* MR-J4-B-RJ010 servo amplifier is compatible



General-purpose interface compatible

MR-J4-A(-RJ)

#### Servo motor

A variety of models are available to match various applications. These include rotary servo motors for high-torque output during high speed, linear servo motors for highly accurate tandem synchronous control, and direct drive motors for compact and rigid machine, and high-torque operations.

#### ■ Rotary servo motor



Small capacity, low inertia HG-KR Series



Small capacity, ultra-low inertia **HG-MR** Series



HG-SR Series



dium/large capacity, low inertia **HG-JR** Series Capacity: 0.5 to 22kW



Medium capacity, ultra-low inertia HG-RR Series Capacity: 1 to 5kW



Medium capacity, flat type HG-UR Series

#### ■ Linear servo motor



LM-H3 Series Rating: 70 to 960N



Core type with magnetic attraction LM-K2 Series Rating: 120 to 2400N



Core type (natural/liquid cooling) LM-F Series Rating: 300 to 3000N (natural cooling) Rating: 600 to 6000N (liquid cooling)



Coreless type LM-U2 Series Rating: 50 to 800N

## ■ Direct drive motor



TM-RFM Series Rating: 2 to 240N·m

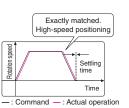
## **Machine**

#### The leading edge in drive control

#### Advanced one-touch tuning

Servo gains including machine resonance suppression filter, advanced vibration suppression control  $\mathbb{I}^*$ , and robust filter are adjusted just by turning on the one-touch tuning function. Machine performance is utilized to the fullest using the advanced vibration suppression control function.

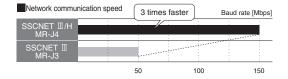
\*1 The advanced vibration suppression control II automatically adjusts one frequency.





#### Motion network SSCNET ${\rm I\hspace{-.1em}I}/H$ triples communication speeds

In the high-speed optical communication SSCNET III/H, communication speed is increased to 150 Mbps full duplex (equivalent to 300 Mbps half duplex), three times faster than the conventional speed. System response is dramatically improved.



## Man

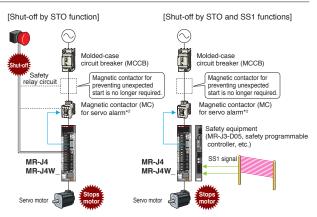
#### The leading edge in safety and convenience

#### Safety function according to IEC/EN 61800-5-2

MELSERVO-J4 series servo amplifiers have integrated STO (Safe Torque Off) and SS1\*1 (Safe Stop 1) functions as standard.

Safety system is easily configured in the machine. (SIL 2)

- Turning off the control power of servo amplifier is not required, cutting out the time for restart. Additionally, home position return is not required.
- Magnetic contactor for preventing unexpected motor start is not required.\*2
- \*1 Safety equipment (MR-J3-D05, safety programmable controller MELSEC QS/WS series, etc.) is required.
- \*2 Two magnetic contactors are not required when STO function is used. However, in this diagram, one magnetic contactor is used to shut off the power at alarm occurrence.

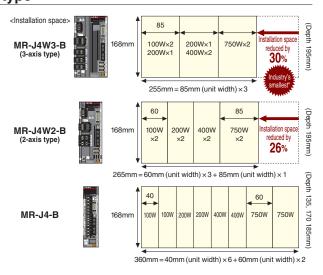


## The environment An evolution in eco-friendly design that's winning acclaim worldwide

#### Space-saving with industry's smallest\* 3-axis type

2-axis servo amplifier MR-J4W2-B requires 26% less installation space than two units of MR-J4-B. 3-axis servo amplifier MR-J4W3-B requires 30% less installation space than three units of MR-J4-B.

- \* This is when two units of 100W, 200W, 400W, and 750W each are used.
- \* Based on Mitsubishi Electric research as of January 2013.





#### Inverter

## Achieving higher drive performance and energy conservation with inverters

The inverter is a variable frequency power device that can easily and freely change the speed of a 3-phase induction

The Mitsubishi inverter is high-performance and environment-conscious, and complies with global standards. Select a model from our diverse lineup to match your needs.



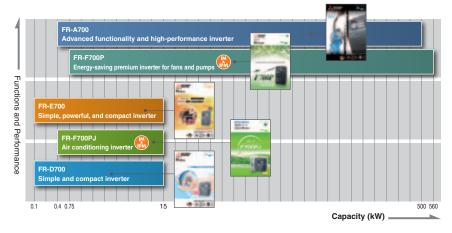
For details, refer to the "INVERTER FAMILY" catalog.



## Answering various needs with the best choices **Frequency Inverter**



#### FR-700 Series inverter



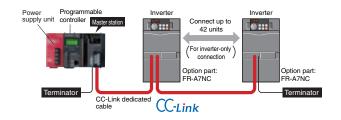
#### Control inverter with CC-Link communication

The inverter can be controlled to a programmable controller with CC-Link.\*1

This function is supported with CC-Link Ver. 1.1 and Ver. 2.0.

The inverter can be operated and monitored, and the parameters set from the programmable controller.

\*1 The inverter operation part (FR-A7NC) is required. Please refer to the relevant catalog for additional information.



#### Easy synchronous operation with SSCNET III connection

Connect to a motion controller with SSCNET II \*2. SSCNET II uses the high-speed synchronous serial communication method (high-speed, high-accuracy, high-reliability optical communication), and is perfect for synchronous operation.

(SSCNET: Servo System Controller Network)

\*2 Supported only with MELSEC-Q series. The inverter operation part (FR-A7NS) is required. Please refer to the relevant catalog for additional information.



5



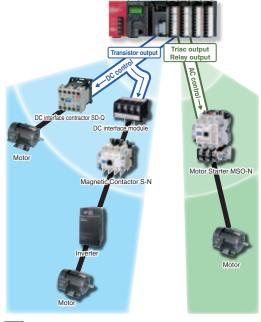
Contactors and **Motor Starters** 

## **Diverse variations** to respond to all situations

The Mitsubishi Electric Contactors and Motor Starters MS-N series and DC interface contactor SD-Q series products are equipped with an environment and global compliance, compact size, ease-of-use and safety. Certification to various international standards, this highly reliable magnetic contactor is suitable for a variety of applications from panels to systems.



For details, refer to the "Contactors and Motor Starters MS-N series'



#### **Direct drive with Programmable Controller**

The SD-Q series has a small coil VA and can be driven by the programmable controller without adding an amplifying relay. By adding the DC interface module, the MS-N series can be used with a wide range of motor capacities.

		Programmable controller output module type			
		Transistor output Contact output		Triac output	
DC interface contactor SD-Q series	DC operation	0	0	_	
Magnetic contactor	AC operation	(Using DC interface module)	0	0	
MS-N series	DC operation	0	×	_	

This table shows the relation of the programmable controller output module type and operation interface. There may be restrictions according to the type of frame size, etc., that can be used.

#### Refer to the MS-N series catalog for the types of magnetic contactor and models that can be used

#### **SD-Q** series

Direct drive is possible with the programmable controller's transistor output. Since a relay and interface module are not required, the number of parts can be reduced, and space can be saved.

#### Standard surge absorber

Prevent adverse effects onto the peripheral equipment.

#### Standard terminal cover

A terminal cover with finger protection function is mounted as a standard.

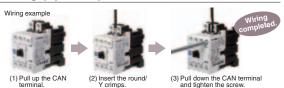
This cover answers to user's needs for safety.

#### **MS-N series**

Environment-friendly Mitsubishi MS-N series ensures safety and conforms to various global standards. Its compact size contributes to space-saving in a machine. The MS-N series is suitable for MELSEC-L series as well as other Mitsubishi FA equipment and can be used globally.

#### Mitsubishi's original CAN terminal structure for simple wiring (optional)

Mitsubishi MS-N series adopts the CAN terminal structure for simple wiring. Thus, wiring is reduced by approximately 35% compared to the conventional screw terminal wiring. (Based on Mitsubishi Electric research.) The CAN terminal structure also provides finger protection that complies with DIN VDE standard.



#### Mirror contact (auxiliary contact off at main contact welding)

The MS-N series meets requirements of "Control functions in the event of failure" described in EN 60204-1 "Safety of machinery-Electrical equipment of machines-", being suitable as interlock circuit contact. The MS-N series is applicable for category 4 safety circuit. We ensure safety for our customers.

#### Conforms to various global standards

Companies to various grobal standards									
	Standard				Certification		EC directive	Authority	CCC
Model	JIS/JEM	IEC	DIN/VDE	BS/EN	UL	CSA	CE	TÜV	GB
	Japan	International	Germany	England Europe	U.S.A	Canada	Europe	Germany	China
S-N10 to S-N400 MSO-N10 to MSO-N400 TH-N12KP to TH-N400KP								[]*	

<sup>\*</sup>The Motor Starters are certified under each type name of the Magnetic contactors and the Thermal Overload Relays on the condition that the Magnetic contactors and the Thermal Overload Relays are used in combination

∏. Compliant as standard



## Vision Solution

# COGNEX® machine vision system and Mitsubishi Electric FA Devices

## Innovating your production with this integral power.

Functioning as devices that "watch" instead of human eyes, COGNEX machine vision systems have continued to reform automation of production lines. Mitsubishi Electric FA devices, such as programmable controllers, lead the tomorrow of FA control.

The possibilities of vision system solutions, created in the integration of this spirit of innovation, have continued to increase. "In-Sight EZ", developed exclusively for use with Mitsubishi Electric FA devices, enhances functions.

Affinity, including connectivity and ease of program development, has also been refined.

The key solution for enhancing efficiency of inspections and identification, etc., for improving product quality and for reducing total costs lies within the integrated power of COGNEX + MITSUBISHI.



For details, refer to the "Vision System & Factory Automation Solution" catalog.

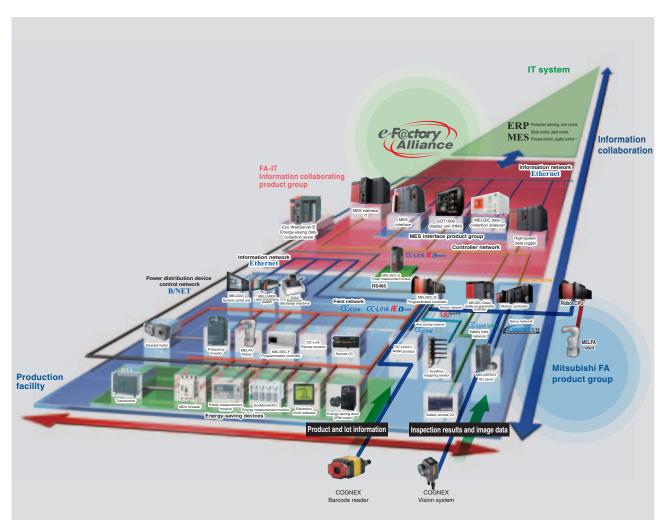
#### FA Integral Solutions

## e-F@ctory + COGNEX Vision

"e-F@ctory" is an assimilation of solutions that integrate the "MES interface" enabling "visualization" with seamless information sharing and "iQPlatform" realizing flexible sharing within the production site.

Mitsubishi Electric collaborates with partners from various fields to supports general factory optimization through the "e-F@ctory" concept.

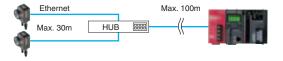
The latest achievement is the partnership of COGNEX Vision products and Mitsubishi Electric FA Devices.



#### Simple connection

#### [ Directly connect with Ethernet ]

The "In-Sight EZ" can be directly connected to the Ethernet port provided on the "MELSEC-Q series universal model" and "MELSEC-L" programmable controller, and to the Ethernet module on the MELSEC-F. By using a switching hub, a multi-unit vision system having units installed as far as 100m away can be created.



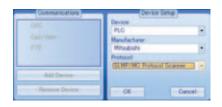
#### [ Connect with CC-Link ]

The expansion module option (CIO-MICRO-CC) supports the reliable open field network "CC-Link". The impressive high-speed response, reaching up to 10Mbps, high reliability and max. 1.2km long distant transmission allows a highly reliable system to be designed freely. CC-Link settings can be completed easily with EasyBuilder.



#### Simple communication with MC protocol

Now that "In-Sight EZ" supports MC protocol (communication protocol for programmable controller), data can be easily written from the vision system to the programmable controller. Communication is easily configured with "EasyBuilder". Just select the connected device and MC protocol, set the programmable controller device used for communication and select the communication data from the list. With the MC protocol scanner mode, a trigger can be applied on the vision system via MC protocol.



#### Simple control with control dedicated function blocks (FB)

The vision system control program can be created in a short time using the programmable controller programming tool "GX Works2" and rearranging labels by dragging and dropping the vision system control FB.

Partner Product

#### **COGNEX DataMan® Barcode Reader**

#### Supporting a variety of barcode reading

#### [ Industrial Ethernet compatible barcode reader ]

This barcode reader with Ethernet can easily be connected to the programmable controller with MC protocol, and can be used in a system with In-Sight EZ in the same Ethernet line. With the Ethernet compatible DataMan, the read code can be adjusted with VisionView® in the same manner as In-Sight F7

In collaboration with e-F@ctory, the code reading results and images can be sent to the MES interface unit.

#### [ Reading various codes with simple adjustments ]

DataMan automatically optimizes the brightness of the image. The automatic focusing model adjusts the focal distance from the barcode reader and workpiece simultaneously, and greatly reduces the man-hours required from installation to operation.

The DataMan common setup tool is available for more detailed settings.

#### [ Amazing code reading algorithms IDMax® ]

1DMax+™: Provides an amazing two-dimensional code reading performance when directly marking parts with a laser or dot peen.

2DMax+™: The new HOTBARS™ technology allows weak codes and damaged large codes to be read at a high speed. Various situations not supported with conventional laser scanning methods are not supported.

#### [ DataMan - active in various industries ]



#### Fixed DataMan 300 Series

- ▶Equipped with latest reading algorithm 1DMax+, 2DMax+
- ▶Powerful in reading extra small markings with a high resolution of 1,300,000 pixels
- ▶ Reduce installation and maintenance man-hours with liquid lens (option) for automatic focus adjustment and the tuning
- ► Support for MC protocol scanner simplifies communication settings



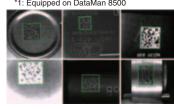
DataMan 300



#### ●Hand-held DataMan 8100/8500 Series

- ► Newly developed body enhances sturdiness
- ►UltraLight®: Two types of lightning enable optimum reading\*
- ▶Standard automatic focus adjustment function
- ►Wireless model (communication range: max. 30m) available

\*1: Equipped on DataMan 8500

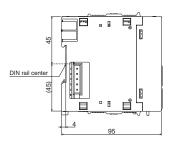


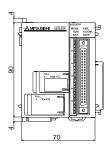


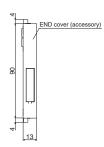
DataMan 8500

#### CPU Modules

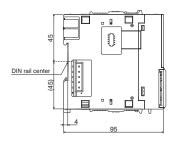
#### L02SCPU NEW

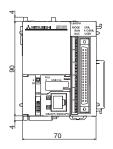


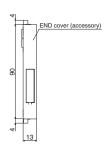




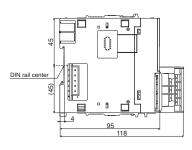
L02CPU, L02CPU-P, L06CPU NEW, L26CPU NEW

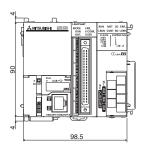


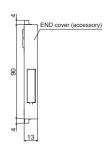




L26CPU-BT, L26CPU-PBT





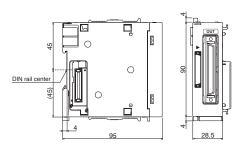


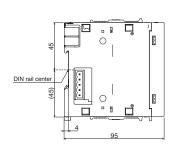
#### Branch Module

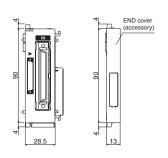
## **Extension Module**

L6EXE

L6EXB





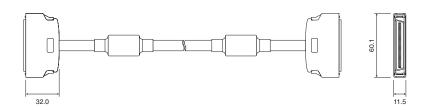


Unit: mm



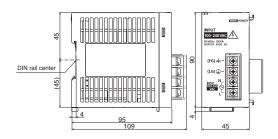
#### Extension Cable

LC06E, LC10E, LC30E



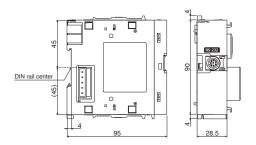
#### **Power Supply Modules**

L61P, L63P



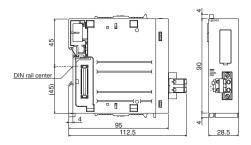
## RS-232 adapter

L6ADP-R2



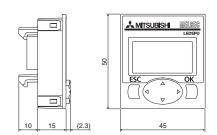
#### END cover with error terminal

L6EC-ET



## Display Unit

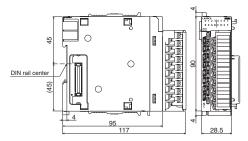
L6DSPU



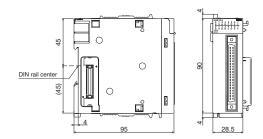
#### I/O Modules

LX10, LX28, LX40C6,

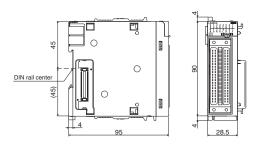
LY10R2, LY20S6, LY40NT5P, LY40PT5P



LX41C4, LY41NT1P, LY41PT1P

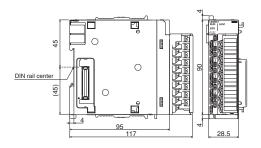


LX42C4, LY42NT1P, LY42PT1P

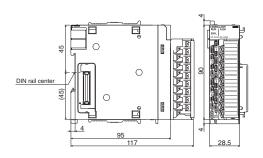


#### **Analog I/O Modules**

L60AD4, L60DA4

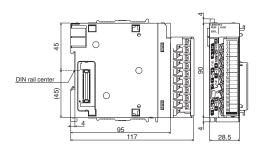


L60AD4-2GH NEW

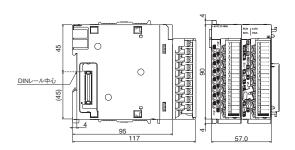


#### **Temperature Control Modules**

L60TCTT4, L60TCRT4



L60TCTT4BW, L60TCRT4BW

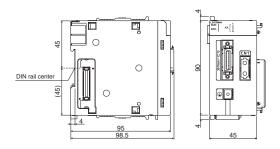


Unit: mm



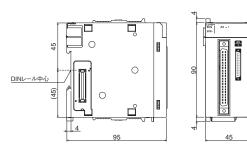
## Simple Motion Module

LD77MH4, LD77MH16

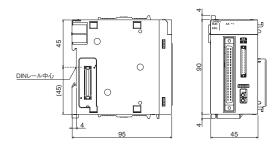


## **Positioning Modules**

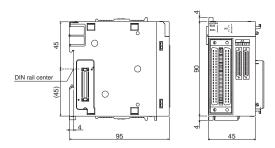
LD75P1, LD75P2



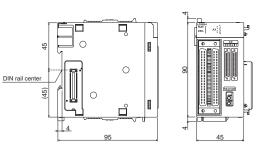
LD75D1, LD75D2



LD75P4

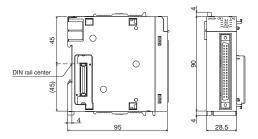


LD75D4



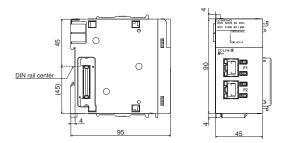
#### High-Speed Counter Modules

LD62, LD62D



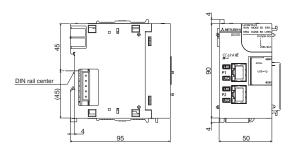
#### CC-Link IE Field Network Master/Local Module

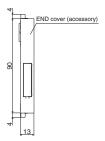
LJ71GF11-T2



#### CC-Link IE Field Network Head Module

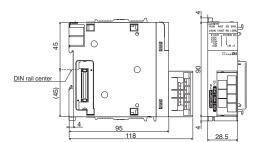
LJ72GF15-T2





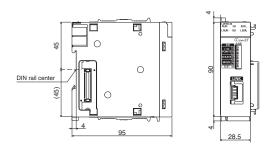
#### CC-Link Master/Local Module

LJ61BT11



#### CC-Link/LT Master Module

LJ61CL12

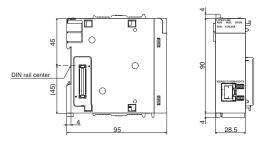


Unit: mm



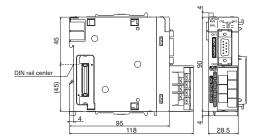
## Ethernet interface module

LJ71E71-100 NEW

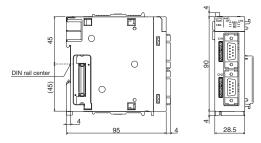


## Serial Communication Modules

LJ71C24



LJ71C24-R2



## **Extensive global support coverage providing expert**

**Global FA centers** 

"Mitsubishi Electric Global FA centers" have been established in various countries around the world to cover the Americas, Europe, and Asia. FA centers help to ensure compliance with the certifications and regulations of different regions, initiate product development in response to local demands, and provide full-time, professional customer service.



#### **UK FA Center**

Mitsubishi Electric Europe B.V. UK Branch 8XB. UK

Tel: +44-1707-28-8780 / Fax: +44-1707-27-8695 Area covered: UK, Ireland



#### **German FA Center**

Mitsubishi Electric Europe B.V. German Branch Gothaer Strasse 8, D-40880 Ratingen, Germany Tel: +49-2102-486-0 / Fax: +49-2102-486-1120 Area covered: Mainly Western Europe



#### Czech republic FA Center

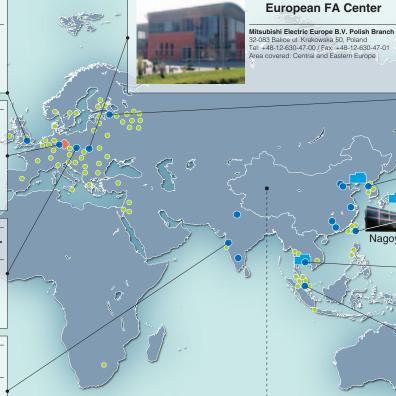
Mitsubishi Electric Europe B.V. Czech Branch Praha5, Czech Republic Tel: +420-251-551-470 / Fax: +420-251-551-471

Area covered: Czech, Slovakia



#### **India FA Center**

Mitsubishi Electric India Pvt. Ltd. Misubish Electric India PVI. Ltd. India Factory Automation Centre Emerald House, EL-3, J Block, M.I.D.C., Bhosari, Pune, 411026, Maharastra State, India Tel: +91-20-2710-2000 / Fax: +91-20-2710-2100 Area covered: India





#### **Beijing FA Center**

Mitsubishi Electric Automation (CHINA) Ltd.

Misubishi Electric Automation (Chirva) Ltd. Beijing Office
Unit 908, Office Tower 1, Henderson Centre, 18
Jianguomennei Avenue, Dongcheng District,

Beijing, China Tel: +86-10-6518-8830 / Fax: +86-10-6518-3907 Area covered: China



#### **Tianjin FA Center**

Mitsubishi Electric Automation (CHINA) Ltd. Tianiin Office

Hanjin Office Unit 2003, Tianjin City Tower, No.35, You Yi Road, Hexi District, Tianjin, China Tel: +86-22-2813-1015 / Fax: +86-22-2813-1017 Area covered: China



#### **Guangzhou FA Center**

Mitsubishi Electric Automation (CHINA) Ltd. Guangzhou Office

Rm.1609, North Tower, The Hub Center, No. 1068, Xin Gang East Road, Haizhu District.

Guangzhou, China Tel: +86-20-8923-6730 / Fax: +86-20-8923-6715

## Shanghai Wuhang-Fuzhou Taipei Taichung Shenzhen Hong Kong

China (including Hong Kong area)

#### Local factory in China

Nagoya, Japan

Mitsubishi Electric Dalian Industrial Products Co., Ltd.

#### Local factory in China

Mitsubishi Electric Automation Manufacturing (Changshu) Co.,Ltd.

No.706 Southeast Building, Chengahu Southeast Economic Development Zone of Jiangsu, 215500

China Tel: 86-512-5213-3077 / Fax: 86-512-5213-3088

#### Shanghai FA Center

Mitsubishi Electric Automaiton (China) Ltd. 10F, Mitsubishi Electric Automation Center, No.1386 Hongqiao Road, Changning District,

Shanghai, China Tel: 86-21-2322-3030 / Fax: 86-21-2322-3000 Area covered: China

## help whenever needed.









## Complying with international quality assurance standards.

All of Mitsubishi Electric's FA component products have acquired the international quality assurance "ISO9001" and environment management system standard "ISO14001" certification. Mitsubishi Electric's products also comply with various safety standards, including UL standards.

\*For jointly developed and partner products, guaranteed quality standards may differ. Please refer to the product manuals for details.

#### **Safety Standards**



CE : Council Directive of the European Communities



UL : Underwriters Laboratories Listing

## **Product List**

<sup>\*</sup>Refer to the product user manuals for information about compatible modules, restrictions, etc., before using the products.
\*Contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

MELSEC-L	series	[ Lege	end ] DB : Double brand product (Note) NEW : Recently released product SOON : Product available soon
Product		Model	Outline
		L02SCPU NEW	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20k steps, Basic operation processing speed (LD instruction): 60ns, Program memory capacity: 80KB, Peripheral connection ports: USB and RS-232, Memory card I/F: None, Built-in I/O functions (General input:16 points, General output (Sink type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L02CPU	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20k steps, Basic operation processing speed (LD instruction): 40ns, Program memory capacity: 80KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Sink type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L02CPU-P	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20k steps, Basic operation processing speed (LD instruction): 40ns, Program memory capacity: 80KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Source type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
CPU		L06CPU NEW	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60k steps, Basic operation processing speed (LD instruction): 9.5ns, Program memory capacity: 240KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Sink type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L26CPU NEW	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260k steps, Basic operation processing speed (LD instruction): 9.5ns, Program memory capacity: 1040KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Sink type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
			Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260k steps, Basic operation processing speed (LD instruction): 9.5ns, Program memory capacity: 1040KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Sink type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
			Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260k steps, Basic operation processing speed (LD instruction): 9.5ns, Program memory capacity: 1040KB, Peripheral connection ports: USB and Ethernet, Memory card I/F: SD Memory Card, Built-in I/O functions (General input:16 points, General output (Source type):8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
		L02CPU-SET	CPU module (L02CPU), Display unit (L6DSPU), and Power supply module (L61P) set
		L02CPU-P-SET	CPU module (L02CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
0011		L06CPU-SET NEW	CPU module (L06CPU), Display unit (L6DSPU), and Power supply module (L61P) set
CPU packages	i	L26CPU-SET NEW	CPU module (L26CPU), Display unit (L6DSPU), and Power supply module (L61P) set
		L26CPU-BT-SET	CPU module (L26CPU-BT), Display unit (L6DSPU), and Power supply module (L61P) set
		L26CPU-PBT-SET	CPU module (L26CPU-PBT), Display unit (L6DSPU), and Power supply module (L61P) set
D 1/5:		L6EXB	Branch module
Branch / Exten	sion module	L6EXE	Extension module with END cover
		LC06E	0.6-m cable for connecting branch and extension modules
	Extension cable	LC10E	1.0-m cable for connecting branch and extension modules
		LC30E	3.0-m cable for connecting branch and extension modules
Power supply		L61P	Input voltage: 100 to 240VAC, Output voltage: 5VDC, Output current: 5A
		L63P	Input voltage: 24VAC, Output voltage: 5VDC, Output current: 5A
RS-232 adapter		L6ADP-R2	For GOT connection, 1 x RS-232 channel, maximum transmission speed: 115.2Kpbs, MELSOFT connectable
END cover with error terminal		L6EC-ET	END cover with error terminal
	Display unit	L6DSPU	STN black-and-white LCD, 16 characters x 4 lines
		Q6BAT	Replacement battery
	Battery	Q7BAT-SET	High capacity battery with a battery holder for CPU installation
CPU options		Q7BAT	High capacity replacement battery
S	ISD Memory Card	L1MEM-2GBSD*1	2GB SD Memory Card
		L1MEM-4GBSD*1	4GB SD Memory Card

<sup>\*1:</sup> Mitsubishi Electric does not guarantee the operation of non-Mitsubishi Electric products.

Note: General specifications and product guarantee conditions of jointly developed products are different from those of MELSEC products.  $For more information, please \ refer to the product \ manuals \ or \ contact \ your \ local \ Mitsubishi \ representative \ for \ details.$ 

	Prod	luct	Model	Outline
			LX10 NEW	16 points, 100 to 120VAC, Response time:20ms or less, 16 points/common, 18-point terminal block
		AC	LX28 NEW	8 points, 100 to 240VAC, Response time:20ms or less, 8 points/common, 18-point terminal block
			LV40CC	16 points, 24VDC, Response time: 1/5/10/20/70ms or less,
	Input	DC	LX40C6	16 points/common, Positive/Negative common, 18-point terminal block
	Imput	(Positiv e or negative	LYA1CA	32 points, 24VDC, Response time: 1/5/10/20/70ms or less,
		common)	LX4104	32 points/common, Positive/Negative common, 40-pin connector
			LX42C4	64 points, 24VDC, Response time: 1/5/10/20/70ms or less,
			27.1201	32 points/common, Positive/Negative common, 40-pin connector x 2
		Relay	LY10R2	16 points, 24VDC/240VAC, 2A/point, 8A/common, Response time: 12ms or less,
				16 points/common, 18-point terminal block
		Triac	LY20S6	16 points, 100 to 240VAC, 0.6A/point, 4.8A/common, Response time:1ms + 0.5 cycles or less, 16 points/common, 18-point terminal block
O module				16 points, 12 to 24VDC, 0.5A/point, 5A/common, Response time: 1ms or less, 16 points/common,
			LY40NT5P	18-point terminal block, overload protection function, overheat protection function, surge suppression
		Transistor		32 points, 12 to 24VDC, 0.1A/point, 2A/common, Response time: 1ms or less, 32 points/common,
		(Sink)	LY41NT1P	Sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
	Output	,		64 points, 12 to 24VDC, 0.1A/point, 2A/common, Response time: 1ms or less, 32 points/common,
			LY42NT1P	Sink type, 40-pin connector x 2, overload protection function, overheat protection function, surge suppre
			LVAORTER	16 points, 12 to 24VDC, 0.5A/point, 5A/common, Response time: 1ms or less, 16 points/common,
			LY40PT5P	18-point terminal block, overload protection function, overheat protection function, surge suppression
		Transistor	LY41PT1P	32 points, 12 to 24VDC, 0.1A/point, 2A/common, Response time: 1ms or less, 32 points/common,
		(Source)	LT4IFIIF	40-pin connector, overload protection function, overheat protection function, surge suppression
			LY42PT1P	64 points, 12 to 24VDC, 0.1A/point, 2A/common, Response time: 1ms or less, 32 points/common,
			L1421 111	40-pin connector x 2, overload protection function, overheat protection function, surge suppression
			L60AD4	4 channels, Input: -10 to 10VDC, 0 to 20mADC, Output (resolution): 0 to 20000, -20000 to 20000,
		Analog input		Conversion speed: 20µs, 80µs, 1ms/ch, 18-point terminal block
nalog I/O mo	odule	gp=:	L60AD4-2GH NEW	4 channels, Input: -10 to 10VDC, 0 to 20mADC, Output (resolution): 0 to 32000, -32000 to 32000,
Ŭ				Conversion speed: 401µs/2ch, 18-point terminal block, Dual channel isolation
		Analog output	L60DA4	4 channels, Input (resolution): 0 to 20000, -20000 to 20000, Output: -10 to 10VDC, 0 to 20mADC,
				Conversion speed: 20µs/ch, 18-point terminal block
			L60TCTT4	4 channels (normal mode) / 2 channels (heating-cooling control), Thermocouple (K,J,T,B,S,E,R,N,U,L,PL II ,W5Re/W26Re), No Heater disconnection detection function
		10010114	sampling cycle: 250ms/4CH, 500ms/4CH, Channel isolated, 18 point terminal block	
		Thermocouple		4 channels (normal mode) / 2 channels (heating-cooling control),
			L60TCTT4BW	Thermocouple (K,J,T,B,S,E,R,N,U,L,PL II, W5Re/W26Re), Heater disconnection detection function,
emperature (	Control			sampling cycle: 250ms/4CH,500ms/4CH, Channel isolated, 18 point terminal block x 2
nodule				4 channels (normal mode) / 2 channels (heating-cooling control),
			L60TCRT4	Platinum type resistive temperature device(Pt100, JPt100), No Heater disconnection detection funct
		RTD		Sampling cycle: 250ms/4CH,500ms/4CH, Channel isolated, 18 point terminal block
		5		4 channels (normal mode) / 2 channels (heating-cooling control),
			L60TCRT4BW	Platinum type resistive temperature device(Pt100, JPt100), Heater disconnection detection function,
				Sampling cycle: 250ms/4CH,500ms/4CH, Channel isolated, 18 point terminal block x 2
			LD77MH4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET Ⅲ connections
imple motior	n module			16 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control,
			LD77MH16	Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET III conne
				1 axis, Control unit: mm, inch, degree, pulse,
			LD75P1	Number of positioning data: 600 data/axis, Maximum output pulse: 200kpps, 40-pin connector
			. = = = =	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse,
		Open collector	LD75P2	Number of positioning data: 600 data/axis, Maximum output pulse: 200kpps, 40-pin connector
Positioning module			LD75P4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, p
			LD/5P4	Number of positioning data: 600 data/axis, Maximum output pulse: 200kpps, 40-pin connector x 2
			LD75D1	1 axis, Control unit: mm, inch, degree, pulse,
				Number of positioning data: 600 data/axis, Maximum output pulse: 4Mpps, 40-pin connector
		Differential driver	LD75D2	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse,
		Dillerential driver		Number of positioning data: 600 data/axis, Maximum output pulse: 4Mpps, 40-pin connector
			LD75D4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, p
High-speed counter module				Number of positioning data: 600 data/axis, Maximum output pulse: 4Mpps, 40-pin connector x 2
			LD62	2 channels, 200/100/10kpps, Count input signal: 5/12/24VDC, External input: 5/12/24VDC, Coincidence output: transister (cipl.) 13//4VDC, 0.5A/coint: 2A/common, 40 pin connector
		ulo		Coincidence output: transistor (sink), 12/24VDC, 0.5A/point, 2A/common, 40-pin connector
ign-speed C	Junier modi	NIG.	LD62D	2 channels, 500/200/100/10kpps, Count input signal: EIA standards RS-422-A (Differential line driver le External input: 5/12/24VDC, Coincidence output: transistor (sink), 12/24VDC, 0.5A/point, 2A/commo
			20020	40-pin connector
		CC-Link IE Field	LJ71GF11-T2	Master/Local station
		Network	LJ72GF15-T2*2	Remote station (Head module with END cover)

communication LJ71C24-R2 RS-232: 2 channels, Total transmission speed of 2 channels: 230.4kbps 2: The CPU module, branch and extension module, display unit, RS-232 adaptor, CC-Link IE Field Network master/local module and Ethernet interface module cannot be mounted on a system using LJ72GF-T2.

10BASE-T/100BASE-TX

Master station, CC-Link/LT system compatible

Master/Local station, CC-Link Ver.2.0 compatible

RS-232: 1 channel, RS-422/485: 1 channel, Total transmission speed of 2 channels: 230.4kbps

Ethernet interface

CC-Link

Serial

CC-Link/LT

Network module

LJ61BT11

LJ61CL12

LJ71C24

LJ71E71-100 NEW

#### **Options**

Product	Model	Outline
	A6CON1*1*2	Soldering type 32-point connector (40-pin connector)
Connector	A6CON2*1 *2	Crimp contact type 32-point connector (40-pin connector)
Connector	A6CON3*1*3	Flat cable pressure welding type 32-point connector (40-pin connector)
	A6CON4*1 *2	Soldering type 32-point connector (40-pin connector, cable connectable in bidirection)
	A6TBXY36*4*5	For positive common type input module and sink type output module (Standard type)
Connector/terminal block converter module	A6TBXY54*4*5	For positive common type input module and sink type output module (2-wire type)
	A6TBX70*4	For positive common type input module (3-wire type)

<sup>\*1:</sup> Available for LO2CPU, LO2CPU-P, L26CPU-BT, L26CPU-PBT, LX41C4, LX42C4, LX41NT1P, LY42NT1P, LY41PT1P and LY42PT1P.
\*2: Available for LD75P1, LD75P2, LD75P4, LD75D1, LD75D2, LD75D4, LD62 and LD62D.
\*3: When used with L02CPU, L02CPU-P, L26CPU-BT, L26CPU-PBT, only when all points are general I/O.
\*4: Available for LX41C4 and LX42C4, (Positive common only)
\*5: Available for LY41NT1P, LY42NT1P, LY41PT1P and LY42PT1P.

#### **Ethernet related products**

	Product	Model	Outline
	U.S.A.	NZ2WL-US*1*2 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
\A(:	Europe	NZ2WL-EU*1*2 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
Adapter	China	NZ2WL-CN*1*2 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Korea	NZ2WL-KR*1*2 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Taiwan	NZ2WL-TW*1*2 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
Indicated accita	hina IIIID	NZ2EHG-T8 DB	10Mbps/100Mbps/1Gbps AUTO-MDIX, DIN rail mountable, 8 ports
Industrial switching HUB		NZ2EHF-T8 DB	10Mbps/100Mbps AUTO-MDIX, DIN rail mountable, 8 ports
CC-Link IE Field Network Ethernet Adapter		NZ2GF-ETB	100Mbps/1Gbps compatible station for expanding CC-Link IE Field Networks

#### ${\bf MELSOFT^{*1}-Programming\ Tool}$

Product	Model	Outline
GX Works2	SW1DNC-GXW2-E	Programmable controller engineering software (Functions integrated software: Programming, simulation, module settings, and monitoring)
OV D1*2	SW8D5C-GPPW-E	Programmable controller programming software
GX Developer*2	SW8D5C-GPPW-EV	Programmable controller programming software (upgrade)
		FA engineering software <sup>*3</sup>
		System Management Software: MELSOFT Navigator     MELSOFT Navigator is a comprehensive system configuration solution that serves as a launching pad for the other software packages.
MELSOFT iQ Works	SW1DNC-IQWK-E (CD-ROM edition)	Controller Programming Software: MELSOFT GX Works2     The next generation configuration, programming, and simulation software for FX, L, and Q series controllers.
	SW1DND-IQWK-E (DVD-ROM edition)	Motion Programming Software: MELSOFT MT Works2     Design and maintenance tool for motion controllers.
		HMI Programming Software: MELSOFT GT Works3     GOT configuration, screen design, and maintenance tool.
		Robot Programing Software: MELSOFT RT ToolBox2 mini Programming and total engineering tool for robots
MX Component NEW	SW4DNC-ACT-E	ActiveX® library for communication
MX Sheet *4 NEW	SW2DNC-SHEET-E	Excel® communication support tool

<sup>\*1:</sup> Each product is usable only in the respective country.
\*2: Both access points and stations are supported, and can be switched with the settings.

<sup>\*1:</sup> For details on the software versions compatible with each module, refer to the manual for each product.
Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

\*2: Some functions have restrictions. For details, refer to "Precautions on L series Modules" in the appendix of the GX Developer Version 8 Operating Manual.

\*3: For detailed information about supported modules, refer to the manuals of the relevant software package.

\*4: To use MX Sheet, MX Component is required.

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<sup>™</sup>М<sub>енг. ДШЧ</sub>О` EC97J1113

## Mitsubishi Electric Programmable Controllers

#### Precautions before use

This publication explains the typical features and functions of the products herein and does not provide restrictions and other information related to usage and module combinations. Before using the products, always read the product user manuals. Mitsubishi Electric will not be held liable for damage caused by factors found not to be the cause of Mitsubishi Electric; opportunity loss or lost profits caused by faults in Mitsubishi Electric products; damage, secondary damage, or accident compensation, whether foreseeable or not, caused by special factors; damage to products other than Mitsubishi Electric products; and to other duties.

#### ♠ For safe use

- To use the products given in this publication properly, always read the relevant manuals before use.
- The products have been manufactured as general-purpose parts for general industries, and have not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the products for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi.
- The products have been manufactured under strict quality control. However, when installing the products where major accidents or losses could occur if the products fail, install appropriate backup or fail-safe functions in the system.

Country/Region	Sales office	Tel/Fax
USA	Mitsubishi Electric Automation Inc. 500 Corporate Woods Parkway, Vernon Hills, IL 60061, USA	Tel: +1-847-478-2100 Fax: +1-847-478-2253
Brazil	Mitsubishi Electric Do Brasil Comercio E Servicos Ltda. Rua Jussara, 1750 - Bloco B- Sala 01 Jardim Santa Cecília- CEP 06465-070, Barueri, São Paulo, Brazil	Tel: +55-11-4689-3000 Fax: +55-11-4689-3016
Germany	Mitsubishi Electric Europe B.V. German Branch Gothaer Strasse 8, D-40880 Ratingen, Germany	Tel: +49-2102-486-0 Fax: +49-2102-486-1120
UK	Mitsubishi Electric Europe B.V. UK Branch Travellers Lane, Hatfield, Hertfordshire, AL10 8XB, UK.	Tel: +44-1707-28-8780 Fax: +44-1707-27-8695
Italy	Mitsubishi Electric Europe B.V. Italian Branch Viale Colleoni 7-20864 Agrate Brianza (Milano), Italy	Tel: +39-039-60531 Fax: +39-039-6053-312
Spain	Mitsubishi Electric Europe B.V. Spanish Branch Carretera de Rubi 76-80.AC.420, E-08190 Sant Cugat del Valles (Barcelona), Spain	Tel: +34-93-565-3131 Fax: +34-93-589-1579
France	Mitsubishi Electric Europe B.V. French Branch 25, Boulevard des Bouvets, F-92741 Nanterre Cedex, France	Tel: +33-1-5568-5568 Fax: +33-1-5568-5757
Czech Republic	Mitsubishi Electric Europe B.V. Czech Branch Avenir Business Park, Radicka 751/113e, 158 00 Praha5, Czech Republic	Tel: +420-251-551-470 Fax: +420-251-551-471
Poland	Mitsubishi Electric Europe B.V. Polish Branch 32-083 Balice ul. Krakowska 50, Poland	Tel: +48-12-630-47-00 Fax: +48-12-630-47-01
Russia	Mitsubishi Electric Europe B.V. Russian Branch St.Petersburg office Piskarevsky pr. 2, bld 2, lit "Sch", BC "Benua", office 720; 195027, St. Petersburg, Russia	Tel: +7-812-633-3497 Fax: +7-812-633-3499
South Africa	CBI-Electric. Private Bag 2016, ZA-1600 Isando, South Africa	Tel: +27-11-977-0770 Fax: +27-11-977-0761
China	Mitsubishi Electric Automaiton (China) Ltd. 10F, Mitsubishi Electric Automation Center, No.1386 Hongqiao Road, Changning District, Shanghai, China	Tel: +86-21-2322-3030 Fax: +86-21-2322-3000
Taiwan	Setsuyo Enterprise Co., Ltd. 6F., No.105, Wugong 3rd Road, Wugu District, New Taipei City 24889, Taiwan, R.O.C.	Tel: +886-2-2299-2499 Fax: +886-2-2299-2509
Korea	Mitsubishi Electric Automation Korea Co., Ltd. 3F, 1480-6, Gayang-Dong, Gangseo-Gu, Seoul, 157-200, Korea	Tel: +82-2-3660-9530 Fax: +82-2-3664-8372
Singapore	Mitsubishi Electric Asia Pte, Ltd. Industrial Division 307, Alexandra Road, Mitsubishi Electric Building, Singapore, 159943	Tel: +65-6470-2308 Fax: +65-6476-7439
Thailand	Mitsubishi Electric Automation (Thailand) Co., Ltd. Bang-Chan Industrial Estate No.111 Soi Serithai 54, T.Kannayao, A.Kannayao, Bangkok 10230 Thailand	Tel: +66-2906-3238 Fax: +66-2906-3239
Indonesia	P.T. Autoteknindo Sumber Makmur Muara Karang Selatan, Block A/Utara No.1 Kav. No.11, Kawasan Industri Pergudangan, Jakarta-Utara 14440, P.O, Box 5045, Indonesia	Tel: +62-21-663-0833 Fax: +62-21-663-0832
India	Mitsubishi Electric India Pvt. Ltd. Emerald House, EL-3, J Block, M.I.D.C., Bhosari, Pune, 411026, Maharastra State, India	Tel : +91-20-2710-2000 Fax : +91-20-2710-2100
Australia	Mitsubishi Electric Australia Pty.Ltd. 348 Victoria Road PO BOX11, Rydalmere, N.S.W 2116, Australia	Tel: +61-2-9684-7777 Fax: +61-2-9684-7245

#### MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE: TOKYO BUILDING, 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN NAGOYA WORKS: 1-14, YADA-MINAMI 5, HIGASHI-KU, NAGOYA, JAPAN